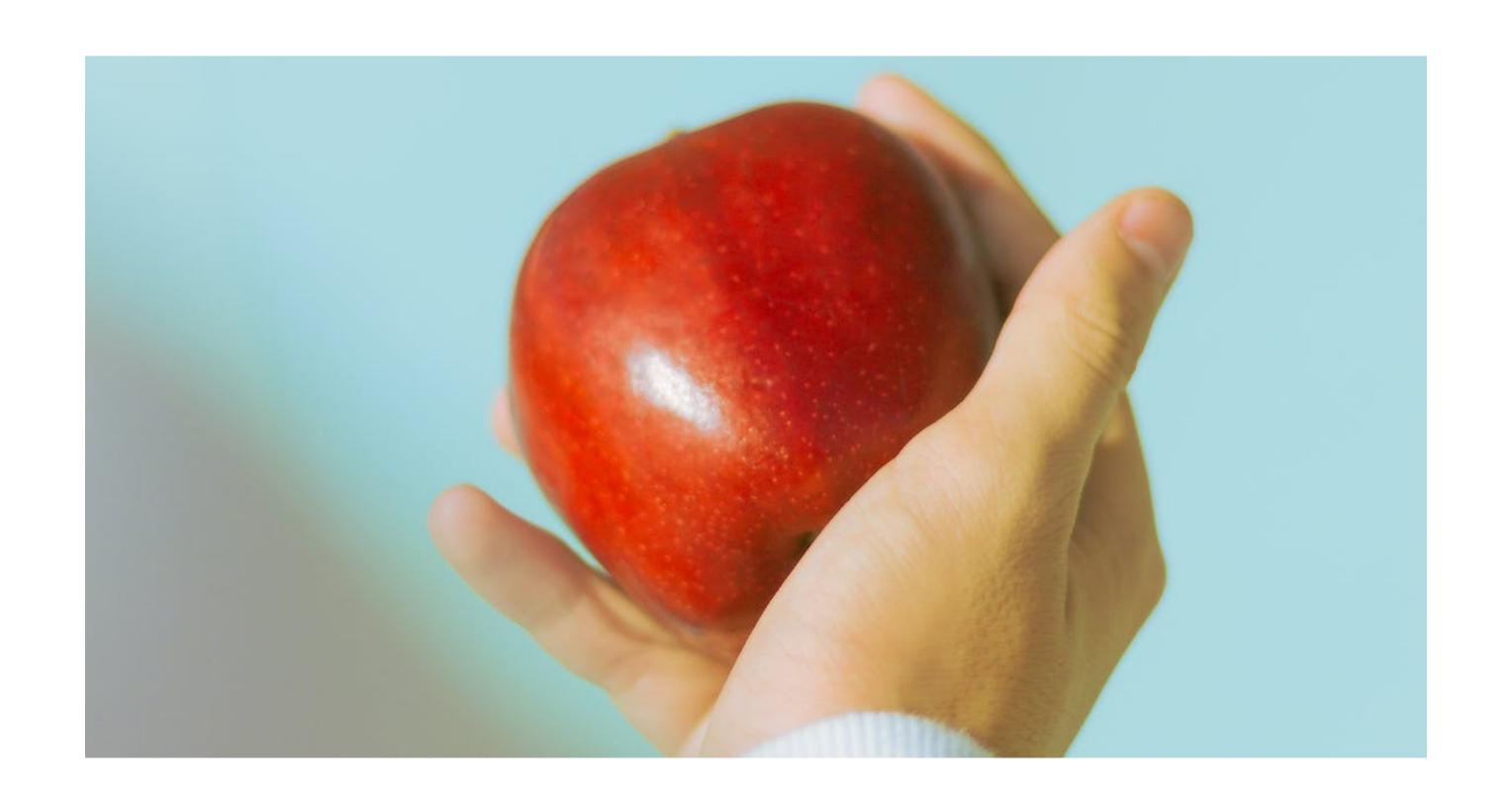
Vision CNNs trained to estimate spatial latents learned similar ventral-stream-aligned representations



Vision is "to know what is where by looking"

