



Energy-guided Entropic Neural Optimal Transport

Petr Mokrov¹ Alexander Korotin^{1,2} Alexander Kolesov¹
Nikita Gushchin¹ Evgeny Burnaev^{1,2}

¹Skolkovo Institute of Science and Technology

²Artificial Intelligence Research Institute

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Entropic Optimal Transport. Theoretical formulation¹

Let \mathbb{P} and \mathbb{Q} be continuous distributions on $\mathcal{X} \subset \mathbb{R}^{D_x}$ and $\mathcal{Y} \subset \mathbb{R}^{D_y}$. **Entropic Optimal Transport (EOT)** is as follows:

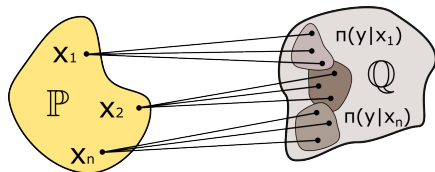
$$\text{EOT}_{c,\epsilon}(\mathbb{P}, \mathbb{Q}) = \min_{\pi \in \Pi(\mathbb{P}, \mathbb{Q})} \int_{\mathcal{X}} C(x, \pi(\cdot|x)) d\mathbb{P}(x)$$

The minimizer π^* is called the Entropic OT plan.

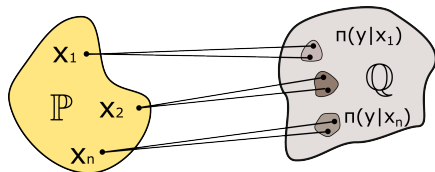
$$C(x, \pi(\cdot|x)) \stackrel{\text{def}}{=} \underbrace{\int_{\mathcal{Y}} c(x, y) d\pi(y|x)}_{\text{Dissimilarity}} - \underbrace{\epsilon H(\pi(\cdot|x))}_{\text{Diversity}}.$$

Regularization strength ϵ controls the diversity.

- $\Pi(\mathbb{P}, \mathbb{Q})$ are distributions on $\mathcal{X} \times \mathcal{Y}$ with marginals \mathbb{P}, \mathbb{Q}



Stochastic EOT maps for large ϵ .



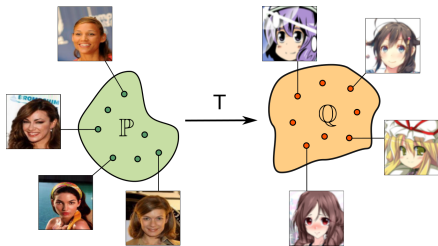
Stochastic EOT maps for small ϵ .

¹Marco Cuturi (2013). "Sinkhorn distances: Lightspeed computation of optimal transport". In: *Advances in neural information processing systems* 26.

Entropic Optimal Transport. Applications

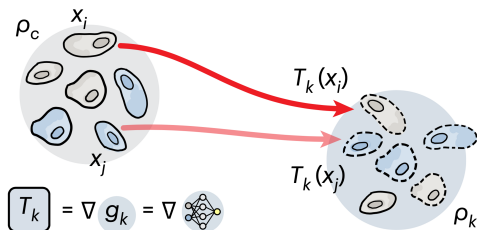
Domain Translation.²

By considering two unpaired image datasets as samples from \mathbb{P} and \mathbb{Q} , EOT learns a map between datasets that preserves content.



Single-Cell (SC) Biological data.³

SC technology determines the gene expression profile of each measured cell, but destroys all measured cells. EOT learns map between cell populations before and after perturbation.



²Alexander Korotin, Daniil Selikhanovych, and Evgeny Burnaev (2023). “Neural Optimal Transport”. In: *International Conference on Learning Representations*.

³Charlotte Bunne et al. (2023). “Learning single-cell perturbation responses using neural optimal transport”. In: *Nature Methods*, pp. 1–10.

