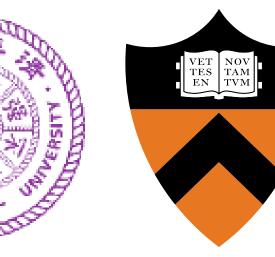


# ICLR A Quadratic Synchronization Rule for Distributed Deep Learning





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#### Overview

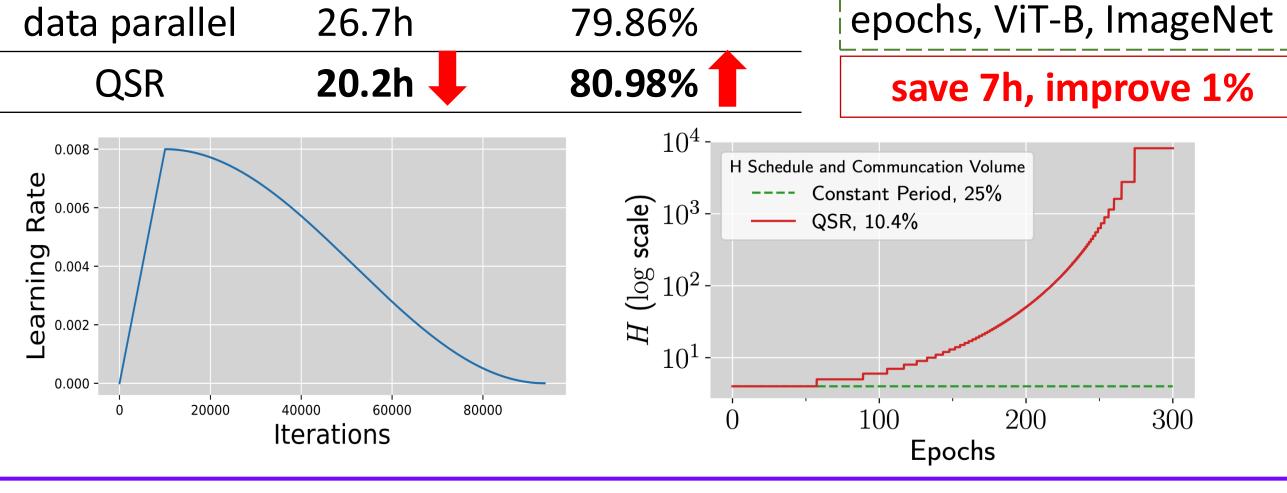
Local gradient methods, e.g., Local SGD, improve the communication efficiency of data parallel training by letting workers communicate only every H steps.

Key question: how to set the synchronization period H? Why hard?

- Optimization theory: larger  $H \Rightarrow$  slower convergence, communication & convergence tradeoff (Stich, 2018; Yu-Yang-Zhu, 2018)
- But for modern neural nets
  - same train loss ⇒ same test loss
  - In some cases, increase  $H \Rightarrow$  higher test acc. (Lin et al., 2020)

Main contribution: a theory-grounded strategy to set *H*!

## Quadratic Synchronization Rule (QSR) $H^{(s)} = \max\{H_{\text{base}}, \lfloor (\alpha/\eta_t)^2 \rfloor\}$ -improve generalization by quadratically scaling H as LR decays - save communication simultaneously val. acc. time Setting: Local AdamW, 300



