The inductive bias of ReLU networks on orthogonally separable data

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Inductive bias

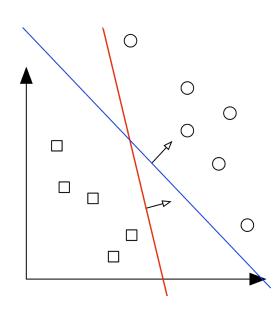
- Many solutions with zero training error, but different generalisation
- Which solution does the algo pick?

Inductive bias

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Setting

- Binary classification $\{(\mathbf{x}_i,y_i)\}\subset \mathbb{R}^d \times \{\pm 1\}$
- Linearly separable data
- Classifier $\operatorname{sign} f_{m{ heta}}(\mathbf{x})$
- Train by minimising the cross-ent loss by gradient flow

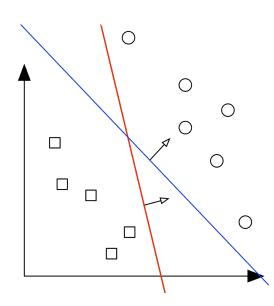


Previous work -- linear models

Logistic regression [Soudry etal 2017]

$$f(\mathbf{x}) = \mathbf{w}^{\mathsf{T}} \mathbf{x}$$

 $\mathbf{w}/\|\mathbf{w}\| \to \text{max-margin direction } \mathbf{w}_{\text{max}}$



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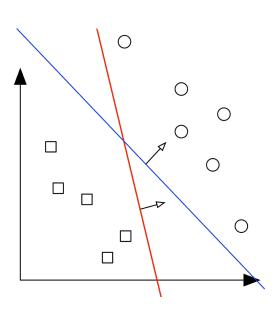
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Deep linear nets [Ji & Telgarsky 2019]

$$f(\mathbf{x}) = \underbrace{\mathbf{W}_L \cdots \mathbf{W}_2 \mathbf{W}_1}_{\mathbf{W}_{\boldsymbol{\theta}}} \mathbf{x}$$

 $\mathbf{w}_{\boldsymbol{\theta}}/\|\mathbf{w}_{\boldsymbol{\theta}}\| \to \text{max-margin direction } \mathbf{w}_{\text{max}}$

$$\mathbf{W}_1/\|\mathbf{W}_1\| \to \mathbf{u}\mathbf{w}_{\max}^{\intercal}$$



This work -- ReLU networks

- Orthogonal separability
 - Stronger version of linear separability
- Two-layer ReLU networks

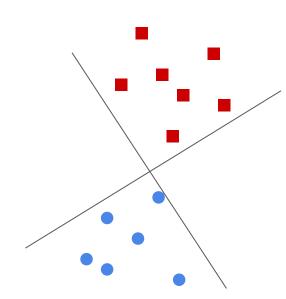
Main result: We characterise what the net converges to.

1. Orthogonal separability

Dataset $\{(\mathbf{x}_i, y_i)\} \subset \mathbb{R}^d \times \{\pm 1\}$ is orthogonally separable, if for all (i,j),

$$\mathbf{x}_i^\mathsf{T} \mathbf{x}_j > 0 \text{ if } y_i = y_j$$

$$\mathbf{x}_i^\mathsf{T} \mathbf{x}_j \leq 0 \text{ if } y_i \neq y_j$$



1. Orthogonal separability

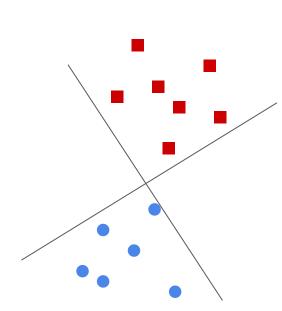
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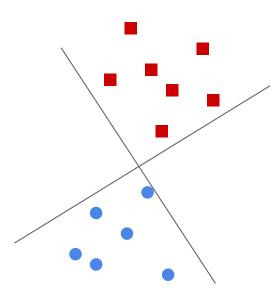
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2. <u>Two-layer ReLU networks</u>

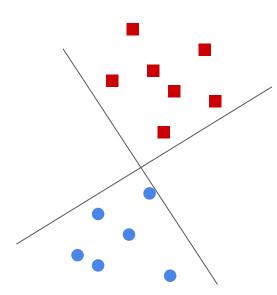
$$f_{\boldsymbol{\theta}}(\mathbf{x}) \triangleq \mathbf{a}^{\mathsf{T}} \rho(\mathbf{W}\mathbf{x})$$



- 1. Orthogonal separability
- 2. Two-layer ReLU networks
- 3. <u>Trained by gradient flow with cross-ent loss</u>



- 1. Orthogonal separability
- 2. Two-layer ReLU networks
- 3. Trained by gradient flow with cross-ent loss
- 4. Near-zero initialisation



Main result

Positive / negative max-margin direction:

$$\mathbf{w}_{+} = \underset{\mathbf{w}}{\operatorname{arg \, min}} \|\mathbf{w}\|^{2}$$
 subject to $\mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} \geq 1$ for $i : y_{i} = 1$, $\mathbf{w}_{-} = \underset{\mathbf{w}}{\operatorname{arg \, min}} \|\mathbf{w}\|^{2}$ subject to $\mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} \geq 1$ for $i : y_{i} = -1$

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Main result

$$\frac{\mathbf{W}(t)}{\left\|\mathbf{W}(t)\right\|_{F}} \rightarrow \mathbf{u}\mathbf{w}_{+}^{\intercal} + \mathbf{z}\mathbf{w}_{-}^{\intercal} \qquad \qquad \frac{\mathbf{a}(t)}{\left\|\mathbf{a}(t)\right\|} \ \rightarrow \ \mathbf{u}\left\|\mathbf{w}_{+}\right\| - \mathbf{z}\left\|\mathbf{w}_{-}\right\|$$

$$\mathbf{u}, \mathbf{z} \in \mathbb{R}^p_+$$
 such that either $u_i = 0$ or $z_i = 0$