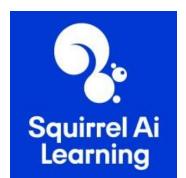
# MME-RealWorld: Could Your Multimodal LLM Challenge High-Resolution Real-World Scenarios that are Difficult for Humans?

Yi-Fan Zhang, Huanyu Zhang, Haochen Tian, Chaoyou Fu, Shuangqing Zhang, Junfei Wu, Feng Li, Kun Wang, Qingsong Wen, Zhang Zhang, Liang Wang, Rong Jin, Tieniu Tan

TL;DR: Existing benchmarks for MLLMs face limitations such as small data scale, model-based annotations, and insufficient task difficulty, hindering their ability to measure real-world challenges. To address these issues, we introduce MME-RealWorld, a large-scale, manually annotated benchmark with high-resolution images and complex real-world scenarios, revealing that even advanced models like GPT-40 and Gemini 1.5 Pro struggle to achieve 60% accuracy, highlighting the urgent need for improved perception and understanding capabilities.







### **Main Motivations**

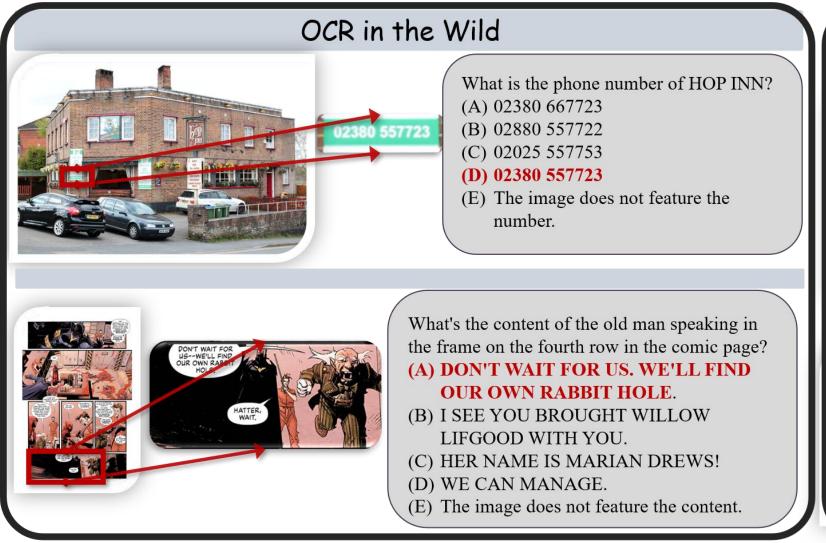
- > Data Scale Many existing benchmarks contain fewer than 10K QA pairs;
- > Annotation Quality Some benchmarks, while larger in scale, rely on annotations generated by LLMs or MLLMs, whose annotations are inherently limited by the performance of the used models.
- > Task Difficulty The top performance of some benchmarks has reached the accuracy of 80%-90%, and the performance margin between advanced MLLMs is narrow.

## **MME-RealWorld**

- > Data Scale We have manually annotated 29, 429 QA pairs focused on real-world scenarios.
- > Data Quality
- > Resolution: The images have an average resolution of 2, 000×1, 500, containing rich image details.
- > Annotation: All annotations are manually completed.
- > Task Difficulty and Real-World Utility Even the most advanced models have not surpassed 60% accuracy.
- > MME-RealWorld-CN We collect 5, 917 QA pairs focusing on Chinese Scenarios, annotated by Chinese

volunteers.	
Object Property  Intention Prediction  Multi-Class Counting  Quicentation Percenting  Acadestrian Counting  Acadestrian Counting  Acadestrian Counting  Acadestrian Counting  Acadestrian Counting  Acadestrian Counting	Contact Inderstanding  Characters Understanding  Characters Understanding  Characters Understanding  Characters Understanding  Characters Understanding
Vehicle Location  Vehicle Existence  Vehicle Counting  Vehicle Intention	Characters Under Counting Characters Under Counting Characters Under Counting Object Counting Spatial Relationship Spatial Recognition Color Recognition Diagram Perception
Pedestrian Intention  Ego Intention  Signal Attention  Signal Attention  Relationship (E2P)  Relationship (C2O)	Table Perception  Calculation (Table)  Comparis:  Comparis:
Multi-Pedestrian Motion  Multi-Pedestrian Motion  Multi-Pedestrian Motion	3 6 8 30 80

