



ICLR 2025

Lightning-Fast Image Inversion and Editing for Text-to-Image Diffusion Models

Dvir Samuel, Barak Meiri, Haggai Maron, Yoad Tewel, Nir Darshan, Shai Avidan,
Gal Chechik, Rami Ben-Ari

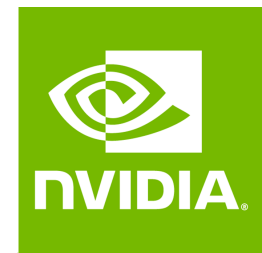
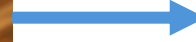


Image Editing from Text



A ~~cat~~ holding up a "Hello world" sign
dog



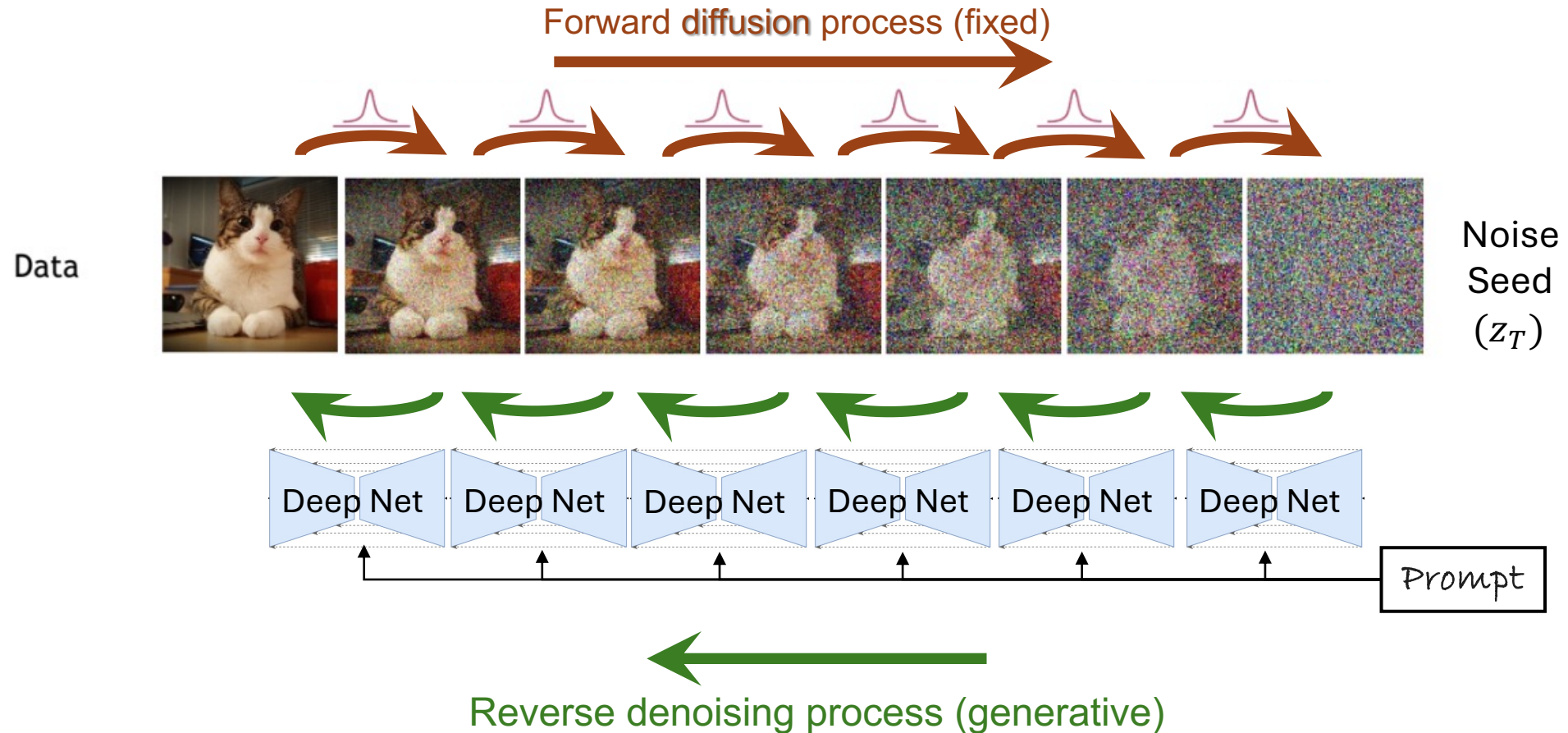
A table with wine, glasses and ~~pizza~~
bread