### **Background: Local Gradient Methods**

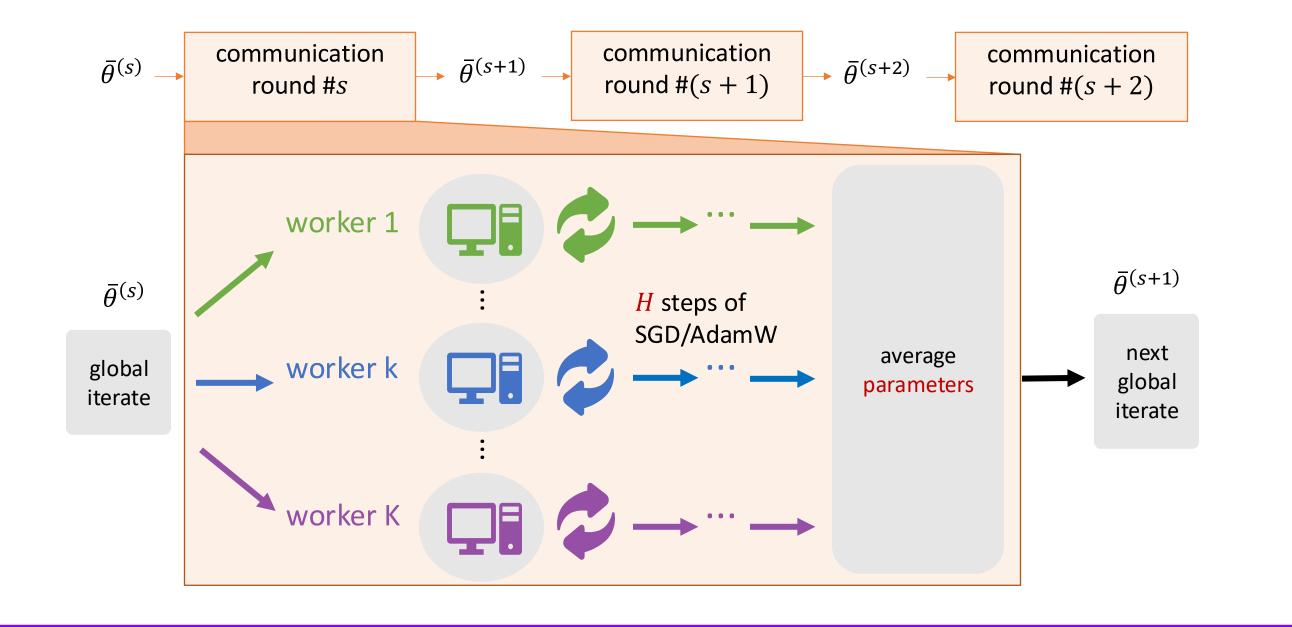
#### Data parallel training

- Distribute gradient computation on B samples to K workers
- Each iteration, each worker: 1. compute gradients on B/K samples; 2. average gradients via All-Reduce; 3. update using the averaged gradient & optimizer OPT

Issue: high comm. cost due to frequent synchronization

#### **Local gradient methods**

- Worker locally updates own replica with OPT
- Average model params. every H steps



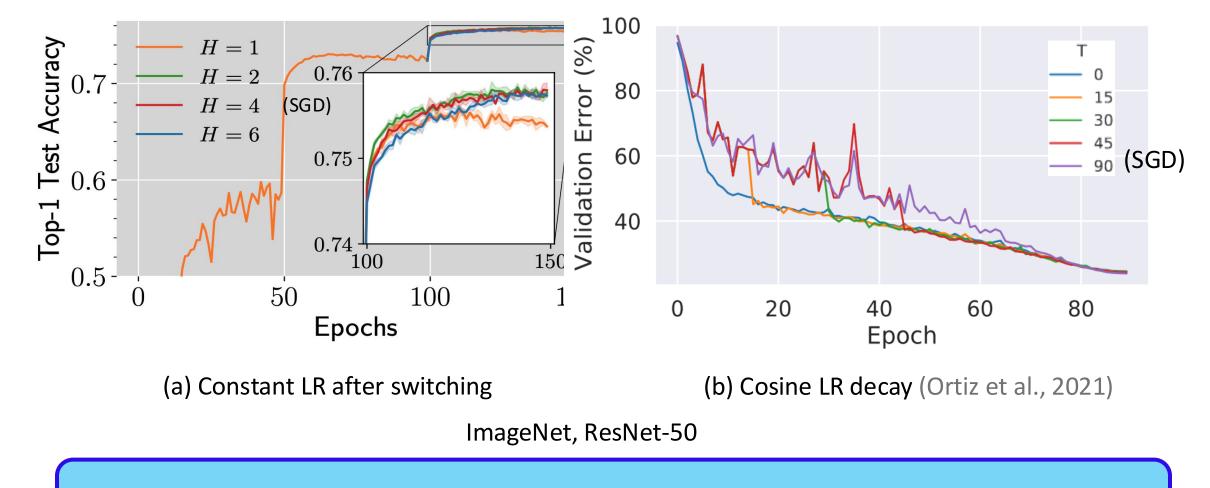
#### **Controversy on the Generalization Benefit of Local SGD**

