

Efficient Continual Learning with Modular Networks and Task-Driven Priors

ICLR 2021

Tom Veniat
Ludovic Denoyer
Marc'Aurelio Ranzato

Different levels of diversity

- Classes (incremental Cifar-100 [Krizhevsky 2009], ...)

Different levels of diversity

- Classes (incremental Cifar-100 [Krizhevsky 2009], ...)
- Domain (VDD [Rebuffi, Bilen, and Vedaldi 2017] ...)

Different levels of diversity

- Classes (incremental Cifar-100 [Krizhevsky 2009], ...)
- Domain (VDD [Rebuffi, Bilen, and Vedaldi 2017] ...)
- Modalities (Text, Vision, Audio, ...)

Different levels of diversity

- Classes (incremental Cifar-100 [Krizhevsky 2009], ...)
- Domain (VDD [Rebuffi, Bilen, and Vedaldi 2017] ...)
- Modalities (Text, Vision, Audio, ...)
- **Amount of data**

The problem

- Some tasks will require transferring knowledge from past experiences to be solved.
- Focus on maximizing transfer instead of minimizing forgetting.

The problem

- Some tasks will require transferring knowledge from past experiences to be solved.
- Focus on maximizing transfer instead of minimizing forgetting.

Contribution

- Identify a set of desired properties of a CL system to deal with this diversity.
- Define metrics and streams for assessing the performance of an algorithm in each of these dimensions : CTrL
- Propose a new model able to perform well in most of the identified scenarios : MNTDP

Direct Transfer

$$\mathcal{S}^- = (t_1^+, t_2, t_3, t_4, t_5, t_1^-)$$

Direct Transfer

$$\mathcal{S}^- = (t_1^+, t_2, t_3, t_4, t_5, t_1^-)$$

Knowledge Update

$$\mathcal{S}^+ = (t_1^-, t_2, t_3, t_4, t_5, t_1^+)$$

Direct Transfer

$$\mathcal{S}^- = (t_1^+, t_2, t_3, t_4, t_5, t_1^-)$$

Knowledge Update

$$\mathcal{S}^+ = (t_1^-, t_2, t_3, t_4, t_5, t_1^+)$$

Transfer to similar Input/Output Distributions

$$\mathcal{S}^{\text{in}} = (t_1, t_2, t_3, t_4, t_5, t_1')$$

$$\mathcal{S}^{\text{out}} = (t_1, t_2, t_3, t_4, t_5, t_1'')$$

Plasticity

$$\mathcal{S}^{\text{pl}} = (t_1, t_2, t_3, t_4, t_5)$$

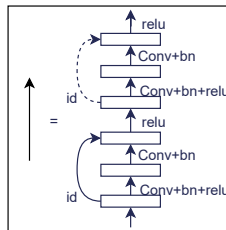
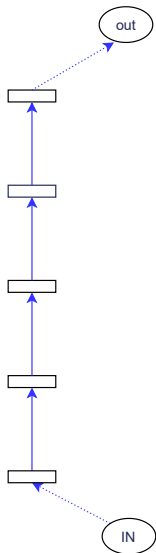
Plasticity

$$\mathcal{S}^{\text{pl}} = (t_1, t_2, t_3, t_4, t_5)$$

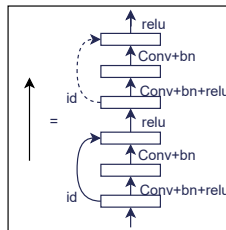
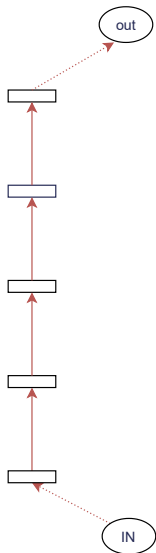
Scalability

- $\mathcal{S}^{\text{long}}$ composed of 100 tasks.
- Contains the 5 other scenarios

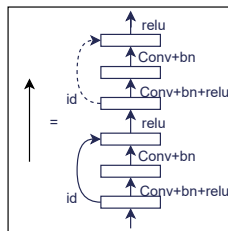
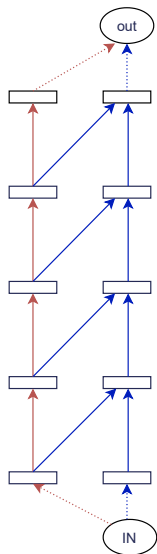
Modular Network



