

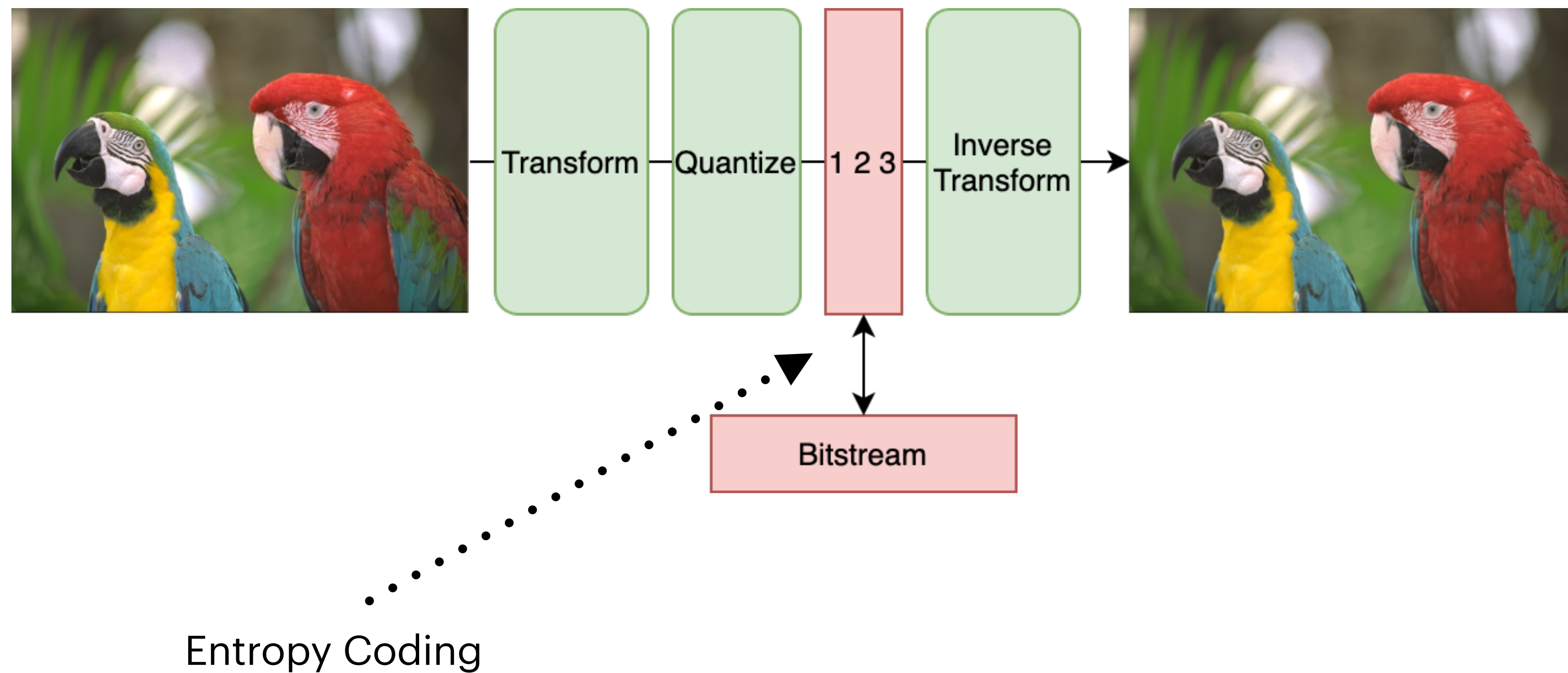
Hierarchical Autoregressive Modeling for Neural Video Compression

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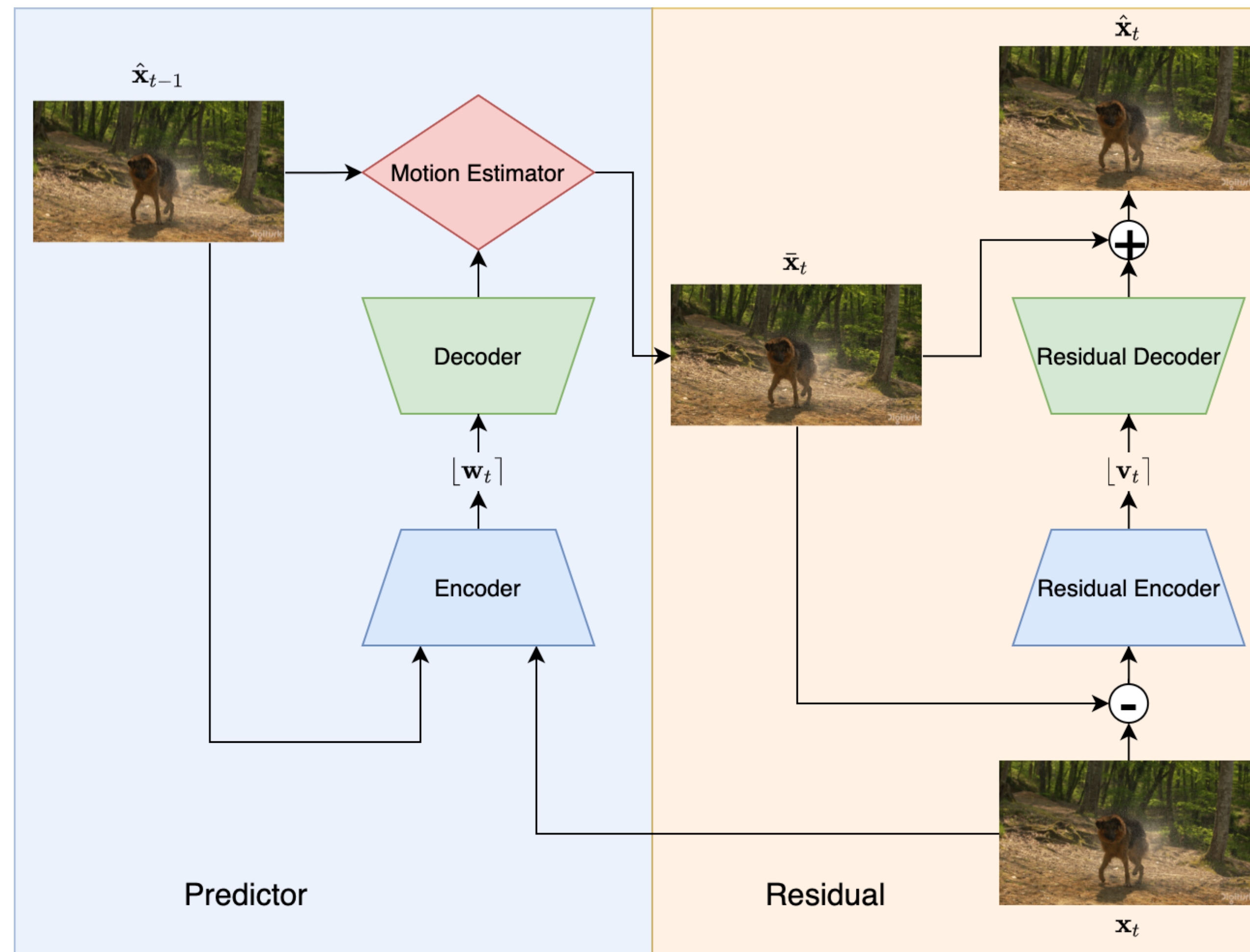
ICLR 2021

Lossy Compression



See “Variational image compression with a scale hyperprior (Balle et al. 2018)”
for latent variable model for image compression.

Low-Latency Video Compression



Motivation & Contribution

- Draw the connection to hierarchical sequential latent variable model.
- Propose a general framework to improve the compression performance.
 - Additional module Inspired by normalizing flow.
 - Especially Improved residual compression.
- Our model outperforms the existing state of the art in rate-distortion performance.

