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Label-Focused Inductive Bias over Latent Object Features in Visual Classification



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ICLR

Preference in Neural Networks in Image Classification

- In most well-known neural networks in image classification
 - Models learn features based on visual similarity and differentiation depending on their classes
 - Preference for the input-domain(=visual information) to handle the similarity of features is a common property
- Neural networks learn relation over the latent objects based on the preference for the input domain

Undescribed World Knowledge (UWK)

- However, **relation on the latent objects** learned by neural networks **may be different in human labeling** based on the world knowledge



Visually similar, but semantically unrelated samples

- Regarded as ambiguous samples in visual classification
- But, we can simply differentiate them by using unobserved relations in the data

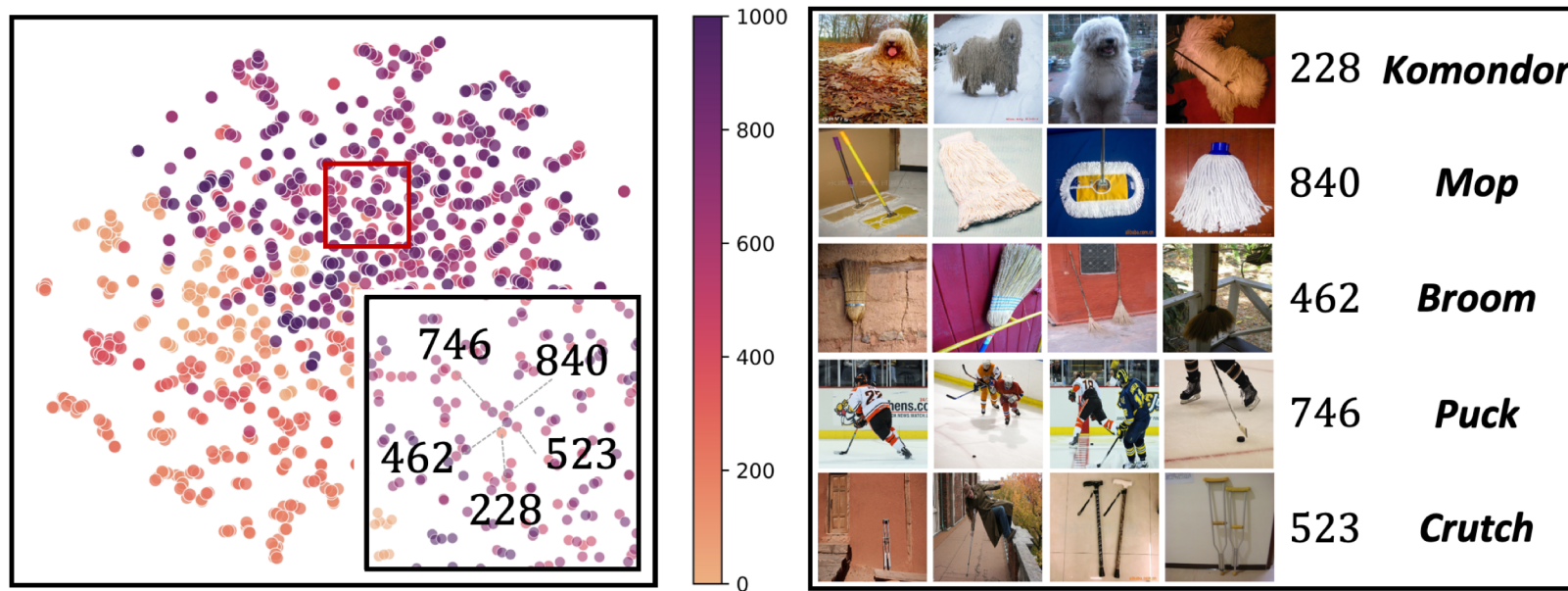
- **Undescribed World Knowledge (UWK)**
 - Undescribed relations over internal objects for determining output human labeling
 - Conflicts between input-domain information and UWK has not been discussed