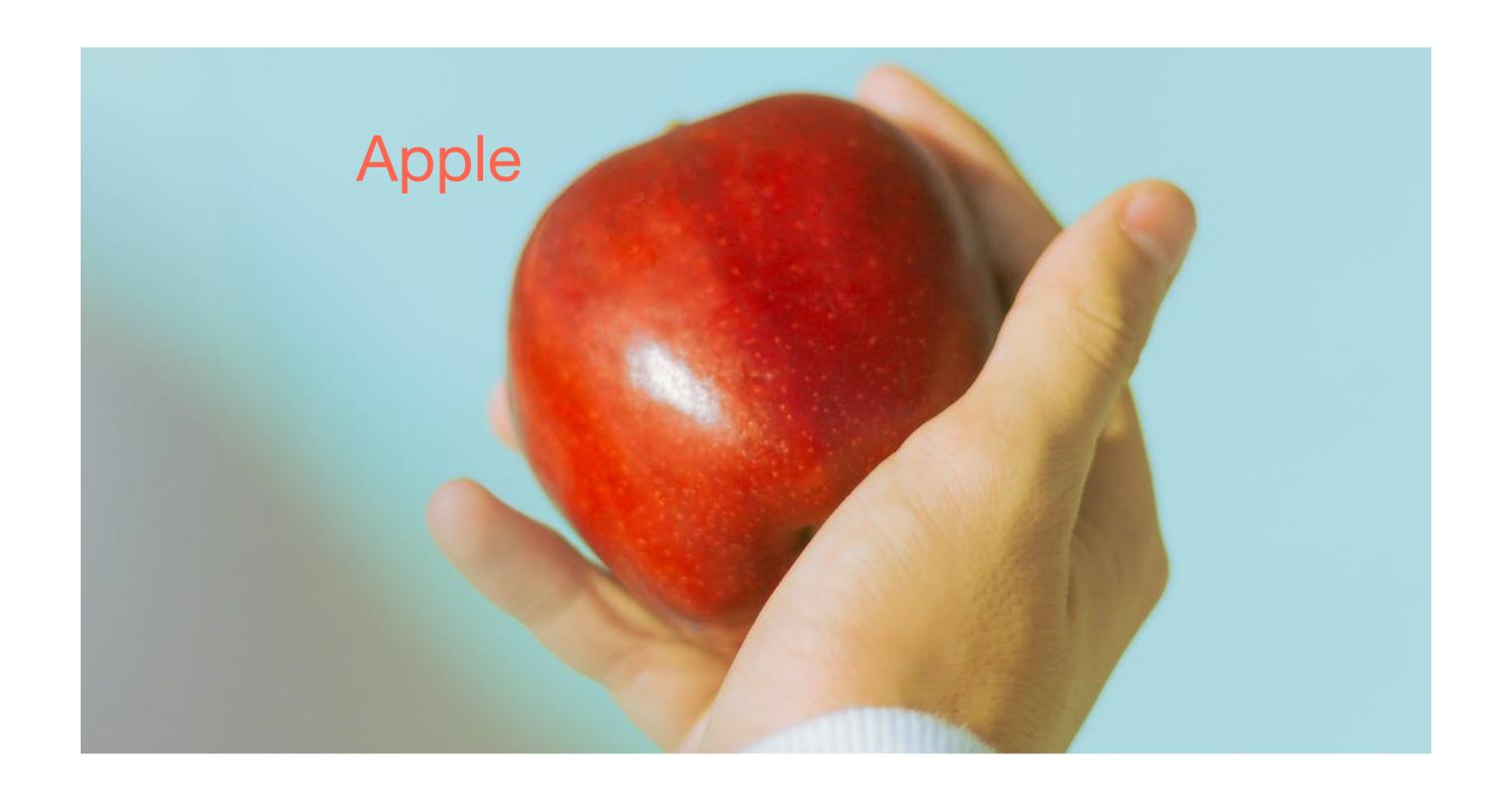
David Marr



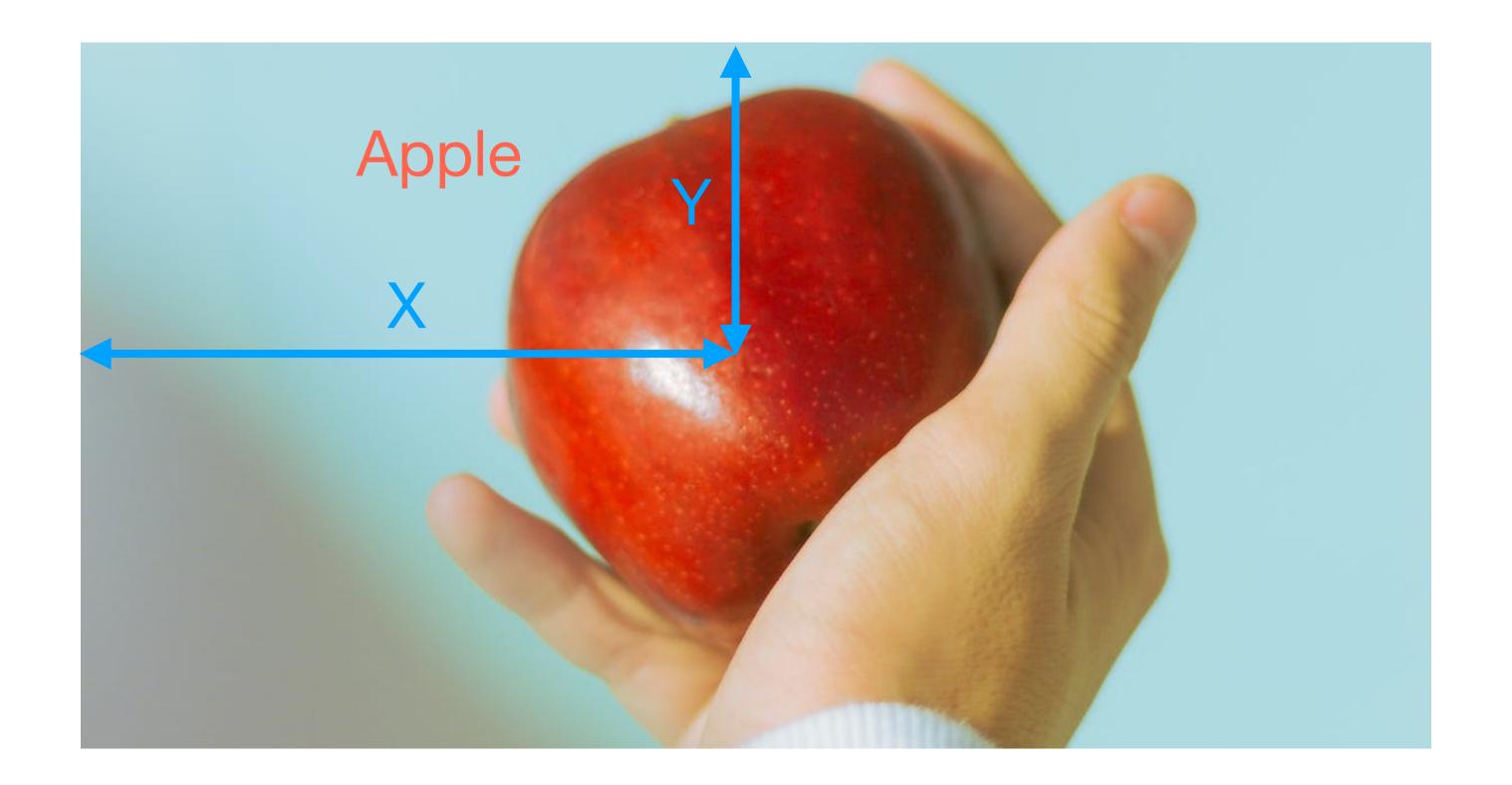




When we see an object, we don't just