Method

Agustsson et al. 2020

- Scale Space Flow (SSF)
- 3D optical flow with trilinear interpolation

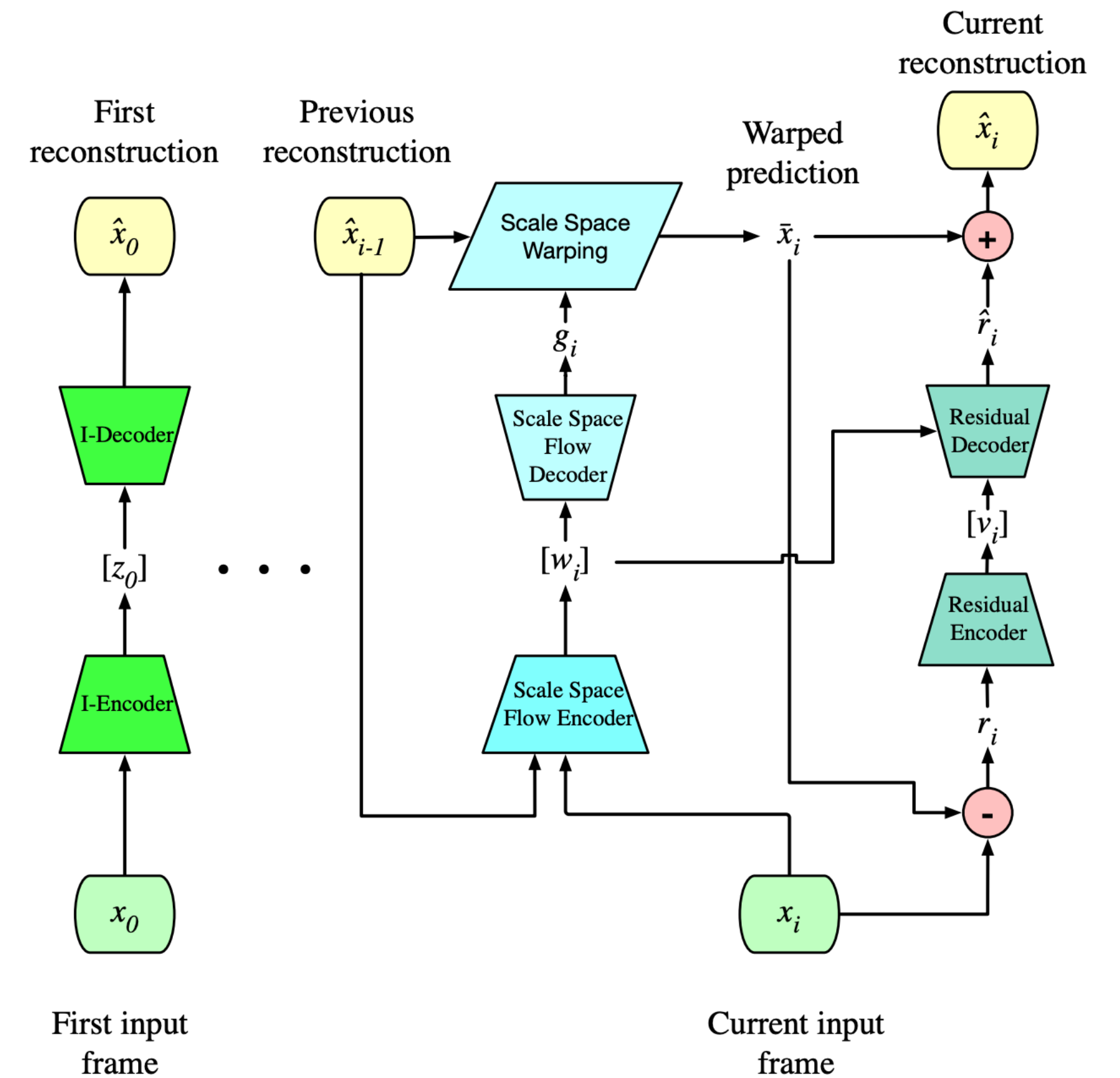


Figure adapted from Agustsson et al. 2020

Method

- Rethink the residual compression as a hierarchical model
- Invertible Transform
- Looks like VAE+Normalizing flow?
 - “Improving Sequential Latent Variable Models with Autoregressive Flows” (Marino et al. 2020)