An oil painting of a woman **with glasses**

Diffusion Models

For text-conditioned image generation



Diffusion Models

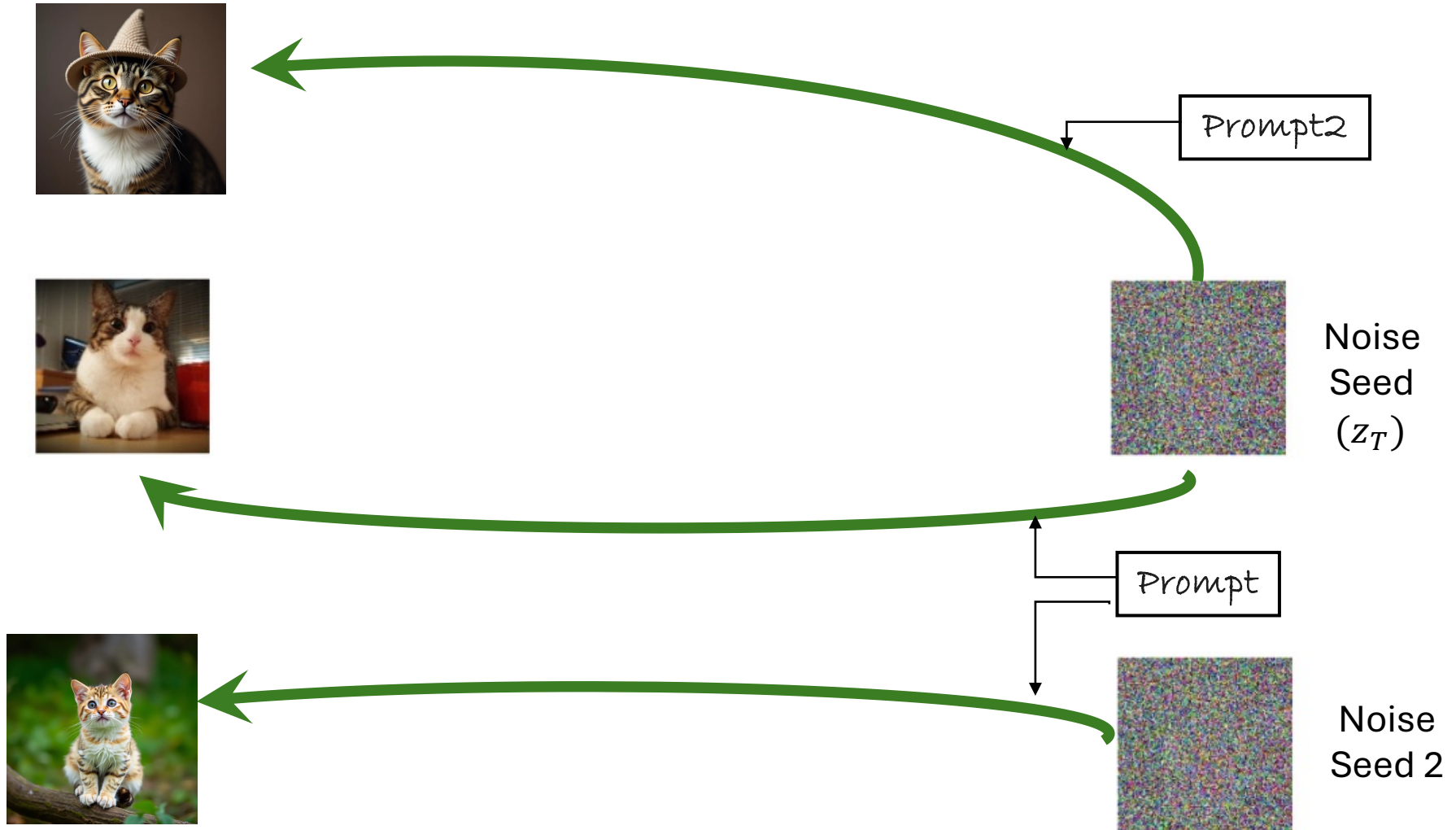
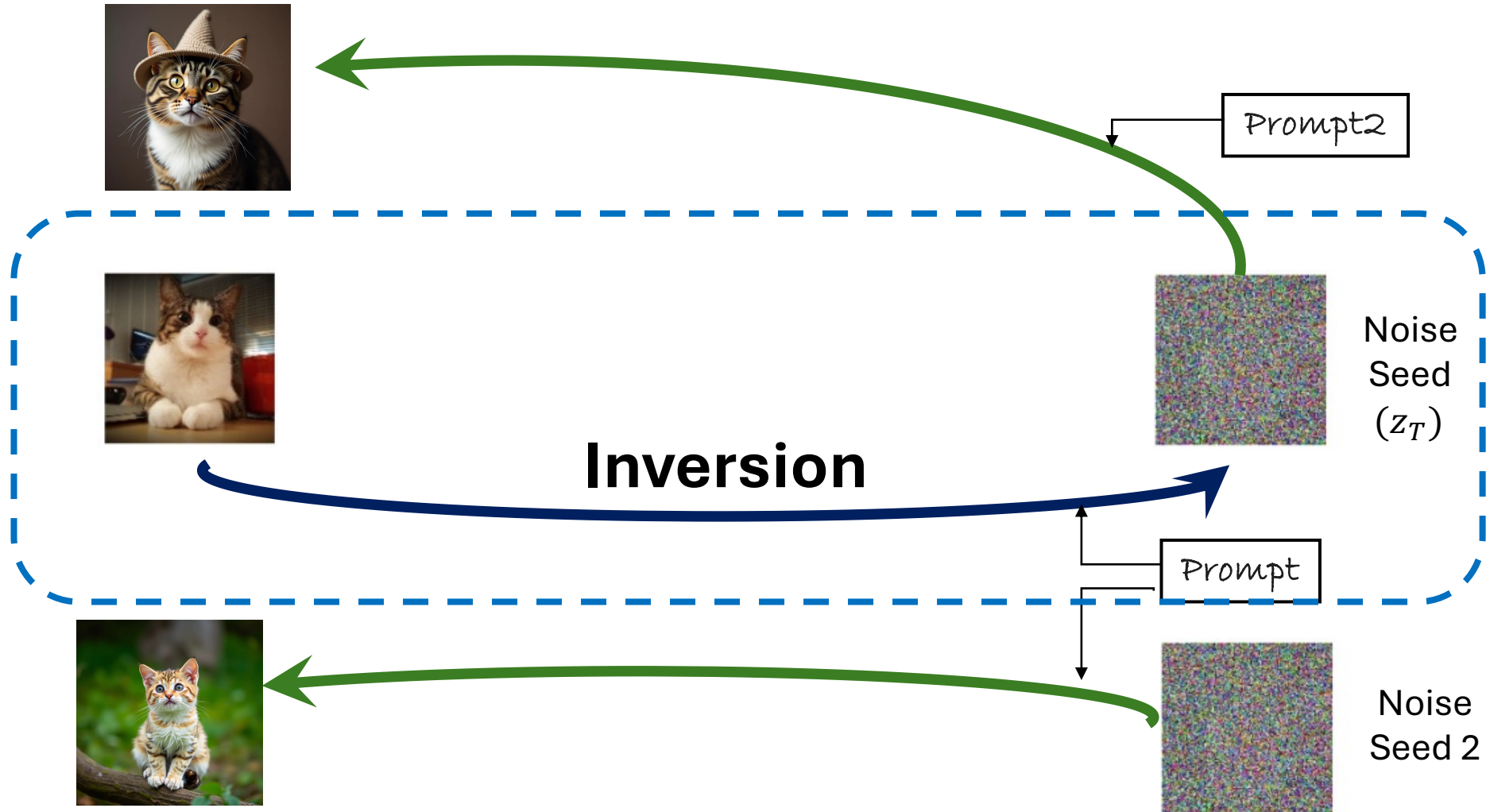