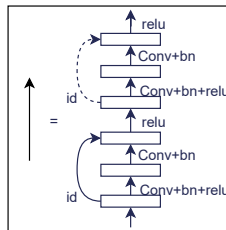
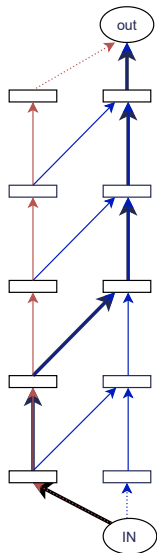
Modular Network



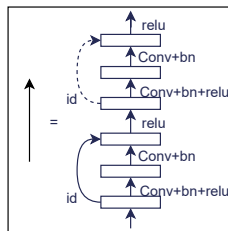
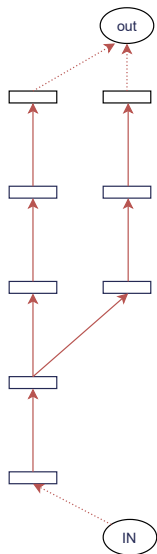
Modular Network



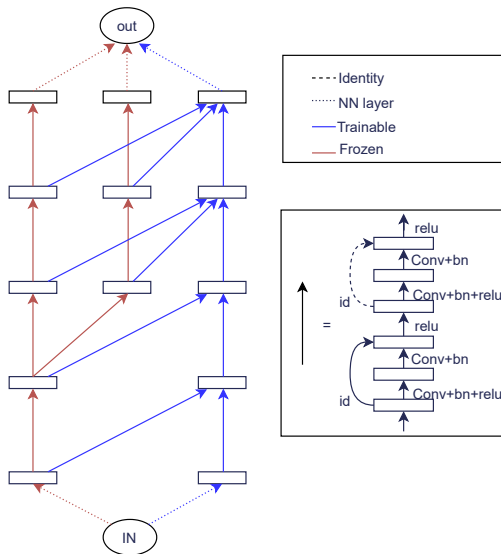
Modular Network



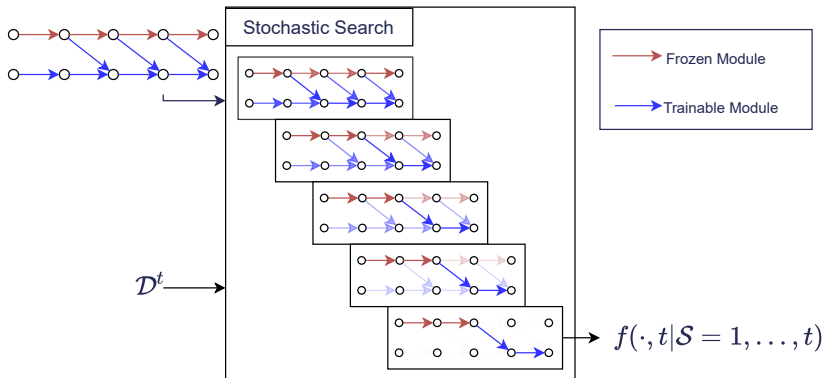
Modular Network



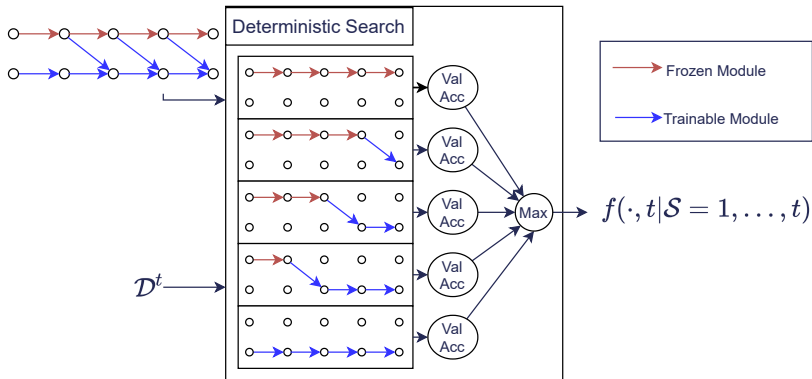
Modular Network



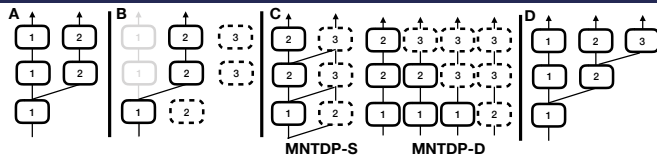
MNTDP-S



MNTDP-D



Modular Network + Task-Driven Prior



Radar plots on CTrL

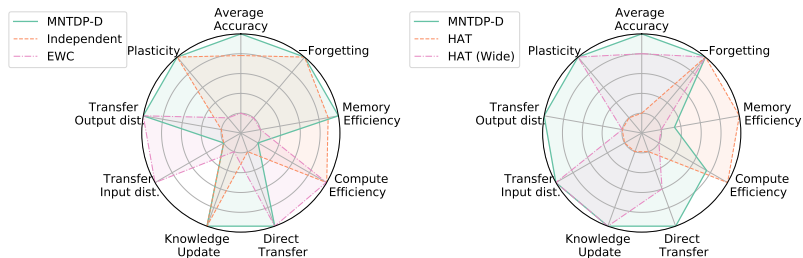


Figure 1: Comparison of various CL methods on the CTrL benchmark using Resnet (left) and Alexnet (right) backbones. MNTDP-D is our method.

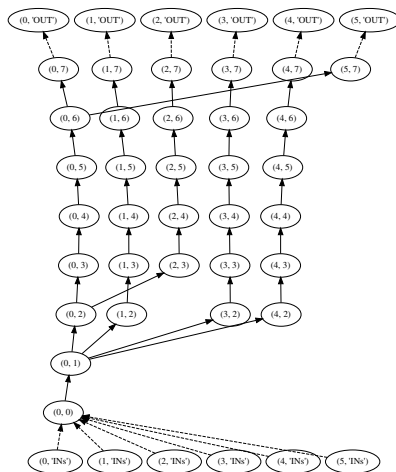