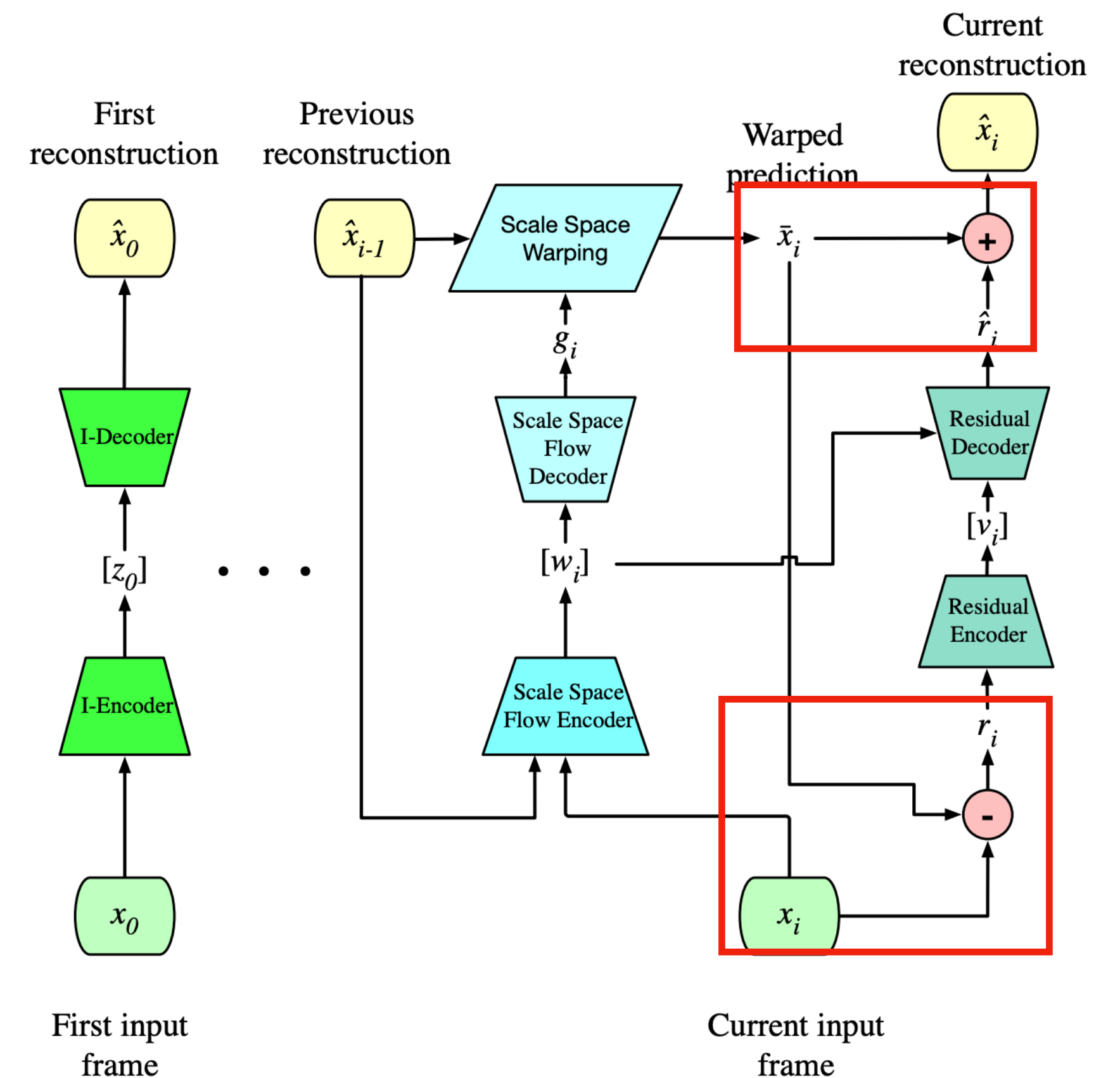


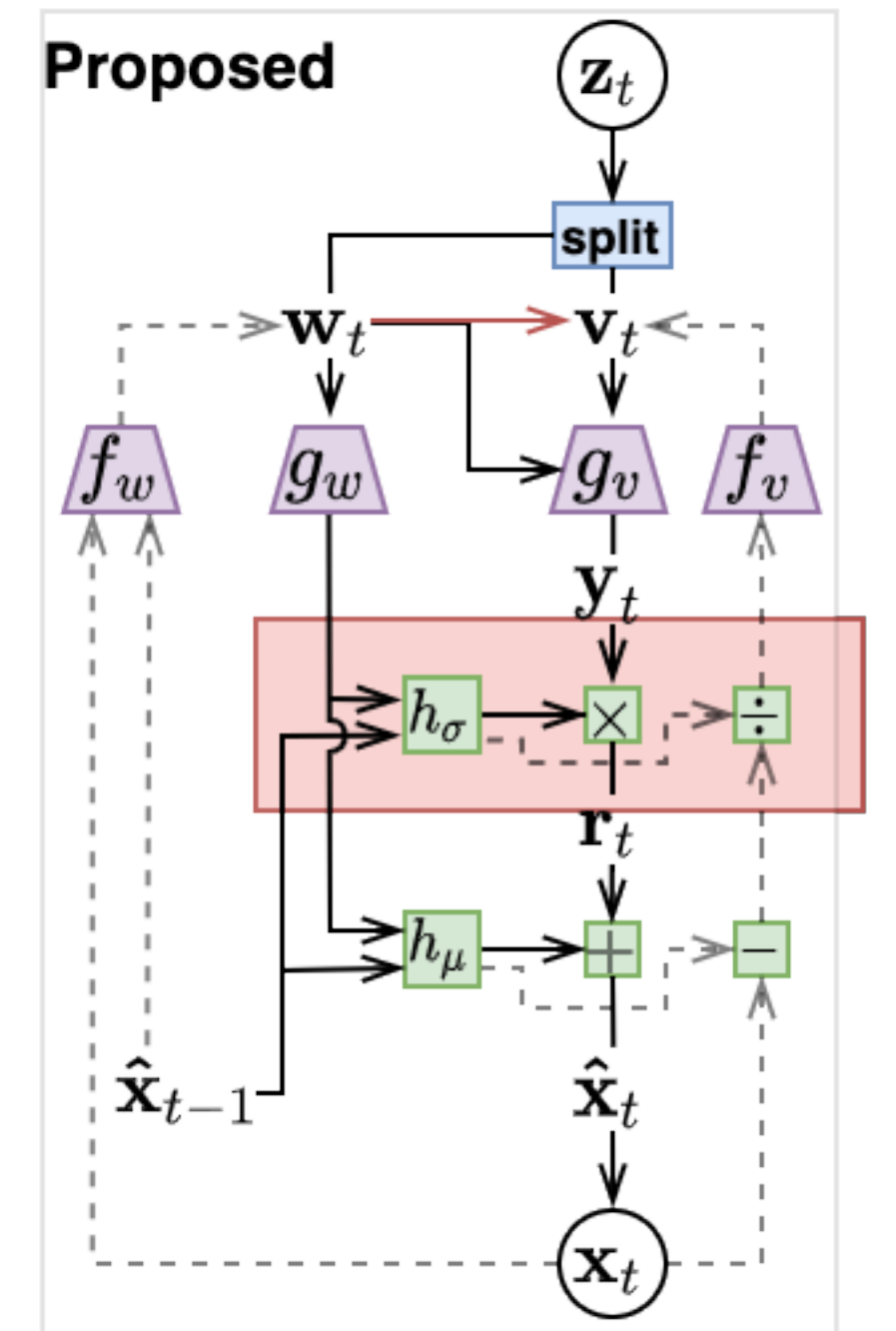
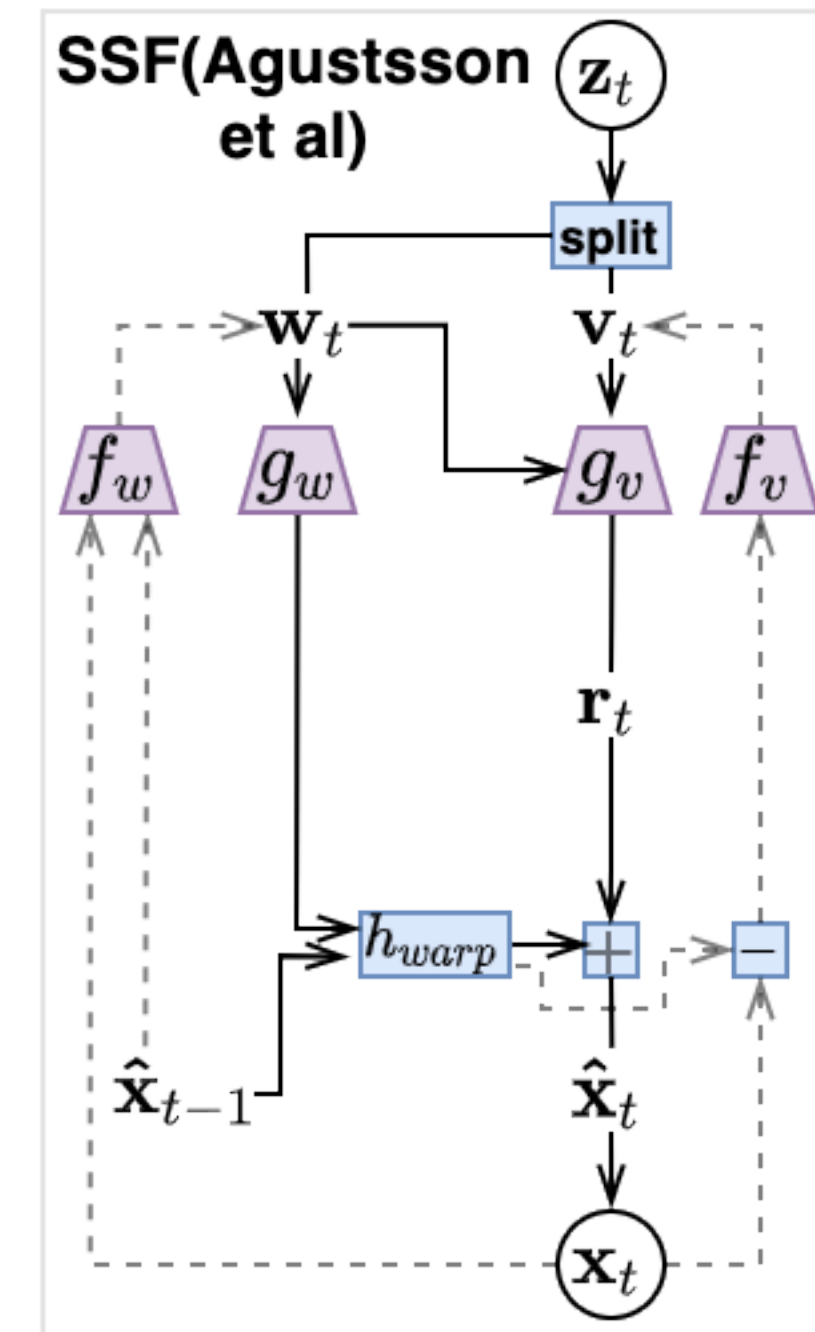
Figure adapted from Agustsson et al. 2020

Method

- Methods to model the invertible transform (coupling layer):
 - Additive coupling: NICE(Dinh et al. 2015): $x = y + m(z)$, $y = x - m(z)$
 - Affine coupling: RealNVP(Dinh et al. 2017): $x = s(z) \odot y + m(z)$,
 $y = (x - m(z))/s(z)$
 - Autoregressive: $x = x_t$, $z = x_{t-1}$, $y = y_t$

Method

- Stochastic Temporal Autoregressive Transform (STAT)
- Original decoding process:
 - $\hat{x}_t = h_{warp}(\hat{x}_{t-1}, g_w(w_t)) + g_v(v_t, w_t)$
- Proposed decoding process:
 - $\hat{x}_t = h_{\mu}(\hat{x}_{t-1}, g_w(w_t)) + h_{\sigma}(\hat{x}_{t-1}, g_w(w_t)) \odot g_v(v_t, w_t)$



Method

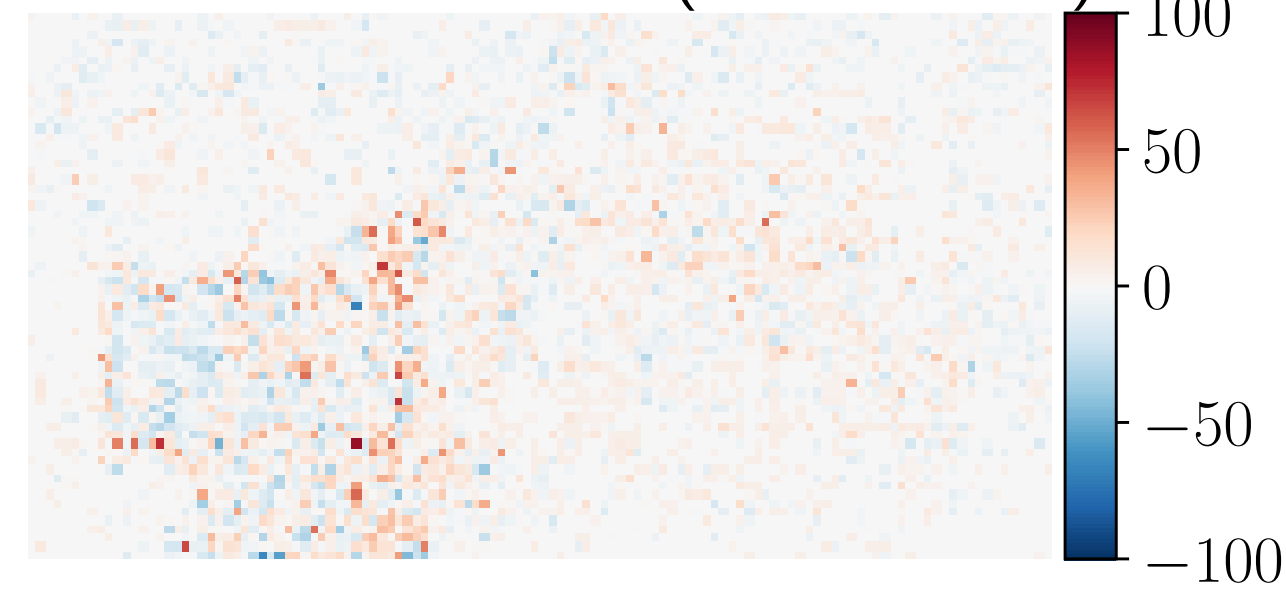
Previous reconstruction $\hat{\mathbf{x}}_{t-1}$
by STAT-SSF-SP