Overview of Our Work

- What do we want to solve?
 - The dominance of input-domain focused inductive bias in visual neural networks
 - Conflicts between input-domain focused inductive bias and UWK limits the generalization
- How can we handle it?
 - Propose training strategy *Label-focused Latent-object Biasing (LLB)*
 - We disconnect visual dependencies
 - Learn *label-focused inductive bias* over latent object features determined solely by categorization of labels
- Strength of our LLB
 - Our LLB can be simply applied to any networks based on Transformer architectures
 - LLB shows general improvements compared to different ViT networks

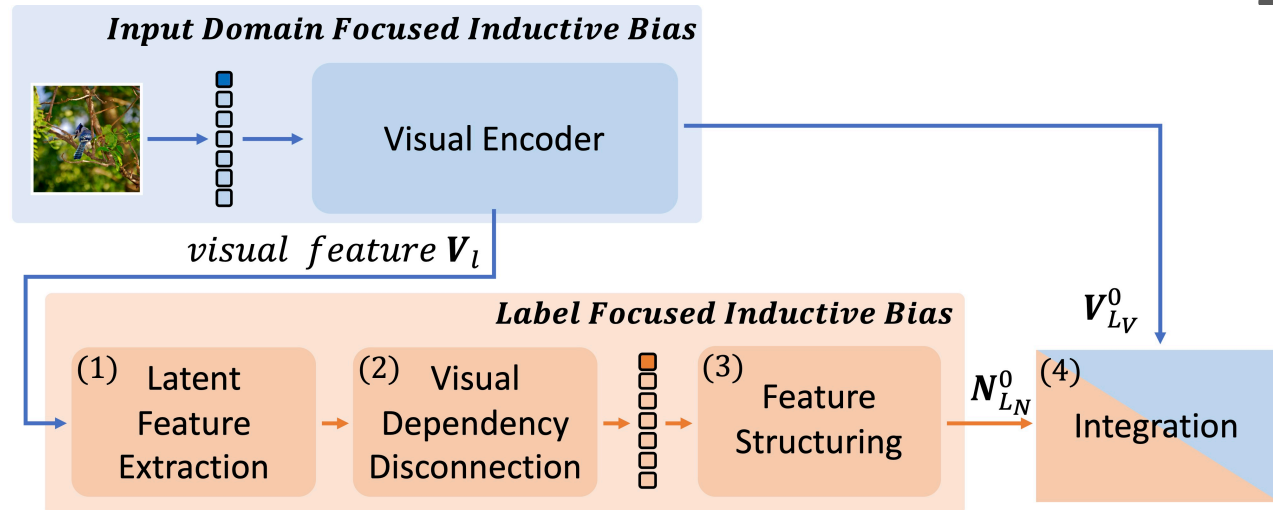
Preliminary Analysis for Problem Confirmation

- Dominance of the input-domain focused inductive bias over the UWK
 - Visually similar, but semantically unrelated class centroids are distributed close



ViT representation centroids of of Class-wise
Features (IN1K classes)

Label-focused Latent-object Biasing (LLB)