see an abstract category.

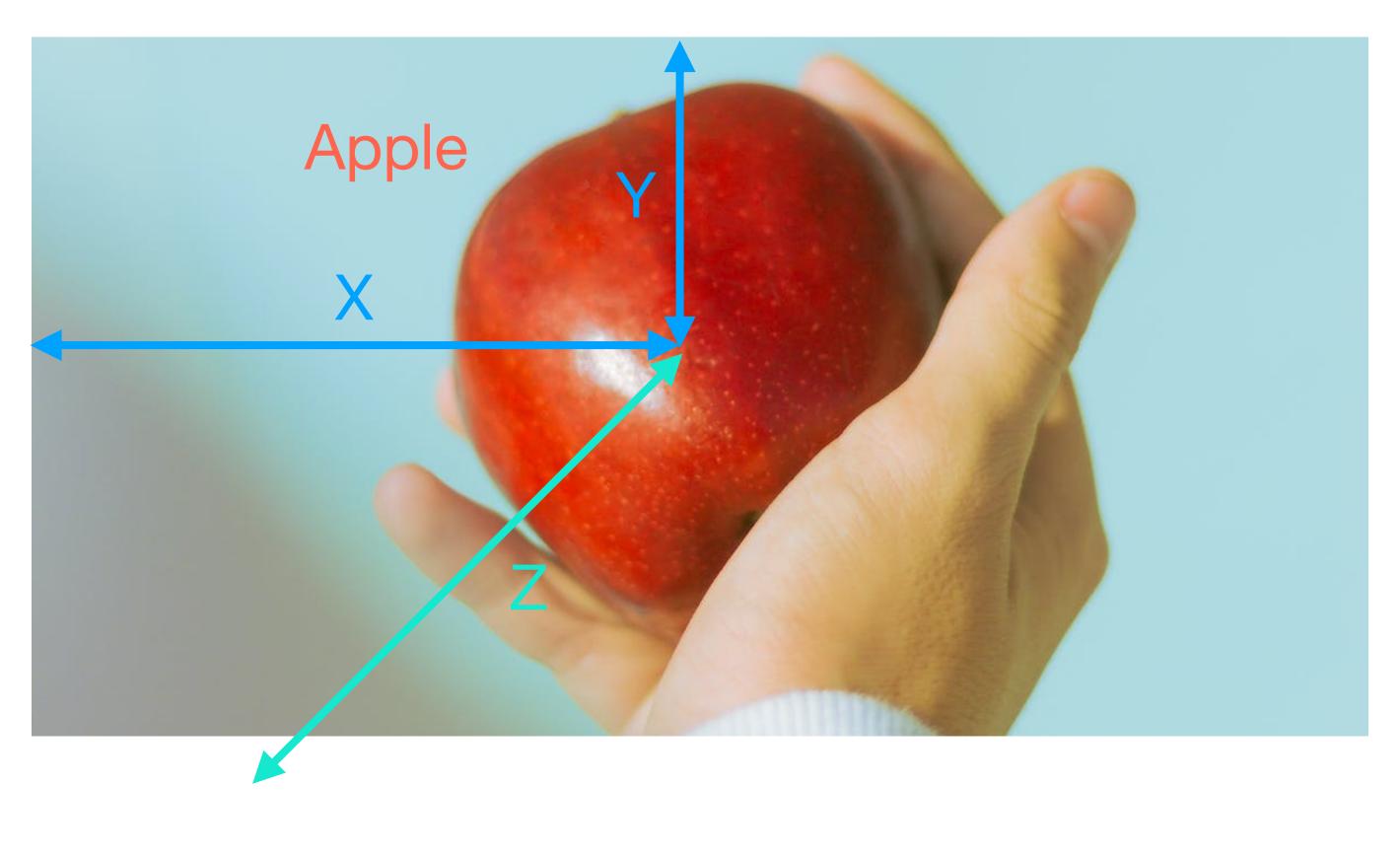


• When we see an object, we don't just see an abstract category.