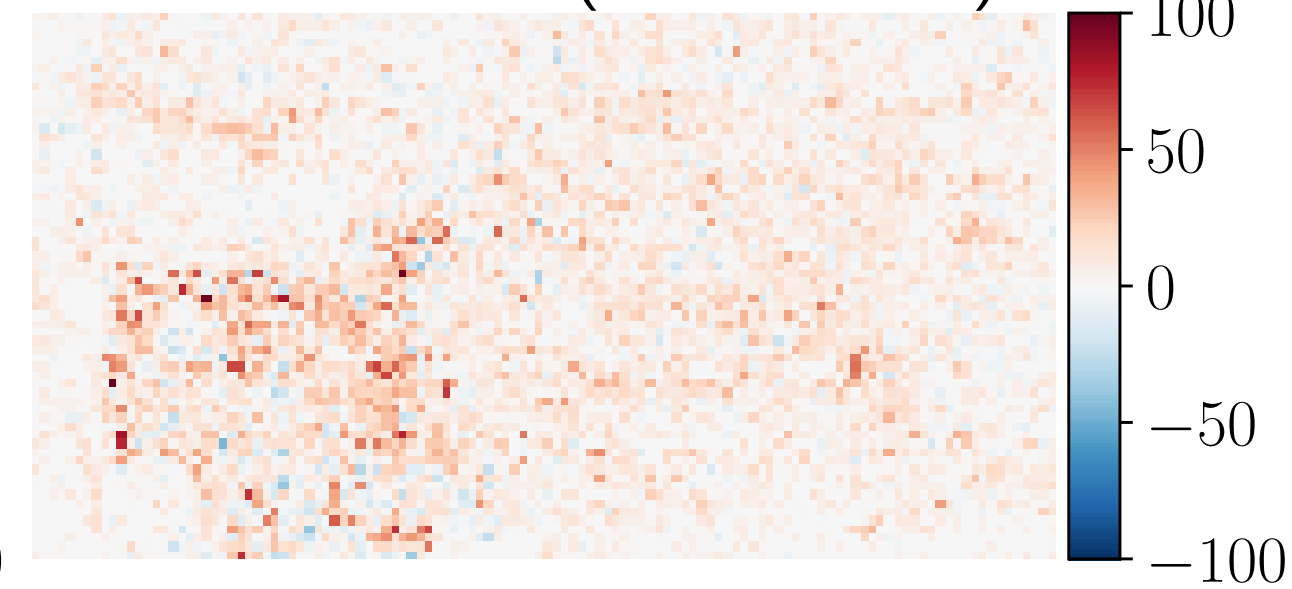
Magnitude of the proposed scale
parameter $\hat{\sigma}_t = h_\sigma(\hat{\mathbf{x}}_{t-1}, \lfloor \bar{\mathbf{w}}_t \rfloor)$



Rate savings in residual encoding $\lfloor \bar{\mathbf{v}}_t \rfloor$
relative to STAT-SSF (BPP=0.053)



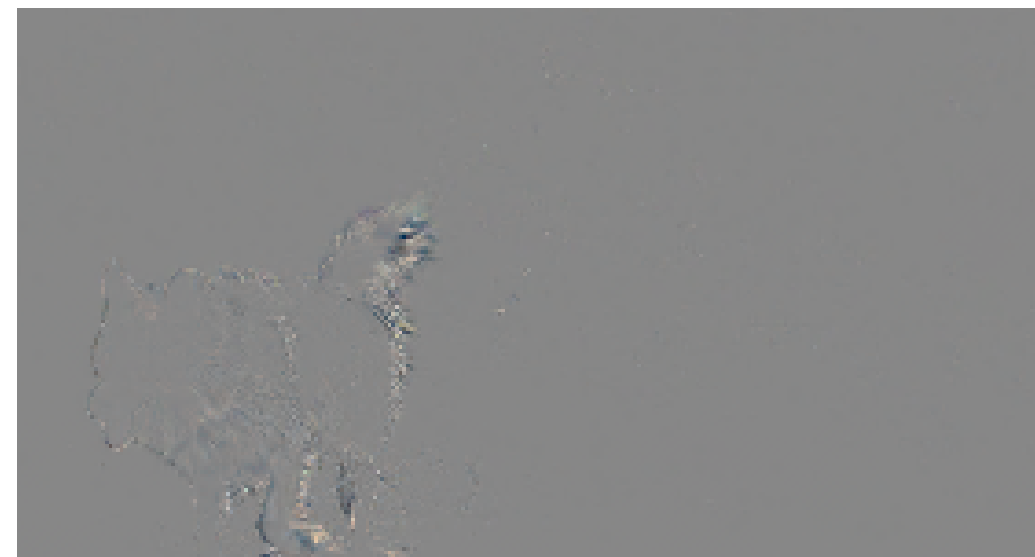
Rate savings in residual encoding $\lfloor \bar{\mathbf{v}}_t \rfloor$
relative to SSF (BPP=0.075)



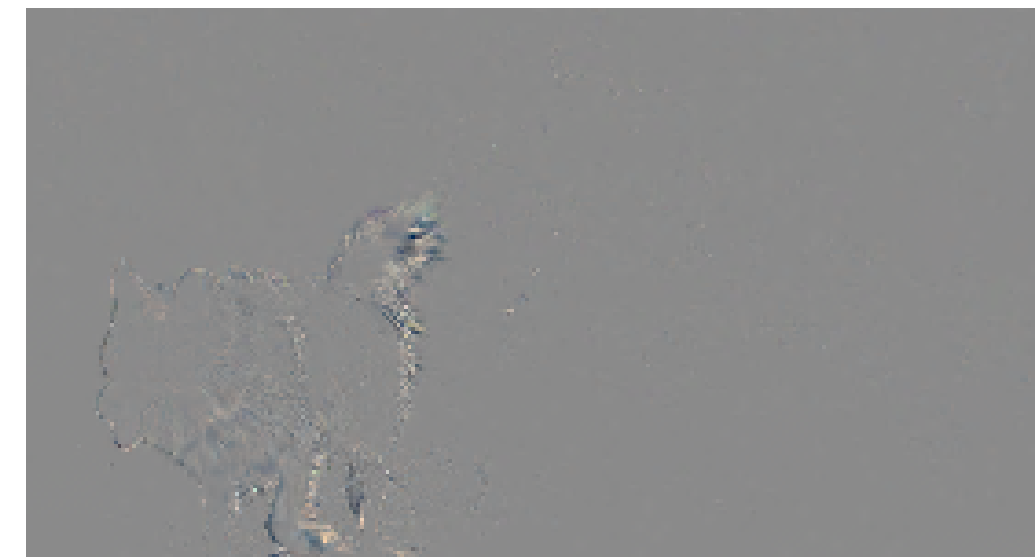
SSF warping (mean) prediction
 $\hat{\mu}_t = h_\mu(\hat{\mathbf{x}}_{t-1}, \lfloor \bar{\mathbf{w}}_t \rfloor)$