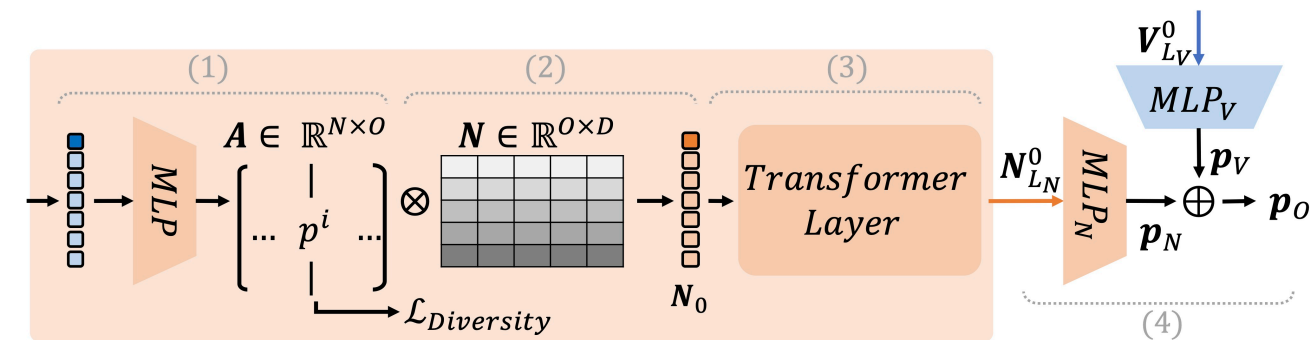
• Four sequential steps

1) Latent Object Extraction from Visual Features

2) Visual Dependency Disconnection

3) Non-visual Feature Structuring

4) Integration of Non-visual and Visual Feature



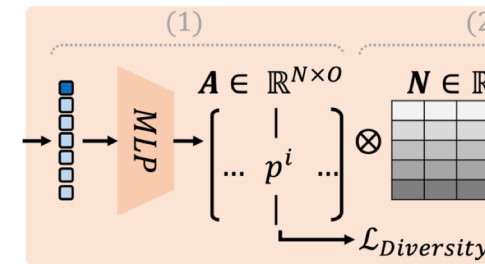
1. Latent Object Extraction from Visual Features

- Aims to **quantize visual features into a set of latent objects**

- We denote visual features from ViT as $V_l = [v_l^i]_{i=0}^N$

- p^i determines the probability of selecting the latent object of index i of O objects

$$p^i = \text{Softmax}(\text{MLP}(v_l^i)) \quad , \quad p^i \in \mathbb{R}^O$$



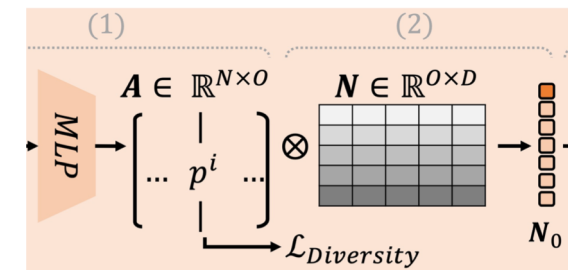
- Additional regularization term that promotes diversity of probabilities

$$\mathcal{L}_{Diversity} = -\mathcal{H}(\tilde{p}), \quad \text{where } \tilde{p} = \frac{1}{N} \sum_{i=0}^N p^i \quad \text{and} \quad \mathcal{H}(p) = -\sum_{i=1}^O p^i \log(p^i)$$

2. Visual Dependency Disconnection

- Main idea of visual disconnection is to **assign separate embedding parameters to visually determined latent objects**
 - Latent object is mapped to separate learnable embedding
 - Learnable embedding **Non-visual features** $N = [n^i]_{i=0}^O \in \mathbb{R}^{O \times D}$
 - Operates matrix multiplication of assign matrix $A = [p^i]_{i=0}^N$

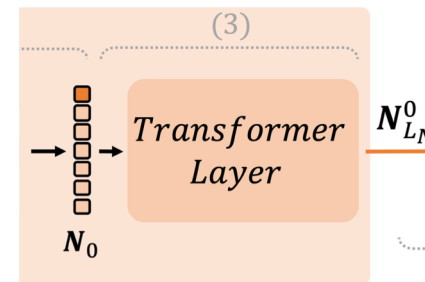
$N_0 = \text{Disconnect}(\mathbf{A}, \mathbf{N}) = \mathbf{A} \times \mathbf{N}$
 \mathbf{A} : A matrix of patch-wise probability vectors to select latent objects
 \mathbf{N} : A matrix of non-visual features in disconnected parameters from input