Location

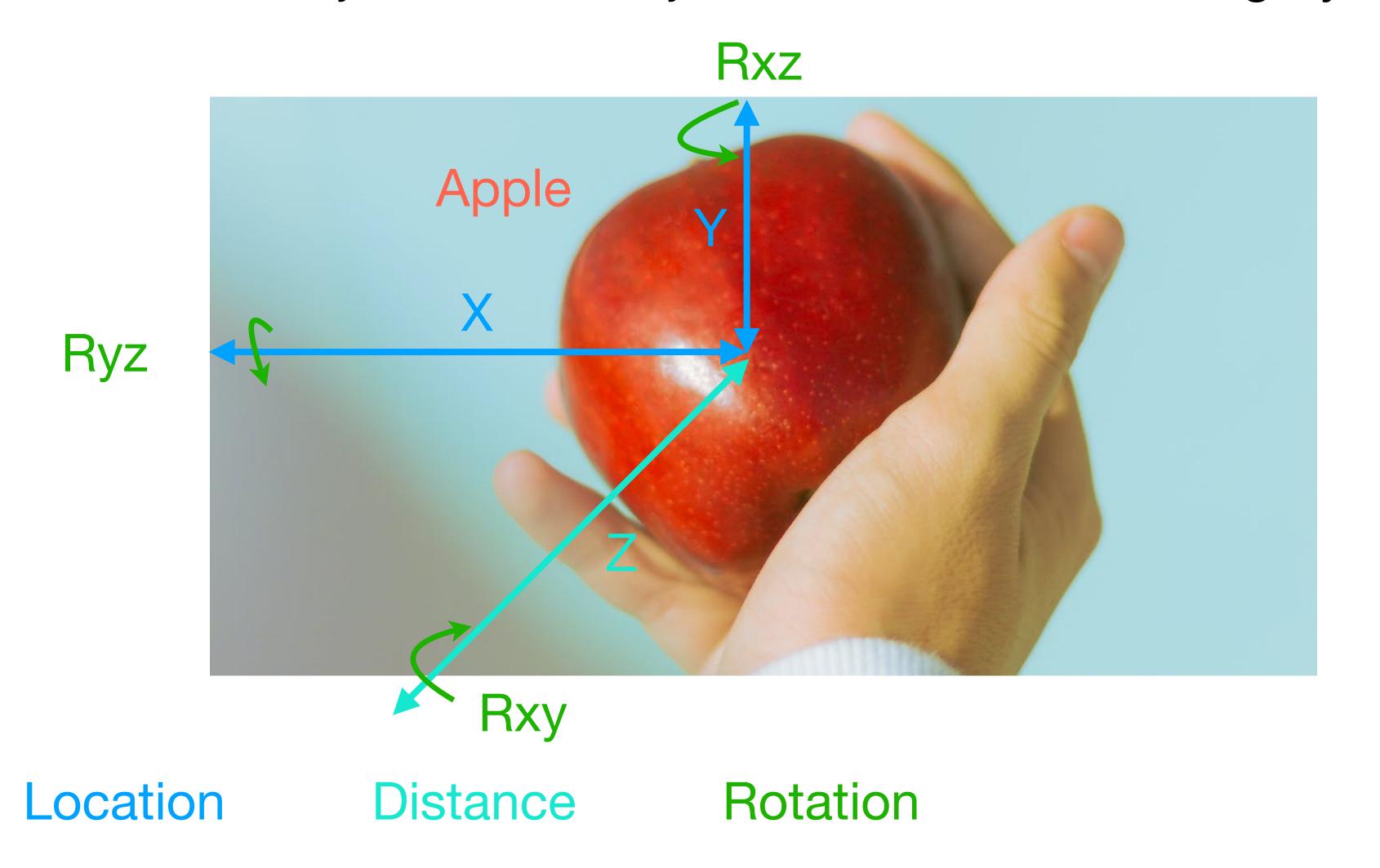
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