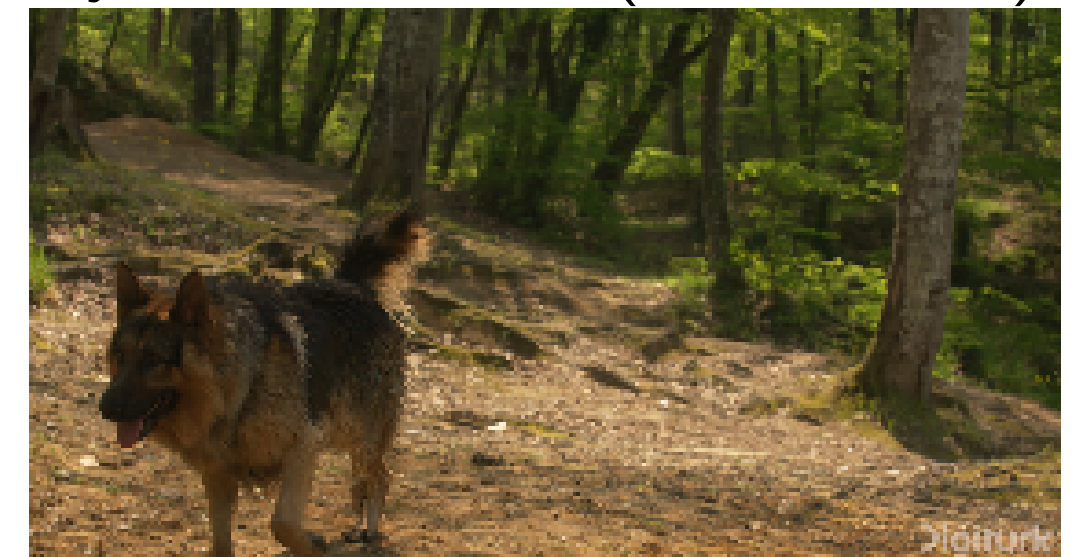
Decoded noise $\hat{\mathbf{y}}_t = g_v(\lfloor \bar{\mathbf{v}}_t \rfloor, \lfloor \bar{\mathbf{w}}_t \rfloor)$



Decoded residual $\hat{\mathbf{r}}_t = \hat{\mathbf{y}}_t \odot \hat{\sigma}_t$



Current reconstruction $\hat{\mathbf{x}}_t = \hat{\mu}_t + \hat{\mathbf{r}}_t$
by STAT-SSF-SP (BPP=0.046)



Method

- Original:

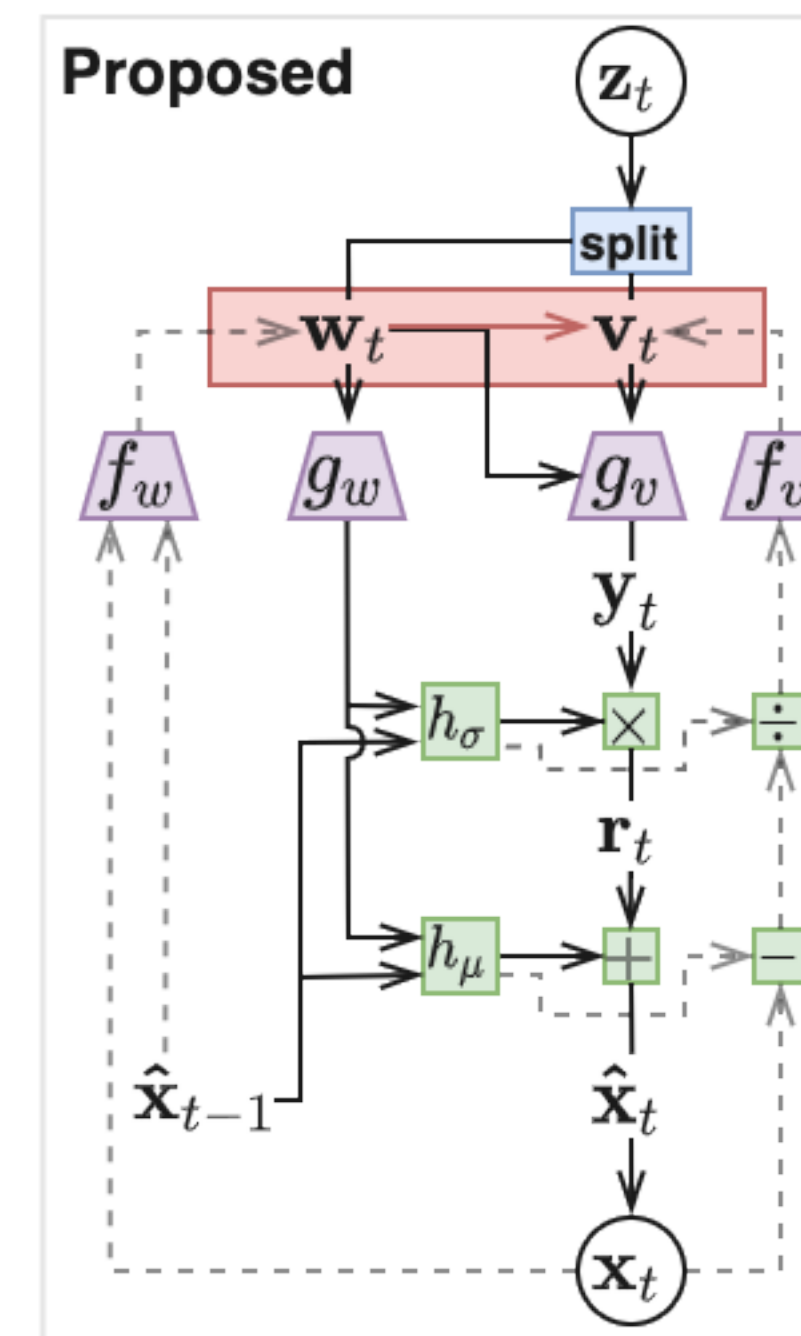
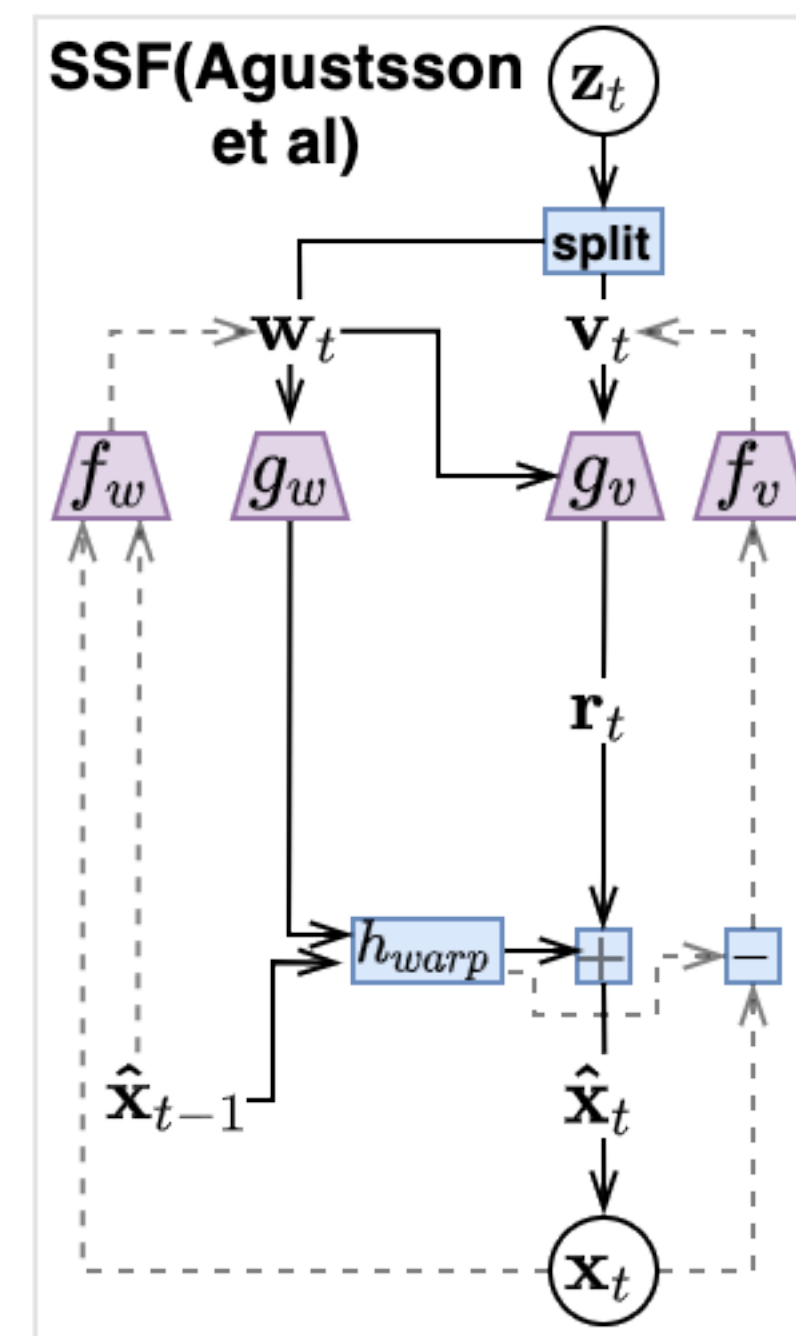
$$p(v_t, w_t) = p(w_t)p(v_t)$$