Image Inversion



Current Inversion Methods



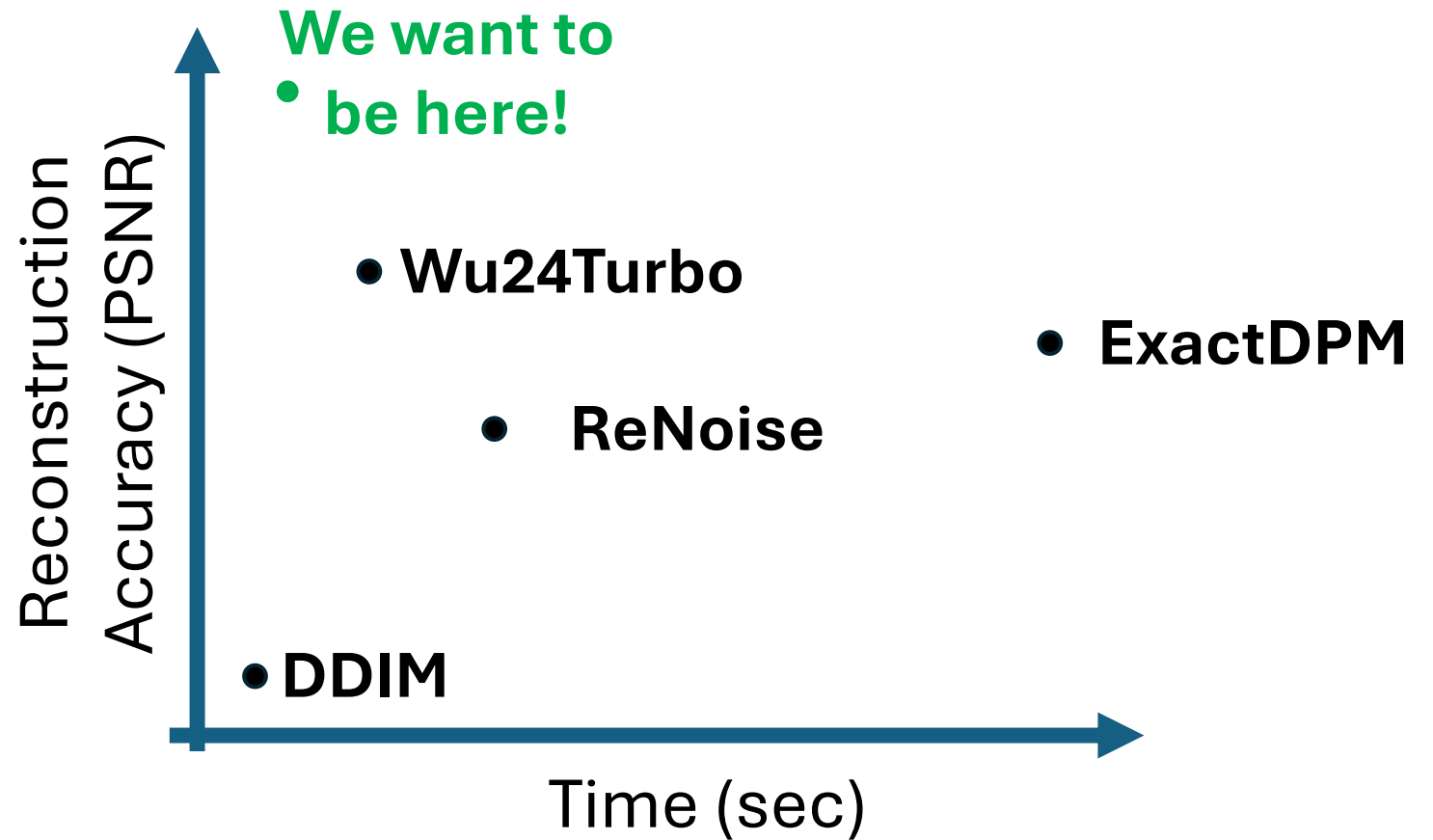
Input Image



Current Inversion Methods



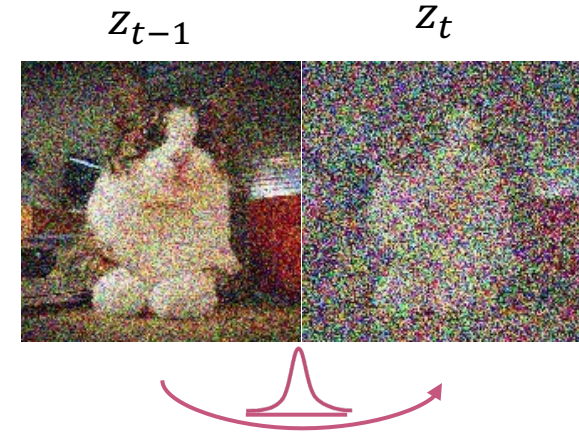
Input Image



Diffusion Models as Markov Chains

The noising process is a markov chain where each step is Gaussian transition:

$$q(z_t|z_{t-1}) = \mathcal{N}(z_t, \sqrt{\alpha_t}z_{t-1}, (1 - \alpha_t)I)$$



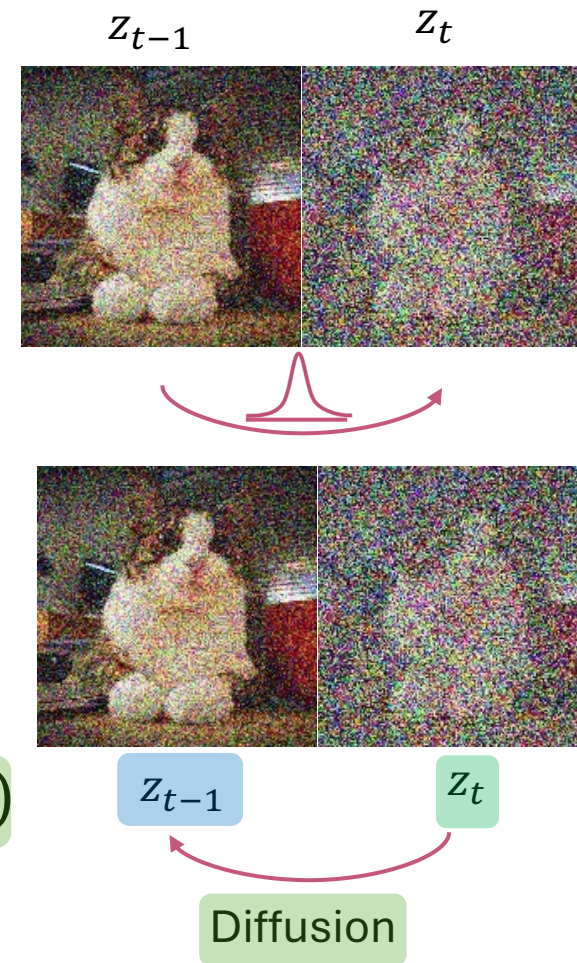
DDIM

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The denosing process (DDIM):

$$z_{t-1} = \sqrt{\frac{\alpha_{t-1}}{\alpha_t}} z_t - \sqrt{\alpha_{t-1}} \cdot \Delta\psi(\alpha_t) \cdot \epsilon_{\theta}(z_t, t, p)$$



DDIM Inversion