Solving EOT problem: Lagrangian multipliers \rightarrow Max-min

◆ Original EOT problem:

$$\pi^* = \arg \min_{\pi \in \Pi(\mathbb{P}, \mathbb{Q})} \left\{ \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) \underbrace{d\pi(x, y)}_{=d\pi(y|x)d\mathbb{P}(x)} - \epsilon \int_{\mathcal{X}} H(\pi(\cdot|x)) d\mathbb{P}(x) \right\}$$

◆ max-min (dual) EOT problem, the second marginal distribution constraint is relaxed with **Lagrangian multiplier** $f : \mathcal{Y} \rightarrow \mathbb{R}$ (continuous functions):

$$(f^*, \pi^*) = \arg \sup_f \min_{\pi \in \Pi(\mathbb{P})} \left\{ \int_{\mathcal{X} \times \mathcal{Y}} c(x, y) d\pi(x, y) - \epsilon \int_{\mathcal{X}} H(\pi(\cdot|x)) d\mathbb{P}(x) - \int_{\mathcal{X} \times \mathcal{Y}} f(y) d\pi(x, y) + \int_{\mathcal{Y}} f(y) d\mathbb{Q}(y) \right\}$$

Remark (max-min reformulation of the EOT problem)

Original and max-min EOT problems from above are equivalent, i.e., they yield the same optimal value $EOT_{c, \epsilon}$ and permit the same minimizer $\pi^* \in \Pi(\mathbb{P}, \mathbb{Q})$.

Solving EOT problem: Max-min \rightarrow Energy-based EOT

◆ max-min EOT problem:

$$\sup_f \min_{\pi \in \Pi(\mathbb{P})} \left\{ \underbrace{\int_{\mathcal{X} \times \mathcal{Y}} c(x, y) d\pi(x, y) - \epsilon \int_{\mathcal{X}} H(\pi(\cdot|x)) d\mathbb{P}(x) - \int_{\mathcal{X} \times \mathcal{Y}} f(y) d\pi(x, y) + \int_{\mathcal{Y}} f(y) d\mathbb{Q}(y)}_{\text{has a closed-form solution } \pi^f \in \Pi(\mathbb{P})} \right\}$$

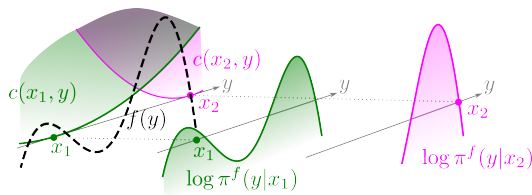
Conditional plans $\pi^f(\cdot|x)$ have **known unnormalized density**:

$$\pi^f(y|x) = \frac{1}{Z(f, x)} \exp\left(\frac{f(y) - c(x, y)}{\epsilon}\right)$$

- $Z(f, x) \stackrel{\text{def}}{=} \int_{\mathcal{Y}} \exp\left(\frac{f(y) - c(x, y)}{\epsilon}\right) dy$ is the **Normalization** const.

◆ Energy-based EOT (after substitution π^f):

$$f^* = \arg \sup_f \left\{ -\epsilon \int_{\mathcal{X}} \log Z(f, x) d\mathbb{P}(x) + \int_{\mathcal{Y}} f(y) d\mathbb{Q}(y) \right\}, \quad \pi^* = \pi^{f^*}.$$



Energy-based EOT: Dealing with π^f

$$d\pi^f(x, y) = d\pi^f(y|x)d\mathbb{P}(x); \quad \pi^f(y|x) = \frac{1}{Z(f, x)} \exp\left(\frac{f(y) - c(x, y)}{\epsilon}\right).$$

Sampling from π^f .