- **Structured Prior (Proposed):**

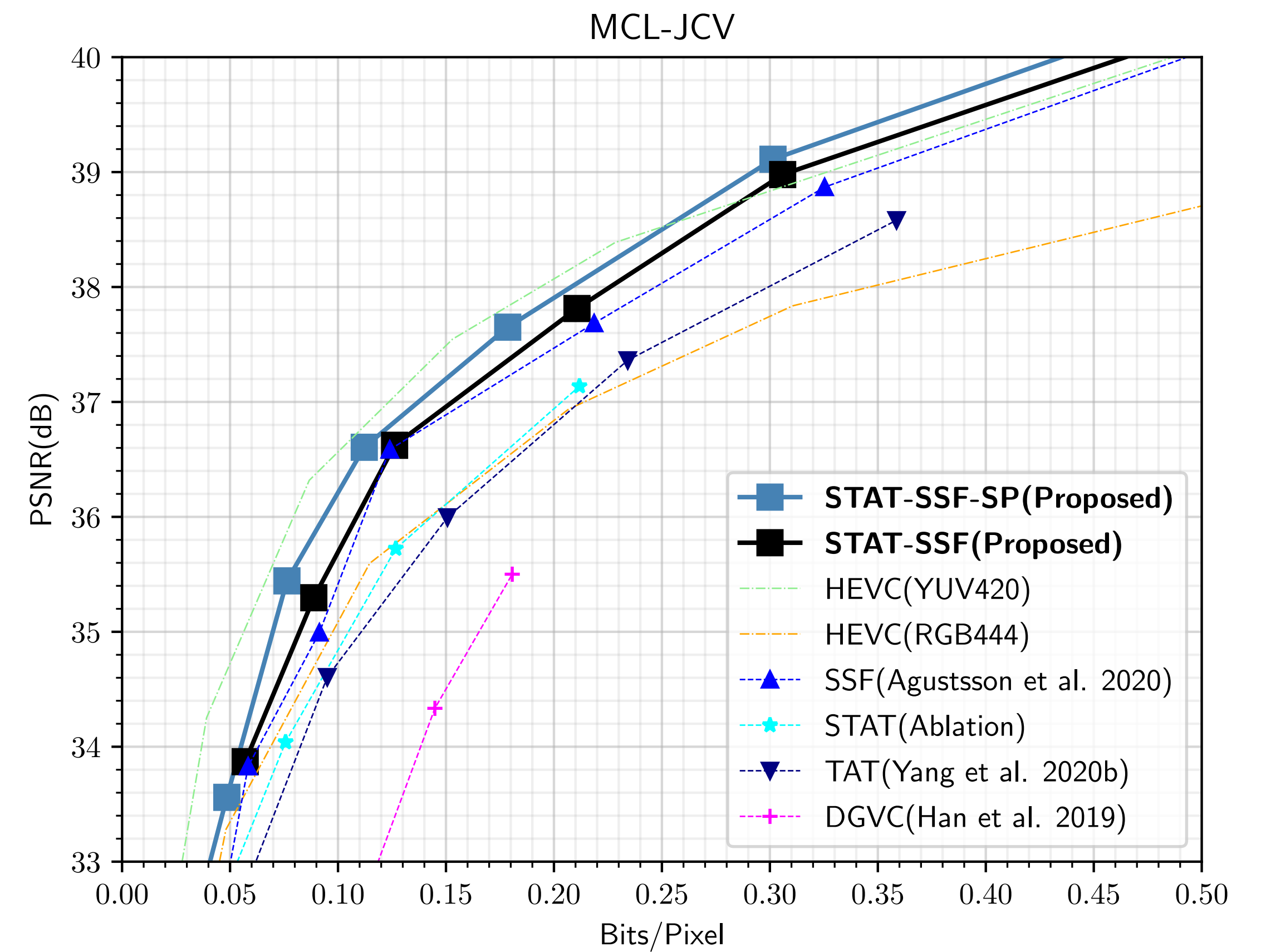
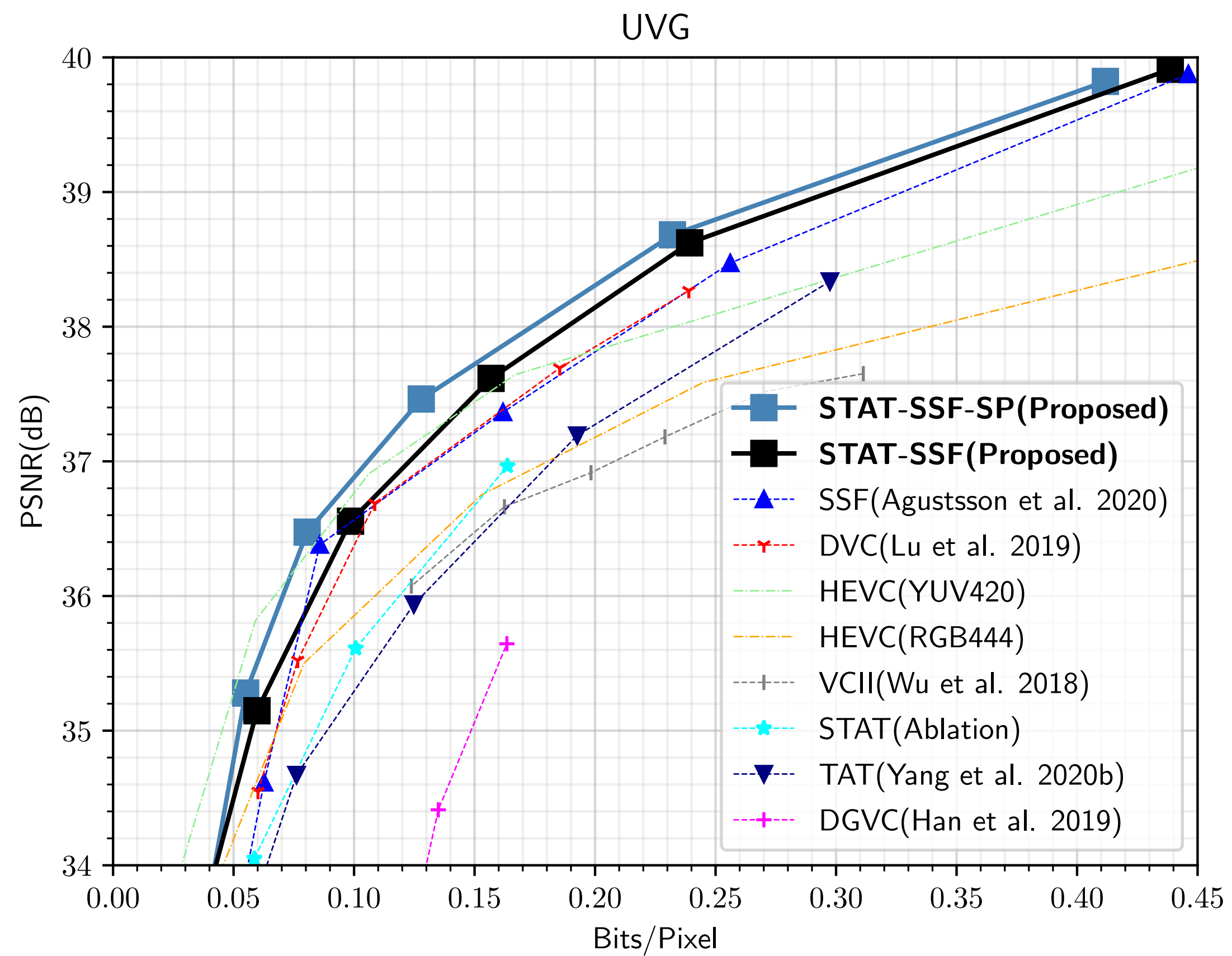
$$p(v_t, w_t) = p(w_t)p(v_t | w_t)$$