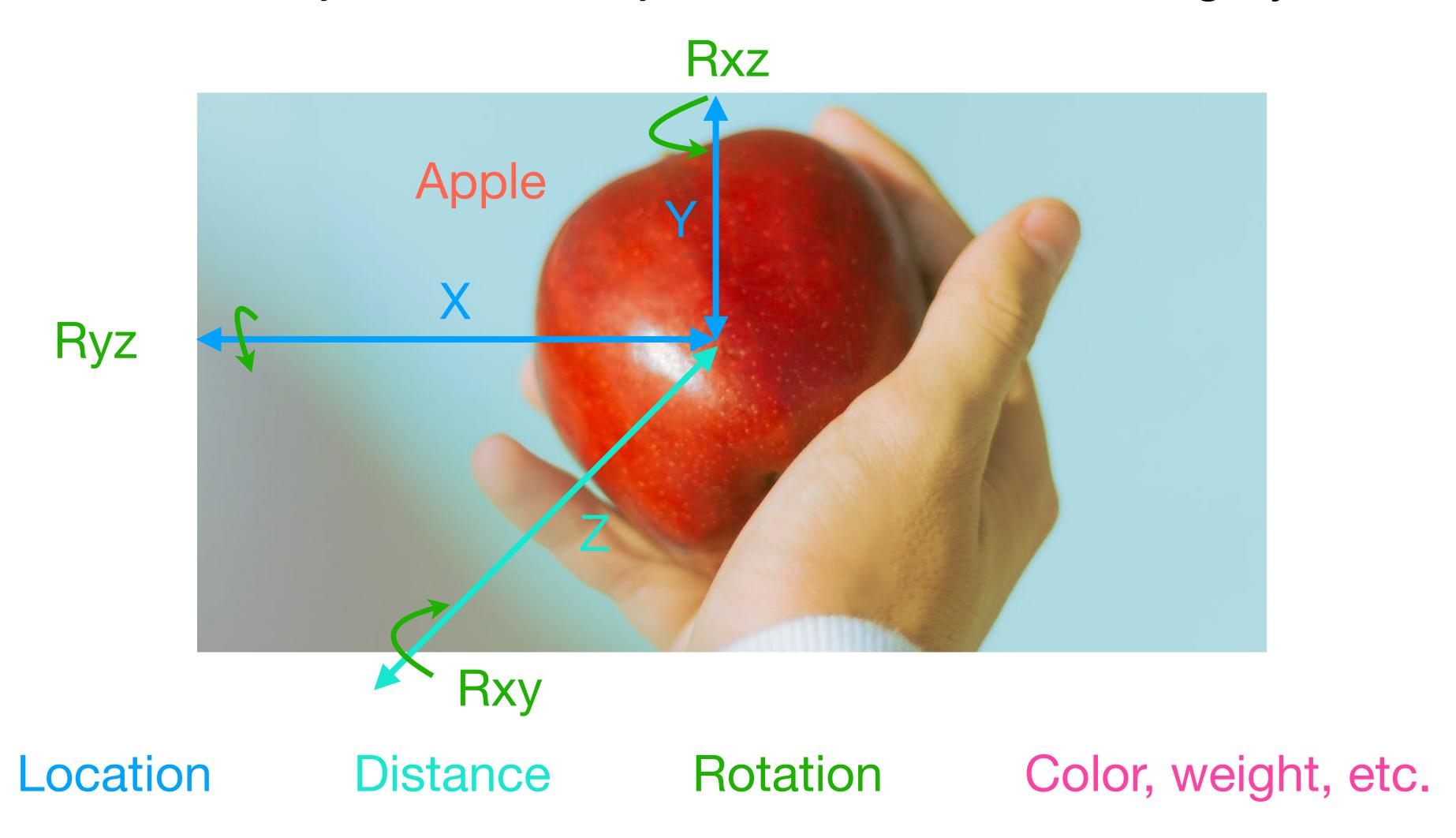
Location