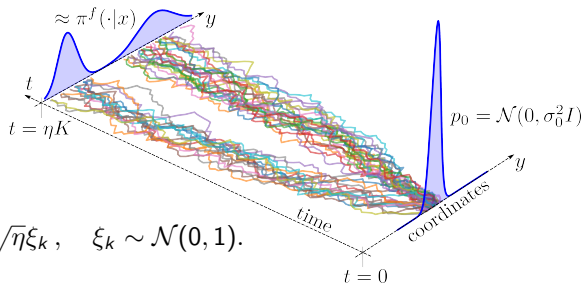
1. Sample $x \sim \mathbb{P}$ (source distribution/dataset).
2. Sample $y \sim \pi^f(\cdot|x)$ (see below).

Sampling from $\pi^f(\cdot|x)$. **Euler-Maruyama**
simulation (a.k.a. Langevin sampling):

- Take prior p_0 (e.g., Gaussian or Uniform); Sample $y_0 \sim p_0$.
- Fix $\eta > 0$ and for $k = 0, 1, \dots, K$ do:

$$y_{k+1} = y_k - \frac{\eta}{2} \nabla_y \left(\frac{c(x, y) - f(y)}{\epsilon} \right) \Big|_{y=y_k} + \sqrt{\eta} \xi_k, \quad \xi_k \sim \mathcal{N}(0, 1).$$

- Output $y = y_K$. It is (approximately) sampled from $\pi^f(\cdot|x)$.



Energy-based EOT: Training aspects

◆ Energy-based EOT objective w.r.t. (scalar-valued) Neural Network f_θ :

$$\mathcal{L}(\theta) = -\epsilon \int_{\mathcal{X}} \log Z(f_\theta, x) d\mathbb{P}(x) + \int_{\mathcal{Y}} f_\theta(y) d\mathbb{Q}(y) \longrightarrow \max_{\theta}.$$

Theorem (Gradient of Energy-based EOT loss $\mathcal{L}(\theta)$)

$$\frac{\partial}{\partial \theta} \mathcal{L}(\theta) = - \int_{\mathcal{X} \times \mathcal{Y}} \left[\frac{\partial}{\partial \theta} f_\theta(y) \right] d\pi^{f_\theta}(x, y) + \int_{\mathcal{Y}} \left[\frac{\partial}{\partial \theta} f_\theta(y) \right] d\mathbb{Q}(y).$$

Proxy loss for Energy-based EOT:

$$\begin{array}{lcl} L(\theta) & = & - \int_{\mathcal{X} \times \mathcal{Y}} f_\theta(y) d\pi^{f_{\text{stop_grad}(\theta)}}(x, y) + \int_{\mathcal{Y}} f_\theta(y) d\mathbb{Q}(y) \\ \left[\begin{array}{c} \text{Sample} \\ \text{estimate} \end{array} \right] \hat{L}(\theta) & = & \left[\begin{array}{c} \text{Langevin Sampling from } \pi^{f_\theta}; \\ \text{Monte-Carlo} \end{array} \right] + \left[\begin{array}{c} \text{Monte-Carlo} \end{array} \right] \end{array}$$

Loss $L(\theta)$ is **maximized** with help of a stochastic gradient ascent procedure.

Training Energy-based EOT: Ultimate Algorithm

Algorithm 1: Entropic OT via Energy-Based Modelling

Input : Source and target distributions \mathbb{P} and \mathbb{Q} , accessible by samples;
Entropy regularization coefficient $\epsilon > 0$, cost function $c(x, y) : \mathbb{R}^{D_x} \times \mathbb{R}^{D_y} \rightarrow \mathbb{R}$;
number of Langevin steps $K > 0$, Langevin discretization step size $\eta > 0$;
basic noise std $\sigma_0 > 0$; potential network $f_\theta : \mathbb{R}^{D_y} \rightarrow \mathbb{R}$, batch size $N > 0$.