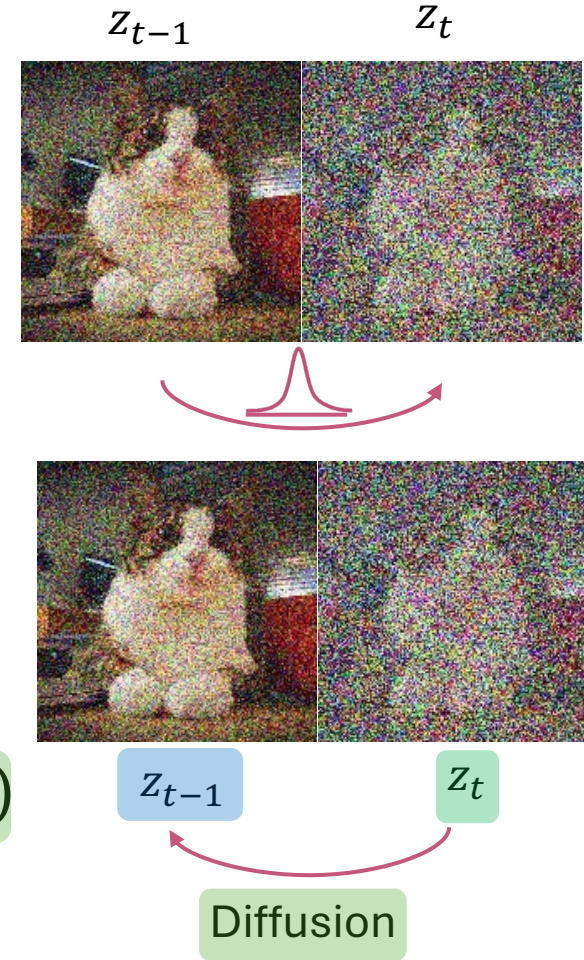
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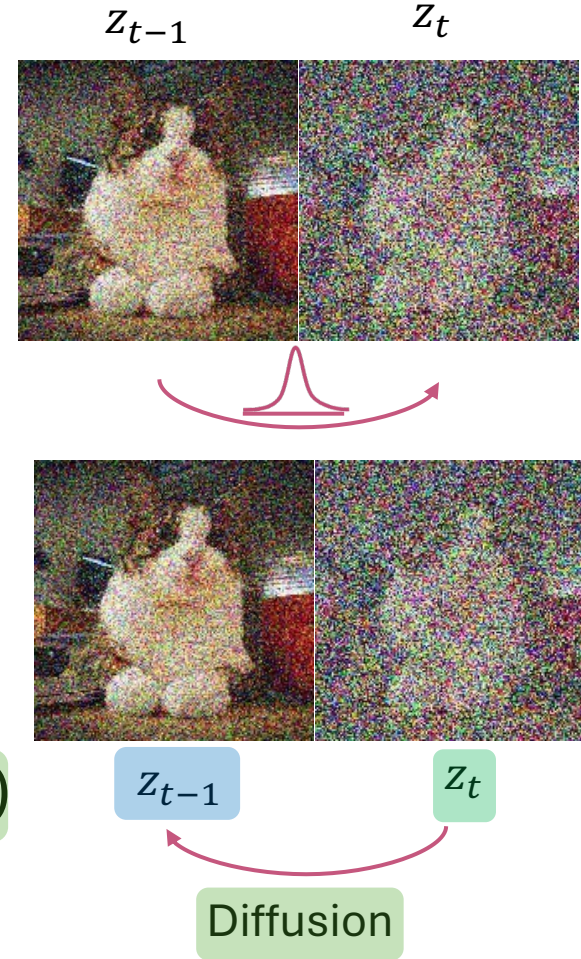
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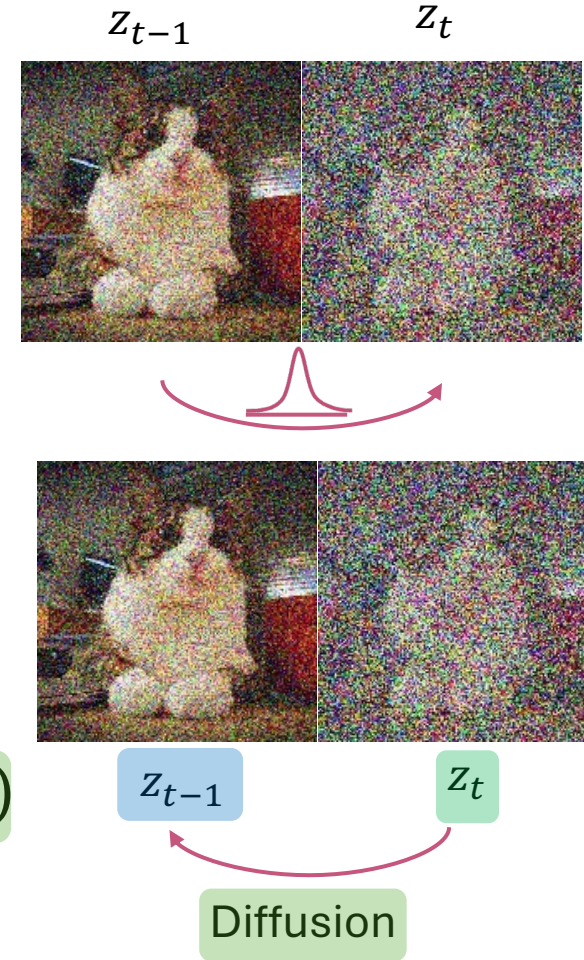
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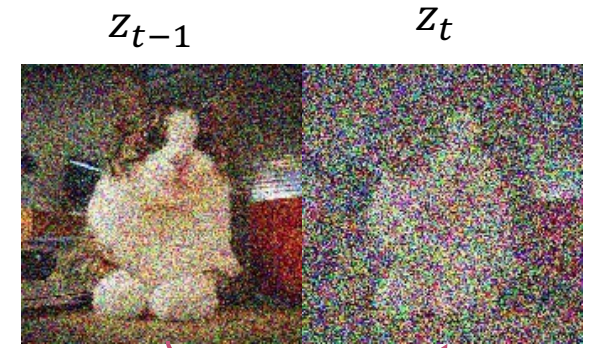
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Recent Inversion Methods