Local steps improve generalization (Lin et al., 2020, Fig. (a))

- Run #1: Parallel SGD ( $\equiv$  Local SGD with H=1)
- Run #2: #1 + switch to Local SGD with H > 1 at some epoch  $t_0$  (Post-local SGD)
- Result: test acc. #2 > #1

#### The improvement seems only short term (Ortiz et al., 2021, Fig. (b))

- For cos LR decay, the generalization benefit appears only shortly after switching



Hint: the generalization benefit has something to do with LR

#### **Our Roadmap**

**Goal**: find the *H* schedule to maximize test acc.

Theory: understanding how the generalization benefit arises

#### **Practical guidance:** QSR $(H \sim \eta^{-2})$

#### **Empirical validation:** Local SGD & AdamW

maximize it!

## **Theory: Why does Local SGD Generalize Better?**

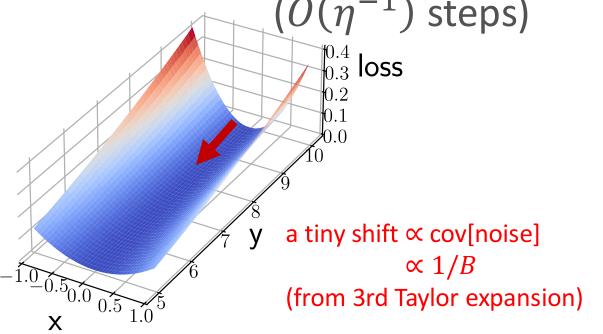
**Setup** (Follow Blanc et al., 2020; Damian et al., 2021; Li et al., 2022) Assume (1) a minimizer manifold  $\Gamma$ ; (2) a small LR  $\eta$ ; (3)

Analyze dynamics of (Local) SGD near  $\Gamma$ 

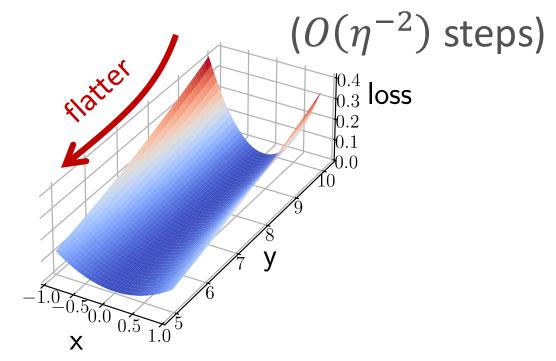
#### Fast and slow dynamics in SGD

(Blanc et al., 2020; Damian et al., 2021; Li et al., 2022) Fast Dynamics (short term)

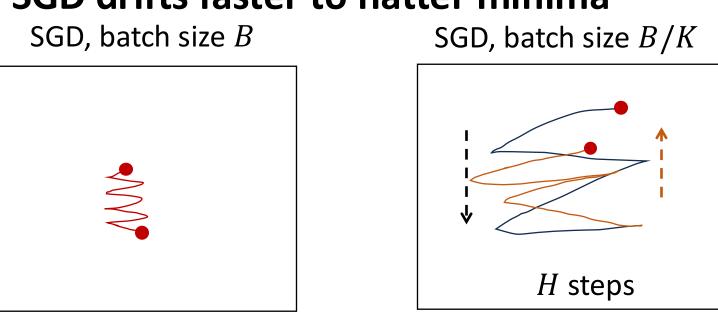
# Diffuse locally near a minimizer $(O(\eta^{-1}) \text{ steps})$