Distance

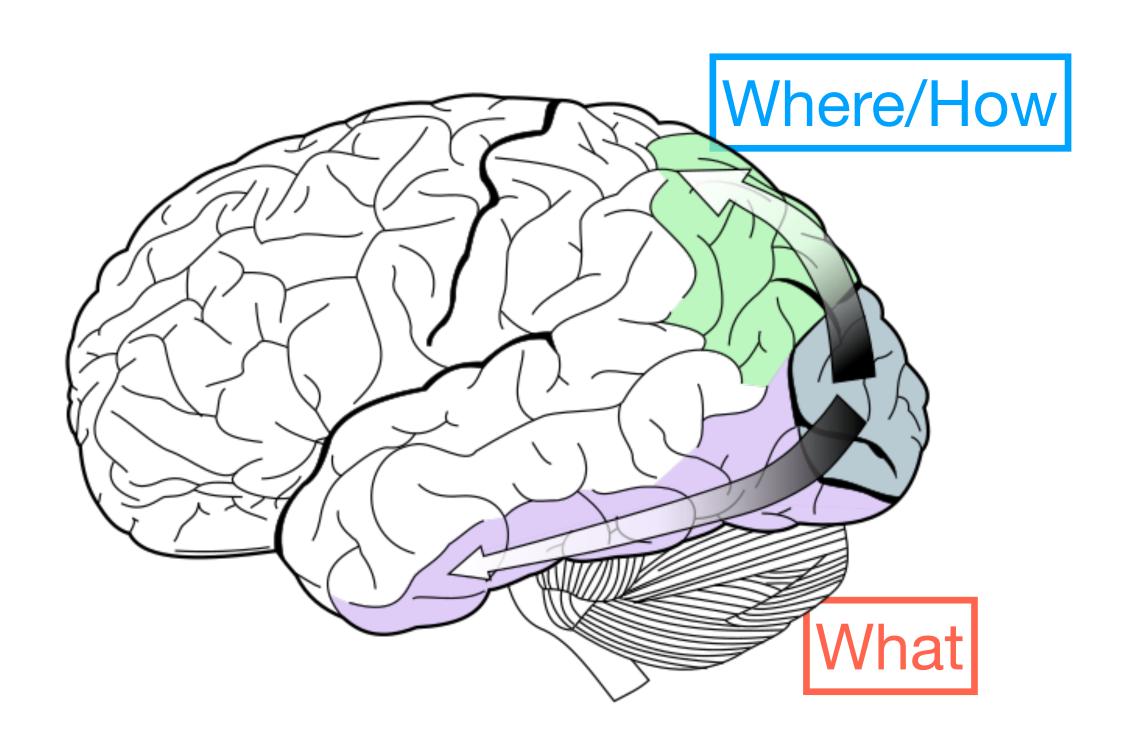
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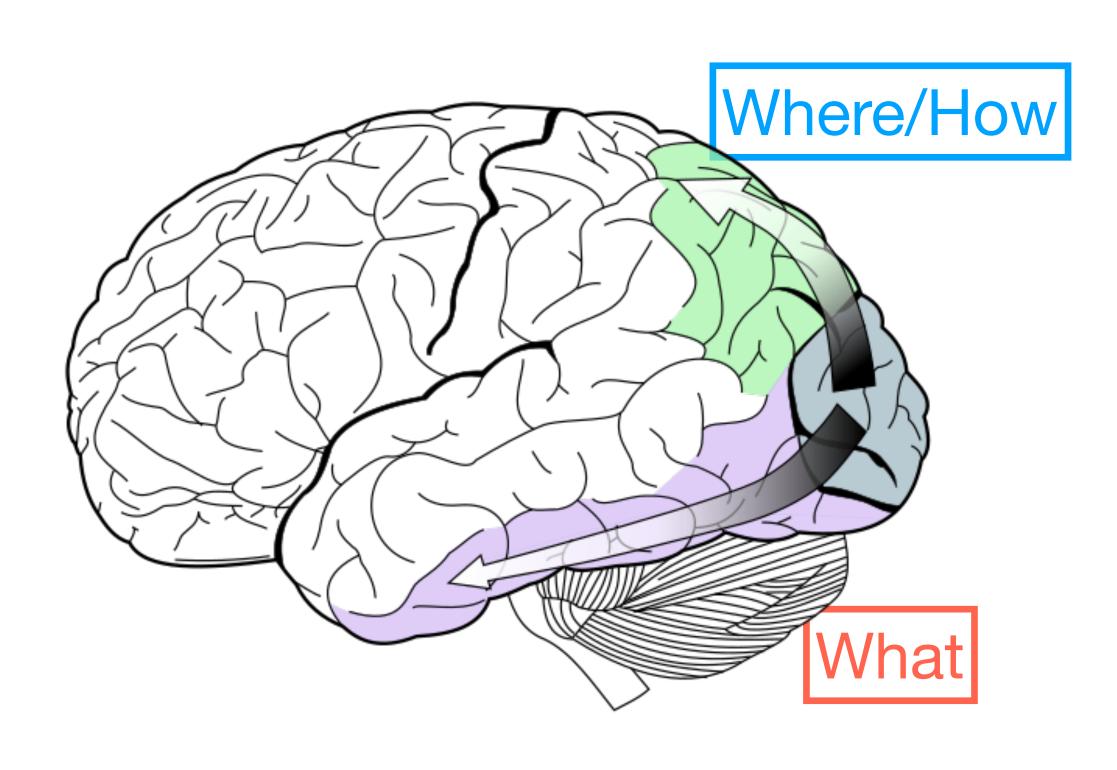
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Ventral stream is thought to perform the "what" function in vision