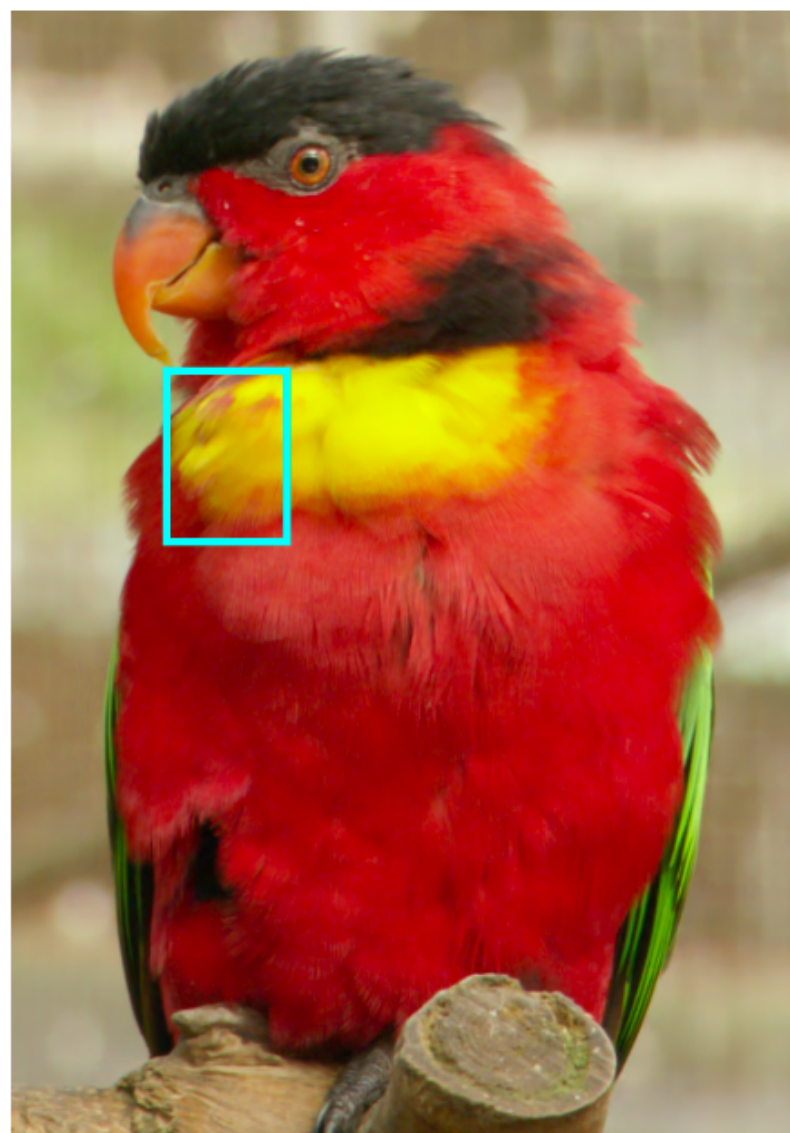
- Temporal Prior (Expensive):