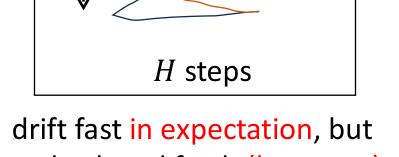


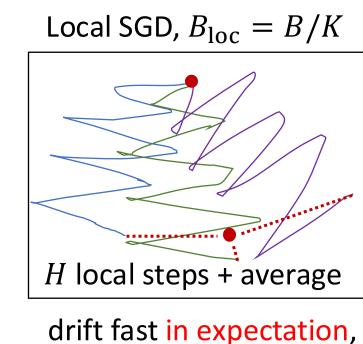
Slow Dynamics (long term) "Center" of the diffusion shifts



#### Local SGD drifts faster to flatter minima







go back and forth (large var.)

# averaging reduces var.

### SDE approximations for different scalings of H

**Theorem (informal).** For  $O(\eta^{-2})$  steps, Local SGD can be approximated by the following SDEs on  $\Gamma$ : 1.  $H = \beta/\eta$  (Gu et al., 2023)

$$\mathrm{d}\boldsymbol{\zeta}(t) = P_{\boldsymbol{\zeta}}\Big(\underbrace{\frac{1}{\sqrt{B}}\boldsymbol{\Sigma}_{\parallel}^{1/2}(\boldsymbol{\zeta})\mathrm{d}\boldsymbol{W}_{t}}_{-\frac{1}{2B}}\nabla^{3}\mathcal{L}(\boldsymbol{\zeta})[\widehat{\boldsymbol{\Sigma}}_{\Diamond}(\boldsymbol{\zeta})]\mathrm{d}t - \underbrace{\frac{K-1}{2B}}\nabla^{3}\mathcal{L}(\boldsymbol{\zeta})[\widehat{\boldsymbol{\Psi}}(\boldsymbol{\zeta})]\mathrm{d}t\Big) \quad \text{- increases with } H; \to 0 \text{ as } H\eta \to 0; \to \widehat{\boldsymbol{\Sigma}}_{\Diamond}(\boldsymbol{\zeta}) \text{ as } H\eta \to \infty$$

· larger ⇒ stronger implicit bias - increases with H;  $\rightarrow 0$  as

What about  $H \sim \eta^{-2}$ 

Same as SGD (Li et al., 2022) Unique drift term of Local SGD

**Remark:** (1) H should be at least  $\eta^{-1}$  to see the benefit (2) stronger implicit bias for larger H (3) but also higher approximation error for larger H (valid for  $o(\eta^{-2})$ , fails for  $\omega(\eta^{-2})$ )

2. 
$$H = (\alpha/\eta)^2$$
 (our new result)
$$d\mathcal{L}(t) = D \cdot \begin{pmatrix} 1 & \mathbf{\Sigma}^{1/2}(\mathcal{L}) d\mathbf{W}(t) & K & \nabla^3 \mathcal{L}(\mathcal{L}) \end{bmatrix} \hat{\mathbf{S}}$$

drift slowly

$$d\boldsymbol{\zeta}(t) = P_{\boldsymbol{\zeta}} \left( \frac{1}{\sqrt{B}} \boldsymbol{\Sigma}_{\parallel}^{1/2}(\boldsymbol{\zeta}) d\boldsymbol{W}(t) - \frac{K}{2B} \nabla^{3} \mathcal{L}(\boldsymbol{\zeta}) [\widehat{\boldsymbol{\Sigma}}_{\Diamond}(\boldsymbol{\zeta})] dt \right)$$

K times of SGD; Local SGD with  $H = \beta/\eta$  when  $\beta \to \infty$ 

 $H \sim \eta^{-1}$  to see the benefit,  $H \sim \eta^{-2}$  to

(also tried  $H \sim \eta^{-3}$ , worse than QSR)