Frame inversion is a root-finding problem and solve $r(z_t) = z_t - f(z_t)$ using:

$$z_t = \underbrace{\sqrt{\frac{\alpha_t}{\alpha_{t-1}}} z_{t-1} - \sqrt{\alpha_{t-1}} \cdot \Delta\psi(\alpha_t) \cdot \epsilon_\theta(z_t, t, p)}_{f(z_t)}$$

Solve it using:

- Fixed-point iteration [Pan et al., ICCV23](#) and [Garibi et al., ECCV24](#)
- Gradient Descent [Hong et al., CVPR24](#)

Our key ideas

1. Use an Efficient Newton-Raphson Iteration

Apply Newton Raphson on the norm of r : $\hat{r}(z_t) = ||z_t - f(z_t)||$. This reduces the Jacobian matrix into a vector, making it easy and fast for computation.

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2. Guide Newton-Raphson to in-distribution solutions

We add a prior over the value of z_t :

$$\mathcal{F}(z_t) := ||z_t - f(z_t)|| - \lambda \log(q(z_t | z_{t-1}))$$

λ is a weighting parameter for the guidance term.

Known by
model definition

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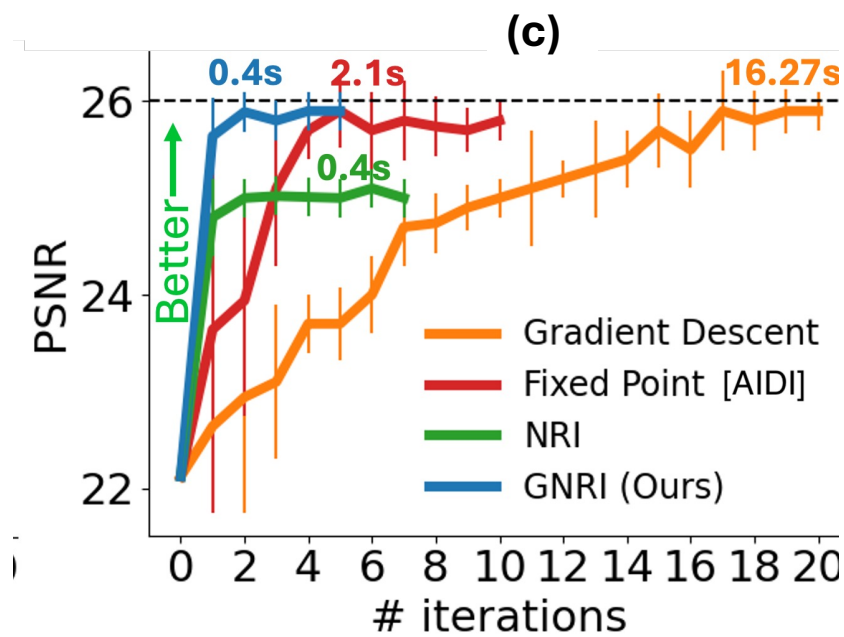
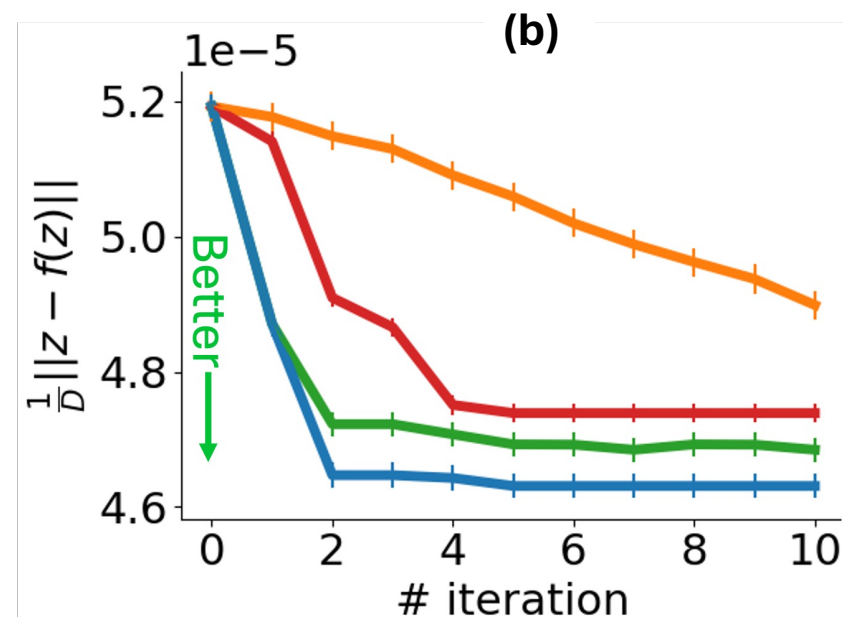
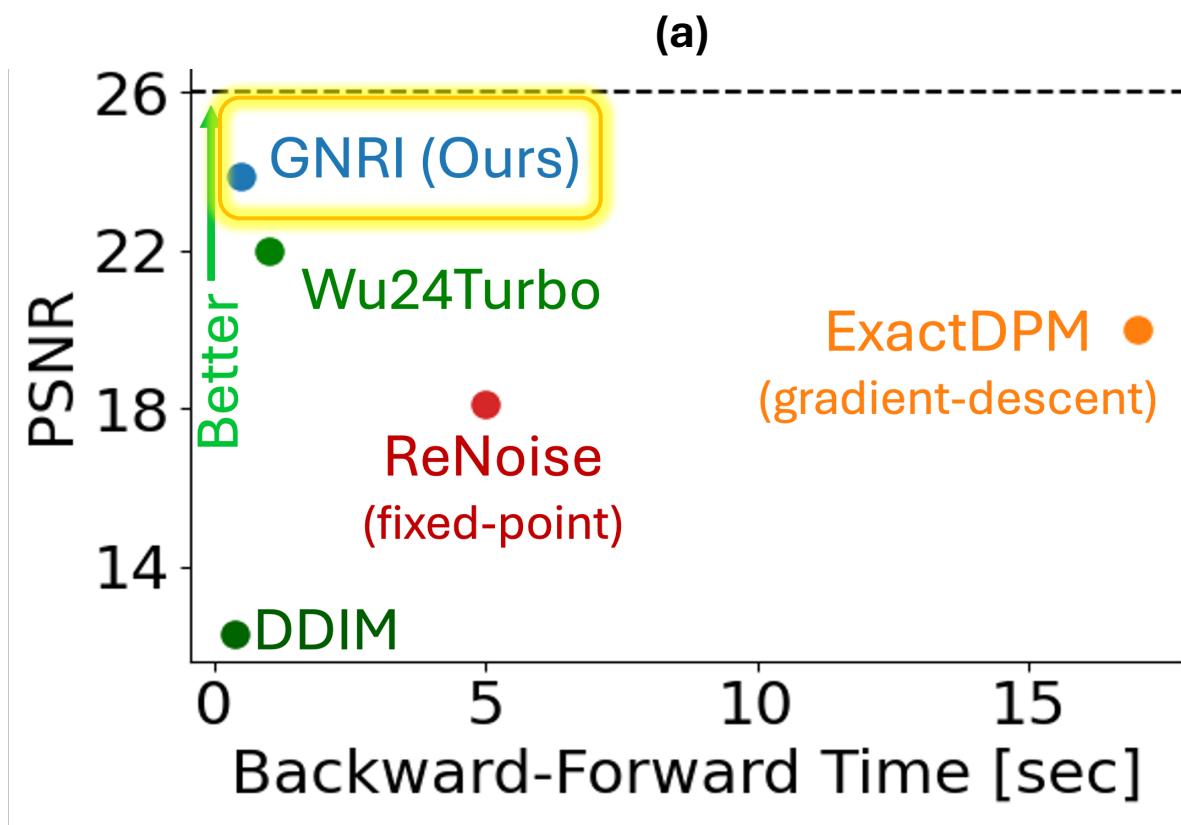
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————→ **Guided Newton Raphson Inversion**