Eng		CN	
Model	Acc	Model	Acc
QwenVL-2	56.5		55.5
InternVL-2	53.5	QwenVL-2	55.5
Claude 3.5 Sonnet	51.6	InternVL- Chat-V1-5	47.9
InternLM-2.5	50.0	Claude 3.5 Sonnet	47.0
InternVL-Chat-V1-5	49.4	SliME-8B	45.8
Mini-Gemini-34B-HD	45.9	YI-VL-34B	42.0
MiniCPM-V 2.5	45.6	CogVLM2	39.8
GPT-4o	45.2	SliME-13B	38.9
CogVLM2	44.6	GPT-40	38.8
Cambrian-34B	44.1	Mini-Gemini-34B-HD	38.5
Cambrian-8B	42.7	Monkey	37.2
SliME-8B	39.6	LLaVA-Next-8B	36.5
Gemini-1.5-pro	38.2	Cambrian-34B	35.7
GPT-40-mini	36.4	Mini-Gemini-7B-HD	34.9
Monkey	35.3	InternLM-2.5	33.9
mPLUG-DocOwl	32.7	Cambrian-8B	33.6
DeepSeek-VL	32.4	LLaVA-Next-72B	30.6
SliME-13B	31.7	mPLUG-DocOwl	28.3
YI-VL-34B	31.0	Gemini-1.5-pro	28.1
Mini-Gemini-7B-HD	30.3	MiniCPM-V 2.5	27.9
LLaVA-Next-8B	30.2	DeepSeek-VL	27.6
LLaVA-Next-72B	28.7	TextMonkey	26.4
LLaVA1.5-13B	28.0	GPT-40-mini	25.9
ShareGPT4V-13B	27.8	ShareGPT4V-13B	25.9



Remote Sensing in the middle area of the picture? (C) Black. (D) Green. (E) The image does not feature the How many aircraft are there in the



(A) 26(B) 80 (C) 133 (D) 92 (E) The image does not feature the



What will the truck do in the (A) Stopping (B) Keep moving (C) Turn left (D) Turn right (E) The image does not feature the

# Autonomous Driving

What is the traffic light on the right? (A) yellow

suv in the middle?

(A) Turn right.

(B) Turn left.

(C) Stationary.

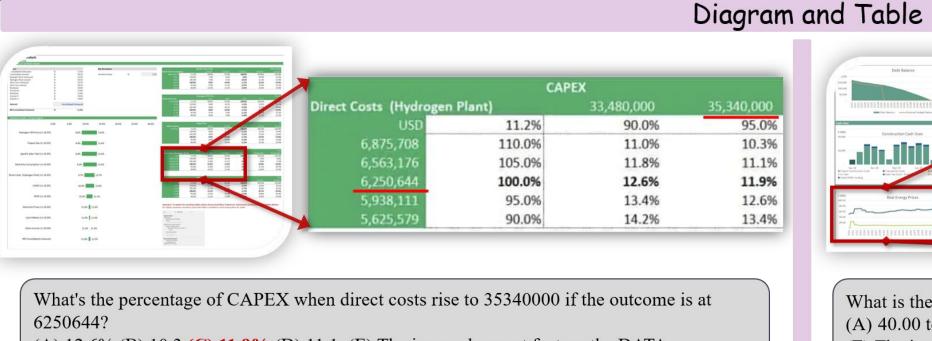
(D) Keep going straight.

(E) The image does not feature the object

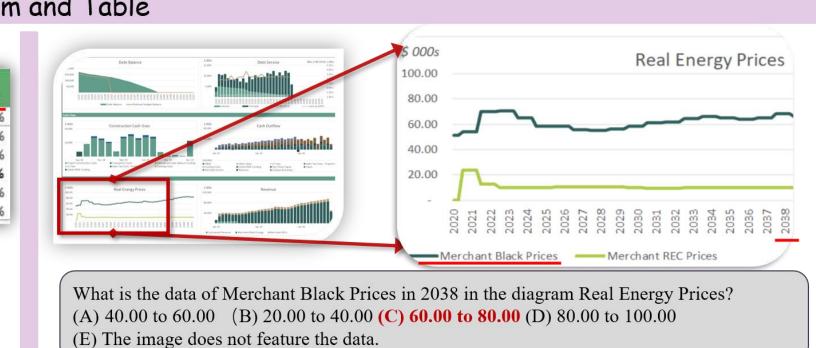
(B) red (C) green

(D) changing/off

(E) The image does not feature the traffic light



(A) 12.6% (B) 10.3 (C) 11.9% (D) 11.1 (E) The image does not feature the DATA.



### **Key Findings:**

- 1) Existing Models Still Lacking in Image Detail Perception.
- 2) Processing high-resolution images reveals significant disparities in computation efficiency across different models.
  - Error analysis reveals that larger models tend to select safer options, while smaller models favor the first choice.
- 4) Some open-source models exhibit limited instruction-following capabilities

### (a) Real-World Tasks

### (b) Leaderboard