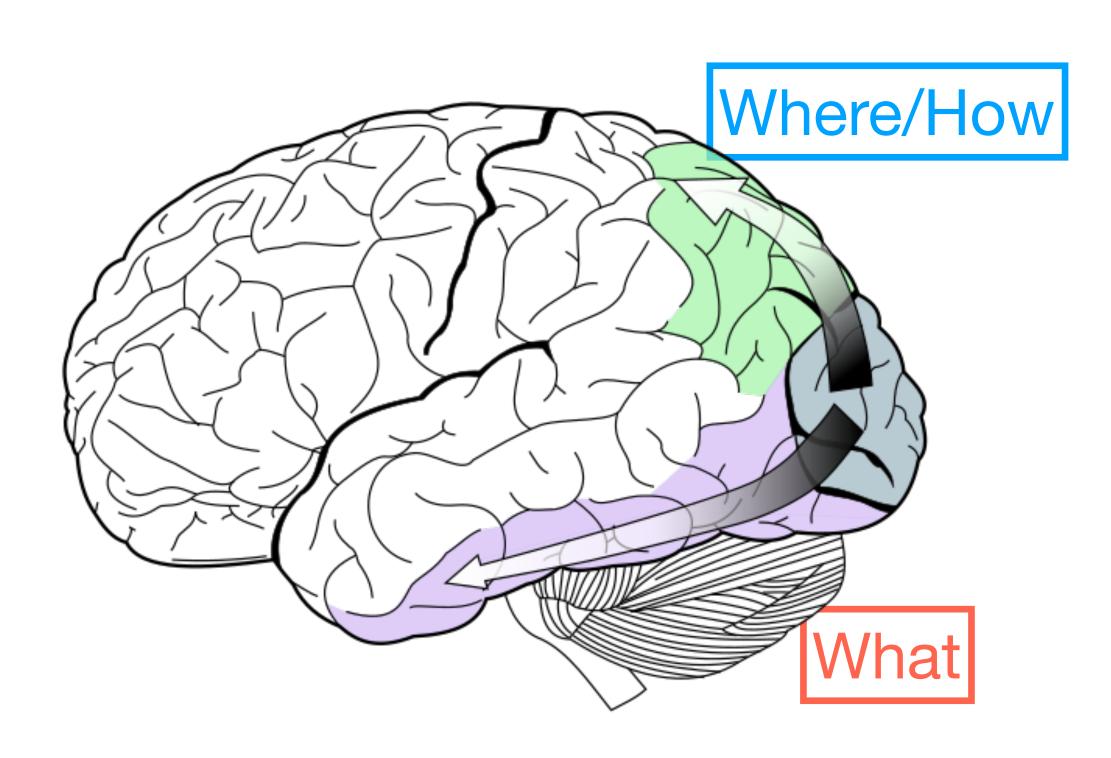


Ventral stream is thought to perform the "what" function in vision

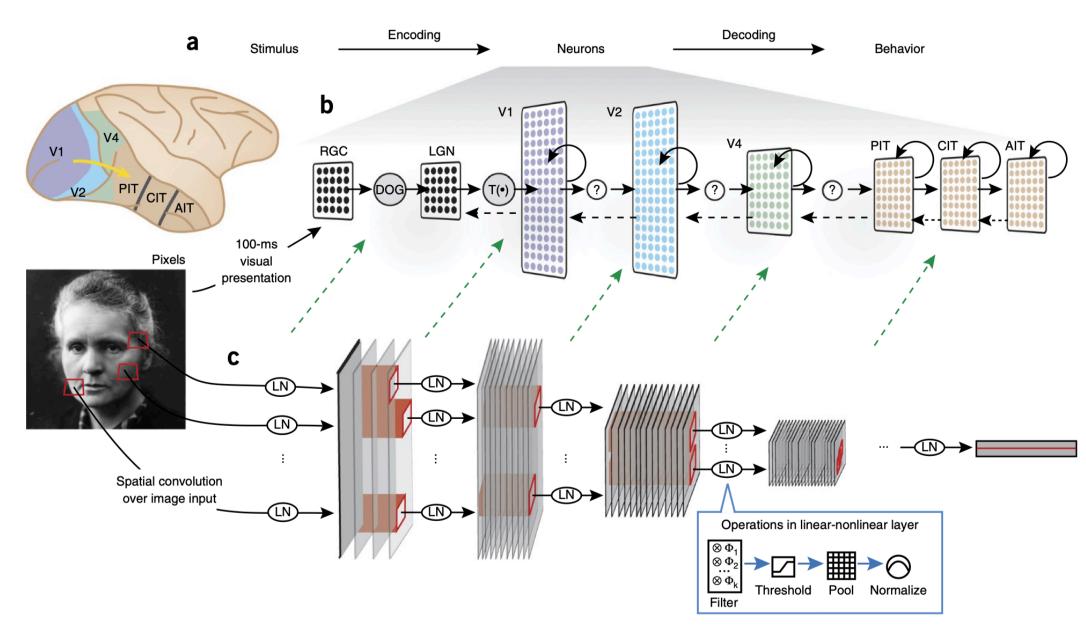


• The ventral stream is thought to perform the "What" function in vision, while the dorsal stream performs spatial processing. Mishkin, Ungerleider (1982)

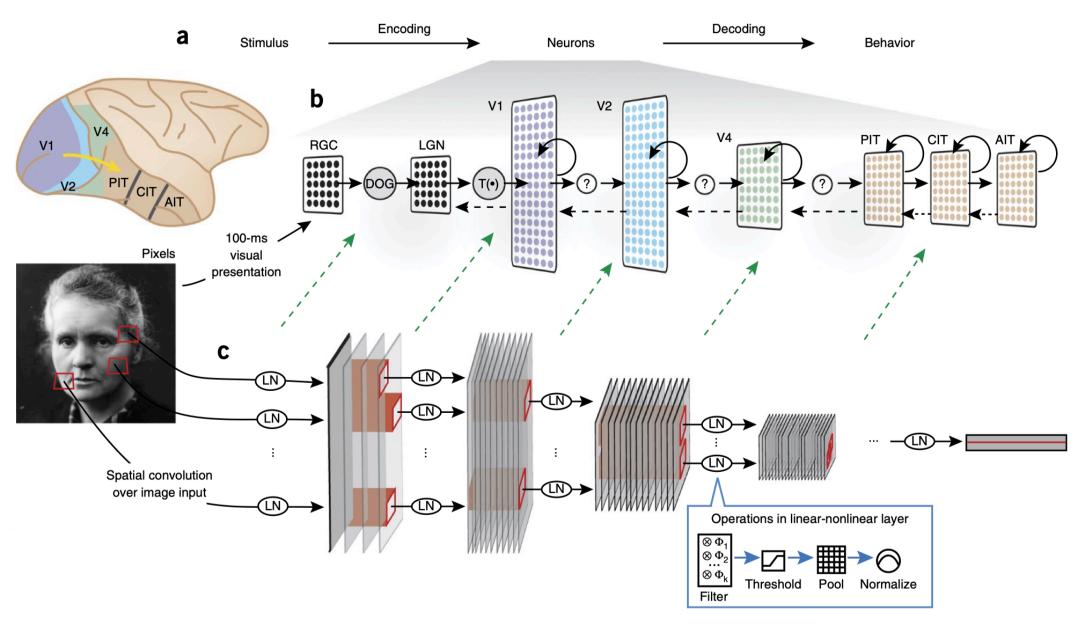
Ventral stream is thought to perform the "what" function in vision



- The ventral stream is thought to perform the "What" function in vision, while the dorsal stream performs spatial processing. Mishkin, Ungerleider (1982)
- Though, what exactly does the "what" function mean is debated. Goodale MA, Milner AD (1992)