3. Non-visual Feature Structuring

- Non-visual Feature Structuring aims to **redefine the similarity of features built over latent objects via solely the categorization of labels**
- We use transformer layers to extensively discern semantic relations

$$\mathbf{N}_{L_N} = g([\mathbf{c}_n || \mathbf{N}_0], \mathbf{W})$$

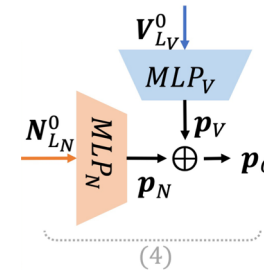


- Outputs **structured non-visual features** \mathbf{N}_{L_N}

4. Integration of Non-visual and Visual Feature

- Aims to **leverage the strengths of both visual and non-visual features**
- We employ a separate classifier for each predictions and aggregate the output probability vectors with balancing parameter α

$$\begin{aligned}\mathbf{p}_V &= \text{SoftMax}(\text{MLP}_V(\mathbf{c}_v)) \\ \mathbf{p}_N &= \text{SoftMax}(\text{MLP}_N(\mathbf{c}_n)) \\ \mathbf{p}_O &= \alpha \times \mathbf{p}_V + (1 - \alpha) \times \mathbf{p}_N\end{aligned}$$



Quantitative Analysis Results

Model	Pre.	Resolution		Image Classification (Top1 acc.)			
		Pre.	Fine.	IN1K	IN-Real	Places365	iNat18
ViT B/16*	IN1K	224	224	79.00 _{0.00} (77.91)	83.76 _{0.00} (83.57)	-	-
+ LLB (Ours)	-	224	-	79.43_{0.03}	84.25_{0.02}	-	-
ViT B/16*	IN21K	224	224	84.40 _{0.00} (83.97)	88.55 _{0.00} (88.35)	-	-
+ LLB (Ours)	-	224	-	84.80_{0.01}	88.90_{0.02}	-	-
ViT L/16*	IN21K	224	224	85.68 _{0.00} (85.15)	89.05 _{0.00} (88.40)	-	-
+ LLB (Ours)	-	224	-	85.92_{0.02}	89.26_{0.01}	-	-
MAE B/16 [†]	IN1K	224	224	83.63 _{0.00} (83.60)	88.29 _{0.00} (-)	57.84 _{0.07} (57.90)	74.20 _{0.05} (75.40)
+ LLB (Ours)	-	224	-	83.78_{0.02}	88.40_{0.02}	57.90_{0.06}	74.32_{0.06}
MAE L/16 [†]	IN1K	224	224	86.08 _{0.00} (85.90)	89.63 _{0.00} (-)	59.60 _{0.06} (59.40)	80.06 _{0.06} (80.10)
+ LLB (Ours)	-	224	-	86.12_{0.01}	89.65_{0.02}	59.70_{0.05}	80.00_{0.06}
SWAG B/16 [‡]	IB3.6B	224	384	85.28 _{0.00} (85.30)	89.00 _{0.00} (89.10)	58.90 _{0.13} (59.10)	79.78 (79.90 _{0.06})
+ LLB (Ours)	-	224	-	85.35_{0.04}	89.10_{0.09}	59.17_{0.02}	79.86_{0.03}

(red: positive, blue: negative)