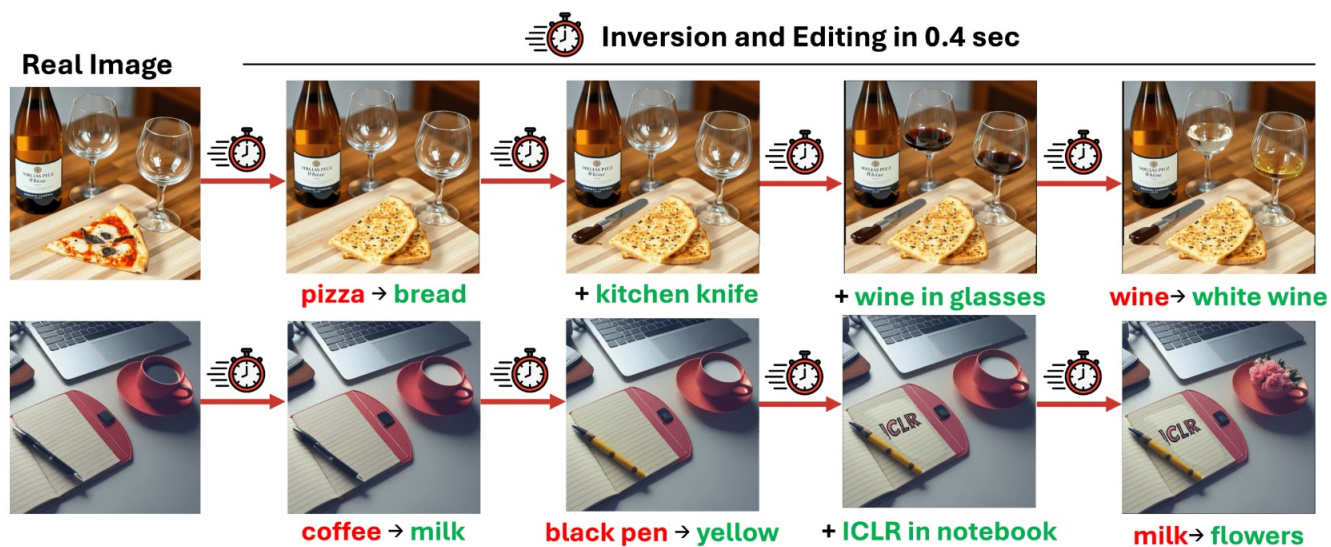
Reconstruction Quality

GNRI converges within 1-2 iterations!



Real-time Image Editing

GNRI enables interactive editing!!



Prompt: A laptop, a cup of coffee, a black pen and a smartphone

Run Interact





Project Page



Demo

Thank you!