Figure 2: Global graph of paths discovered by MNDTP-D on the $\mathcal{T}(\mathcal{S}^{\text{out}})$ Stream. "INs" (resp. "OUT") nodes are the input (resp. output) of the path for each task.

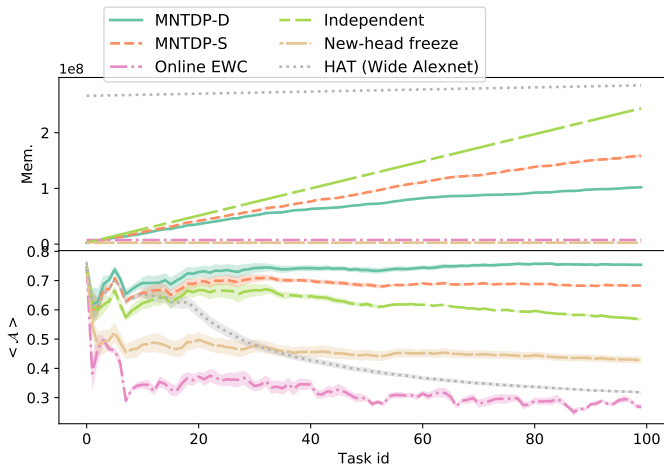
$\mathcal{S}^{\text{long}}$


Figure 3: Evolution of $\langle \mathcal{A} \rangle$ and Mem. on $\mathcal{S}^{\text{long}}$.



Krizhevsky, Alex (2009). “Learning Multiple Layers of Features from Tiny Images”. In: *University of Toronto, technical report*.



Rebuffi, Sylvestre-Alvise, Hakan Bilen, and Andrea Vedaldi (2017). “Learning multiple visual domains with residual adapters”. In: *Advances in Neural Information Processing Systems 30: Annual Conference on Neural Information Processing Systems 2017, 4-9 December 2017, Long Beach, CA, USA*. Ed. by Isabelle Guyon et al., pp. 506–516. URL: <http://papers.nips.cc/paper/6654-learning-multiple-visual-domains-with-residual-adapters>.