Output: trained potential network f_{θ^*} recovering optimal conditional EOT plans

for $i = 1, 2, \dots$ **do**

Derive batches $\{x_n\}_{n=1}^N = X \sim \mathbb{P}$, $\{y_n\}_{n=1}^N = Y \sim \mathbb{Q}$ of sizes N ;

Sample basic noise $Y^{(0)} \sim \mathcal{N}(0, \sigma_0)$ of size N ;

for $k = 1, 2, \dots, K$ **do**

Sample $Z^{(k)} = \{z_n^{(k)}\}_{n=1}^N$, where $z_n^{(k)} \sim \mathcal{N}(0, 1)$;

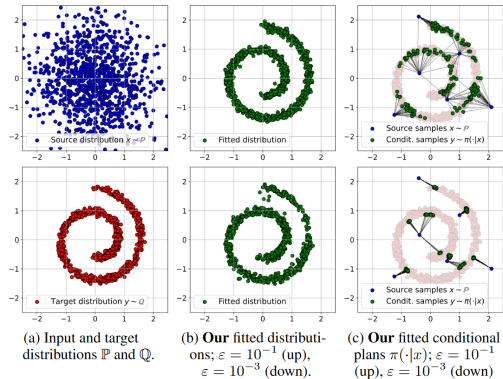
Obtain $Y^{(k)} = \{y_n^{(k)}\}_{n=1}^N$ with Langevin steps:

$$y_n^{(k)} \leftarrow y_n^{(k-1)} + \frac{\eta}{2\epsilon} \cdot \text{stop_grad} \left(\frac{\partial}{\partial y} [f_\theta(y) - c(x_n, y)] \Big|_{y=y_n^{(k-1)}} \right) + \sqrt{\eta} z_n^{(k)}$$

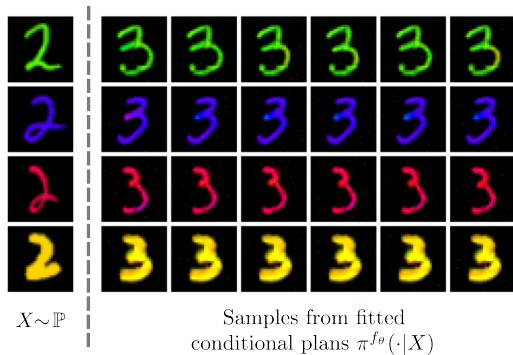
$$\hat{L} \leftarrow -\frac{1}{N} \left[\sum_{y_n^{(K)} \in Y^{(K)}} f_\theta \left(y_n^{(K)} \right) \right] + \frac{1}{N} \left[\sum_{y_n \in Y} f_\theta \left(y_n \right) \right];$$

Perform a gradient step over θ by using $\frac{\partial \hat{L}}{\partial \theta}$;

Energy-guided EOT: Experiments



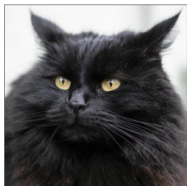
2D Gaussian to Swissroll translation with different Entropic regularizations.



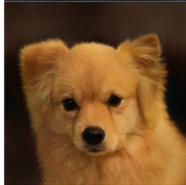
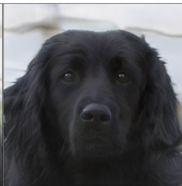
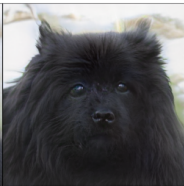
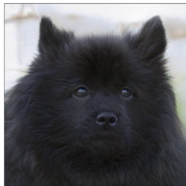
Unpaired image to image translation on Colored MNIST.

Energy-guided EOT: Latent-space AFHQ'512 experiment

Unpaired I2I by latent-space **Energy-guided EOT**



source 512×512
images



generated 512×512 images by **Energy-guided EOT**
working in the latent space of StyleGAN

Thank you!

Energy-guided Entropic Neural Optimal Transport

Towards the Unification of Entropic Optimal Transport and Energy-based Modeling.



<https://github.com/PetrMokrov/Energy-guided-Entropic-OT>

OpenReview.net

<https://openreview.net/forum?id=d6tUsZeVs7>



<https://iclr.cc/virtual/2024/poster/18274>