$$p(v_t, w_t) = \prod p(w_t | w_{<t})p(v_t | v_{<t})$$

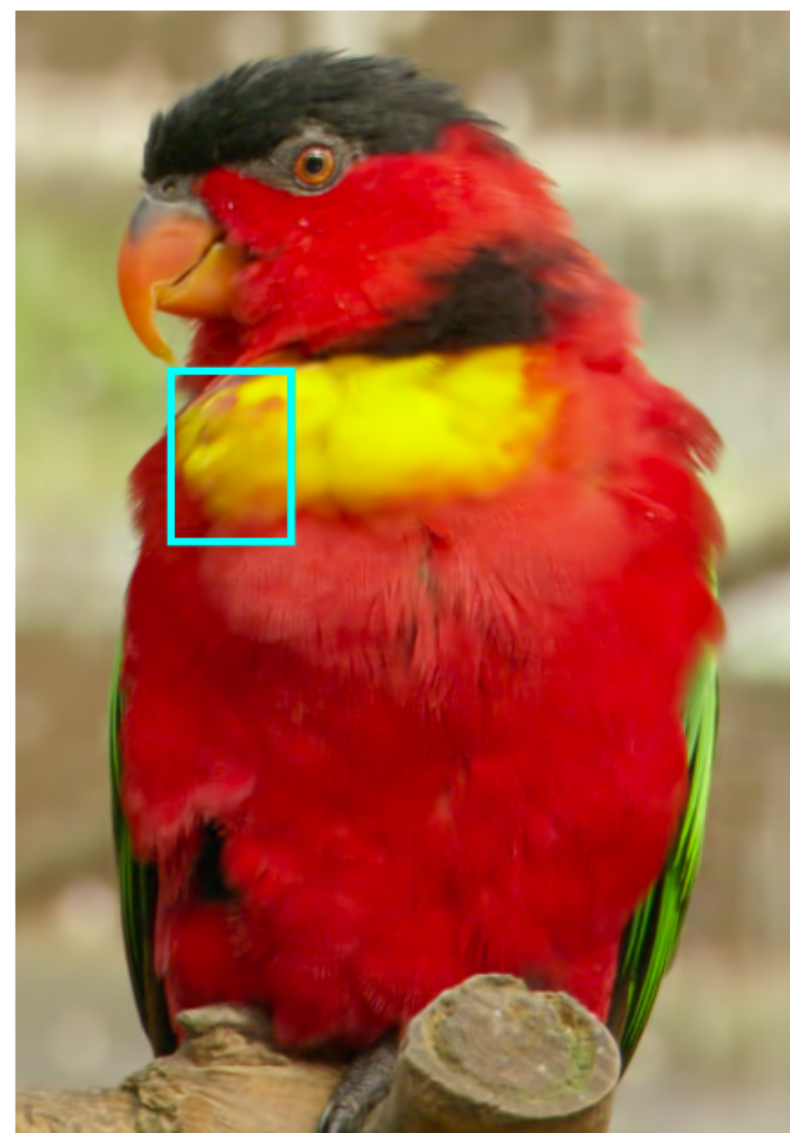


Experiment

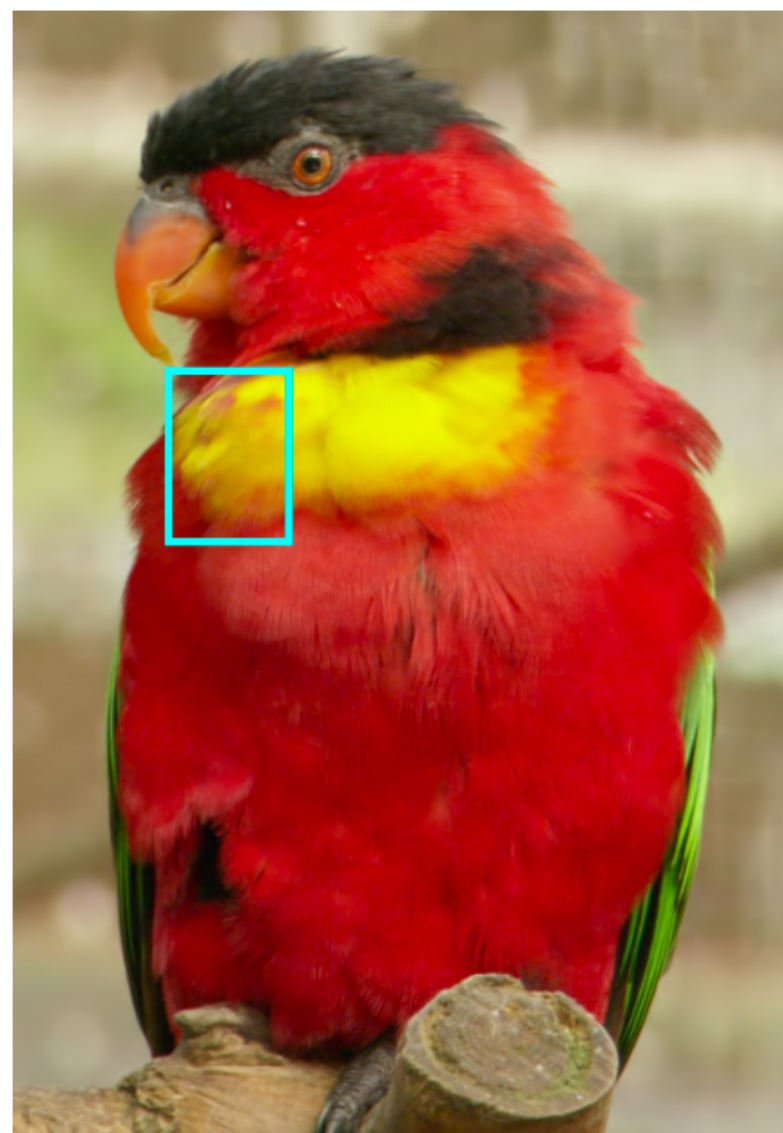




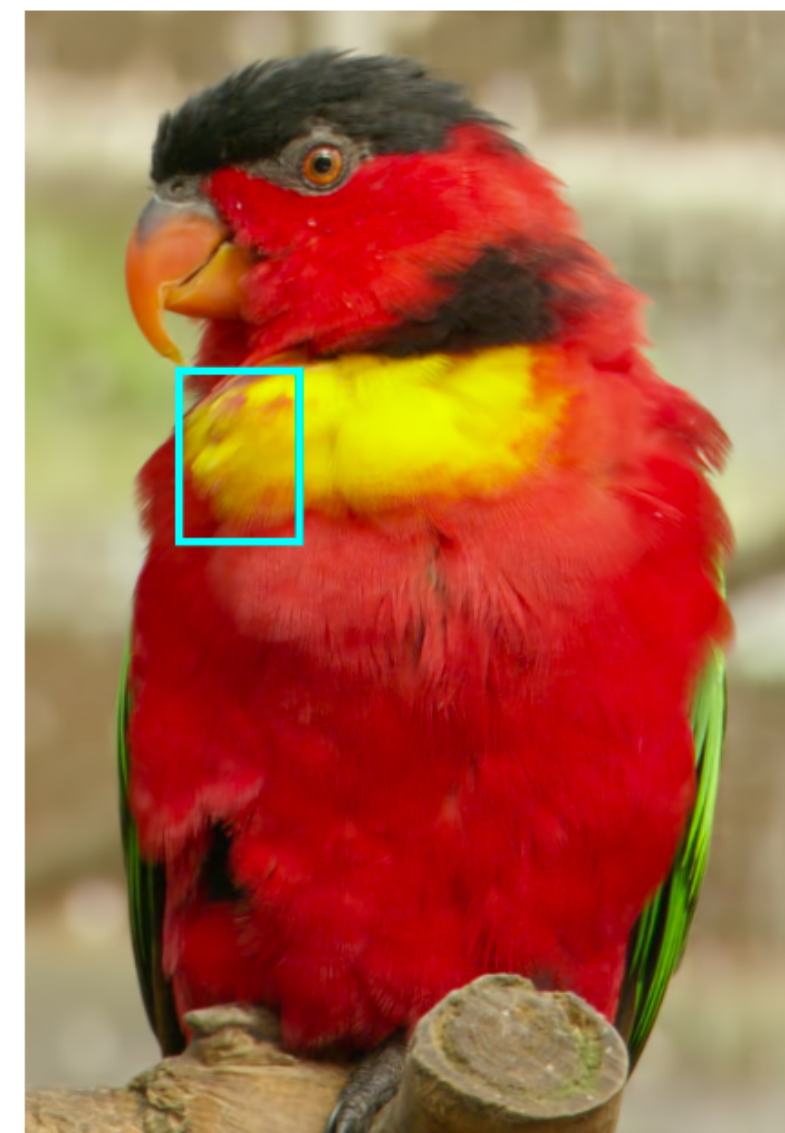
(a) HEVC;
BPP = 0.087,
PSNR = 38.099



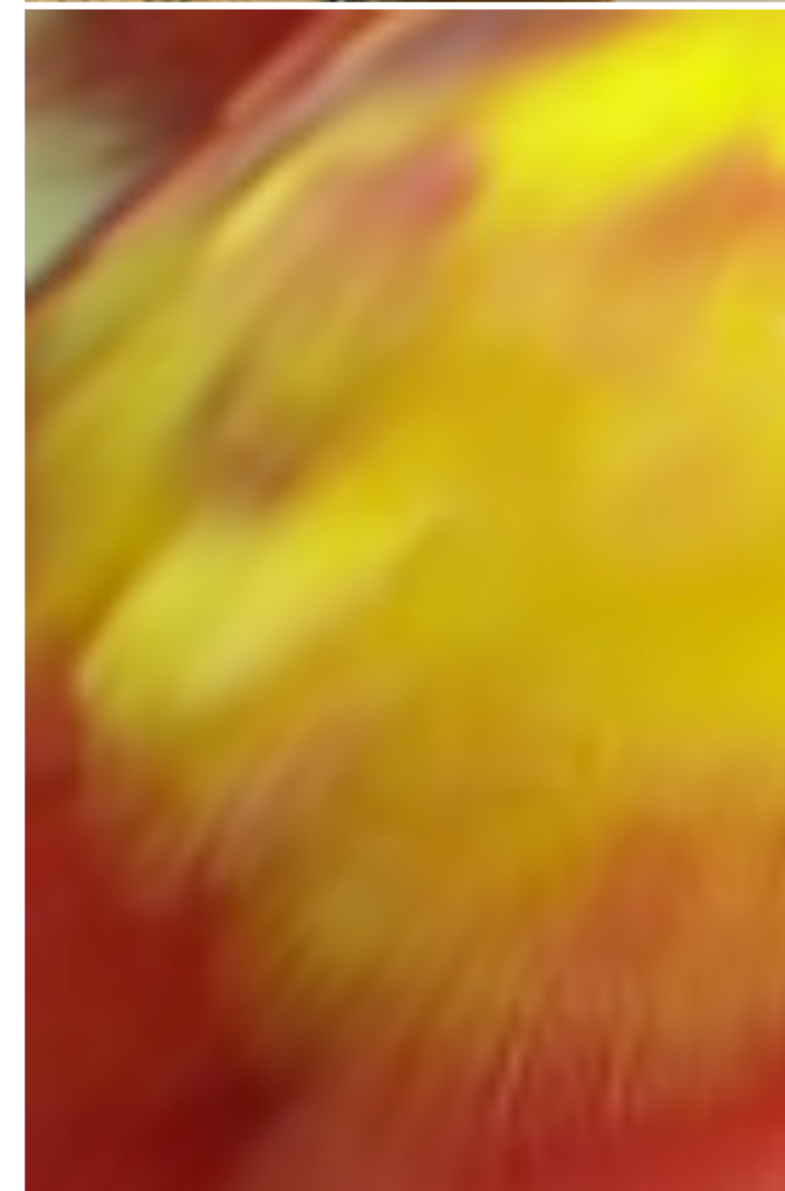
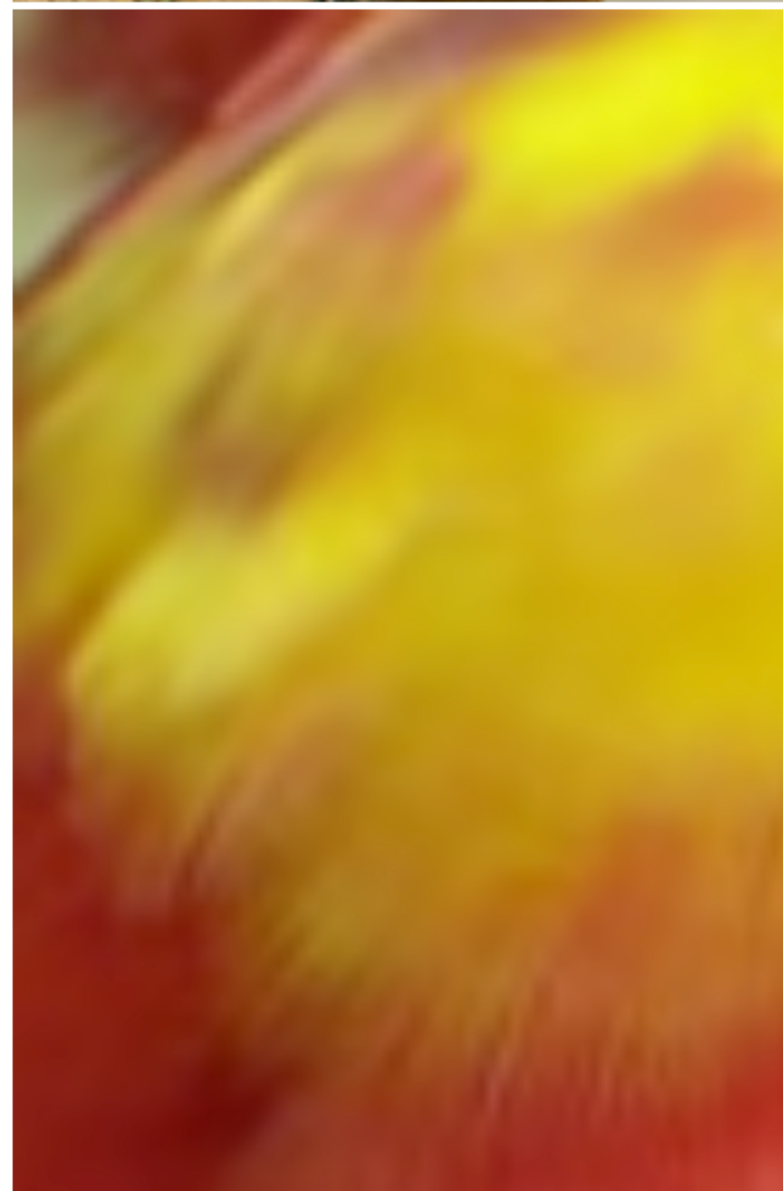
(b) SSF;
BPP = 0.082,
PSNR = 37.440



(c) STAT-SSF (ours);
BPP = 0.0768,
PSNR = 38.108



(d) STAT-SSF-SP (ours);
BPP = 0.0551,
PSNR = 38.097



Thank you