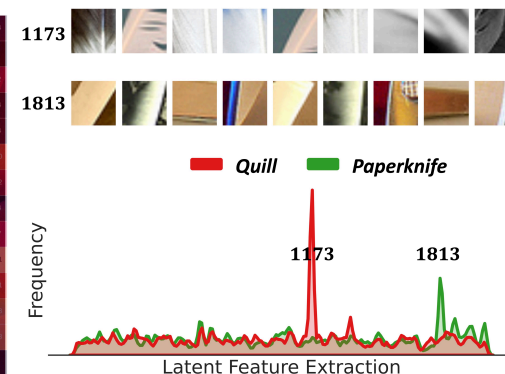
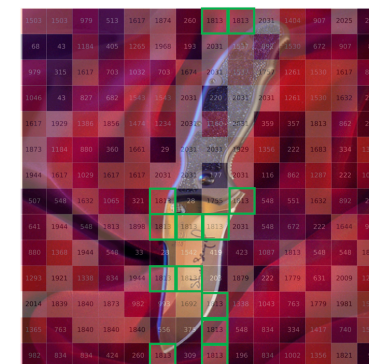
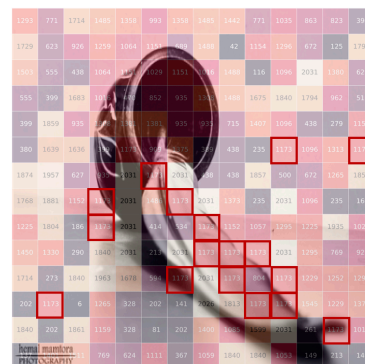
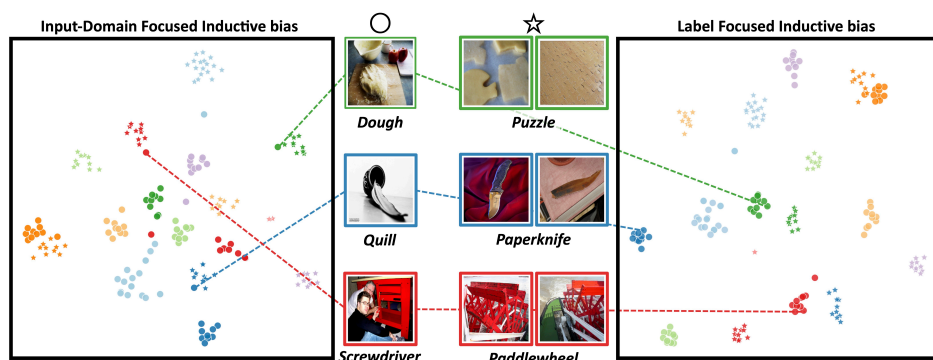
- LLB shows general improvements compared to different ViT networks across diverse data in image classification task

Ablation Study

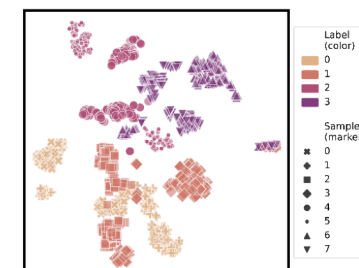
Model	Visual Disc.	Diversity	w/o Pos.	Integration	IN1K (Top1- Acc_{std} %)
LLB (Ours)	✓	✓	✓	✓	84.80_{0.01}
		✓	✓	✓	84.25 _{0.04}
	✓		✓	✓	84.74 _{0.01}
	✓	✓		✓	84.77 _{0.02}
	✓	✓	✓		82.58 _{0.12}
Baseline					84.40 _{0.00}

- Our ablation study show that each configuration is required to obtain the best performance

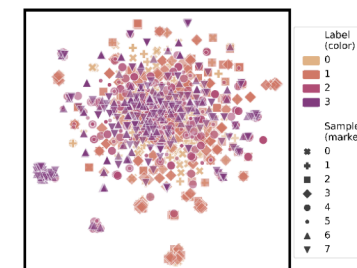
Qualitative Analysis Results



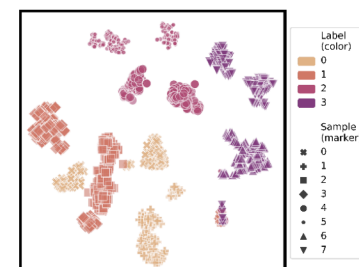
- Our LLB works as an effective identifiers for correct classification
- Our implementation
 - Effetely disconnects input-domain focused inductive bias
 - Learn *label-focused inductive bias* determined solely by categorization of labels



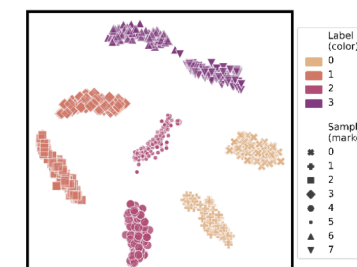
(a) visual feature (internal)



(b) non-visual feature (internal)



(c) visual feature (final)



(d) non-visual feature (final)

Contribution

- We raise the dominance of input-domain focused inductive bias of neural networks that conflicts with UWK
- We proposed training strategy *Label-focused Latent-object Biasing (LLB)*, to obtain UWK and utilize it as label-focused inductive bias
- We verified our method in various image classification benchmarks with quantitative and qualitative analysis

Thank You

For details of our proposal, check out our Paper & GitHub



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