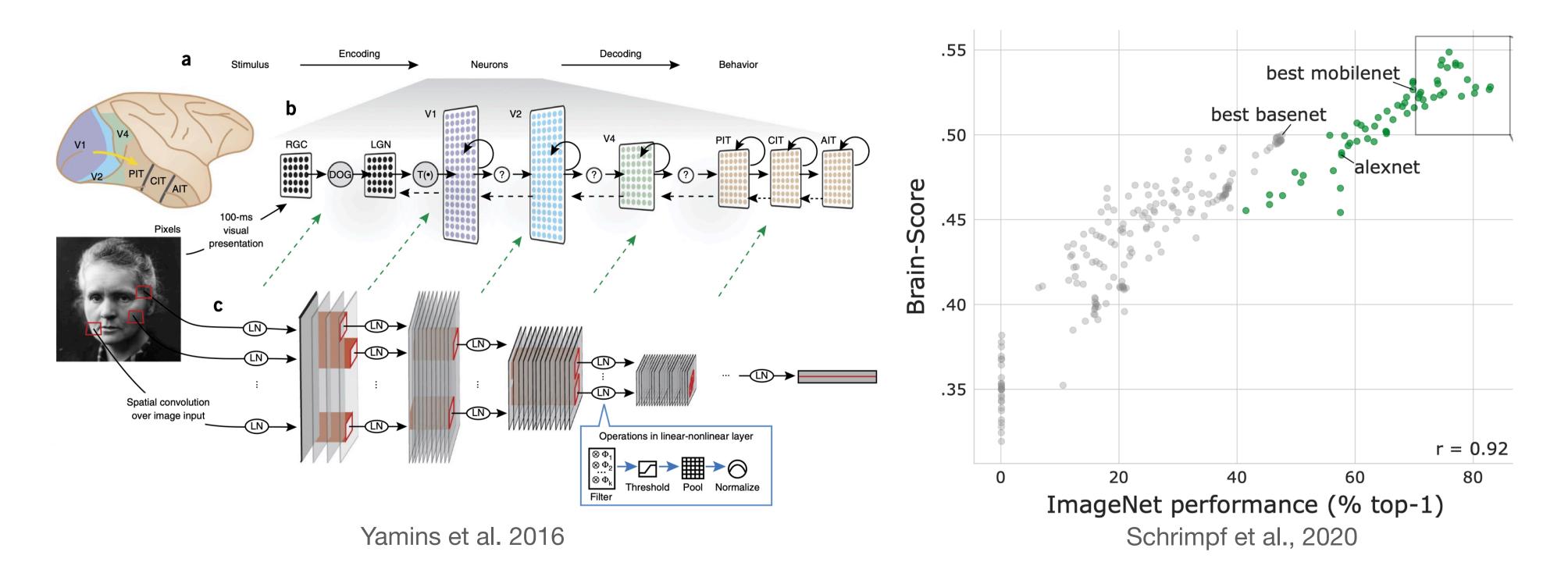


Yamins et al. 2016

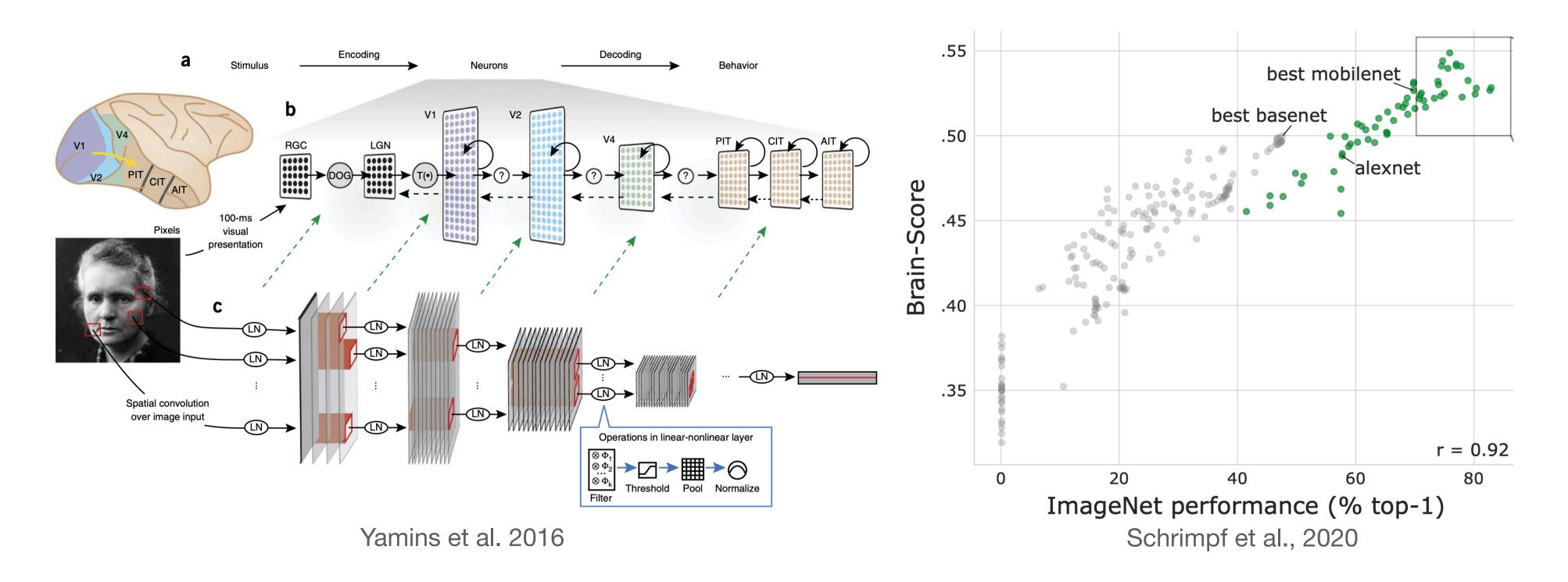


Yamins et al. 2016

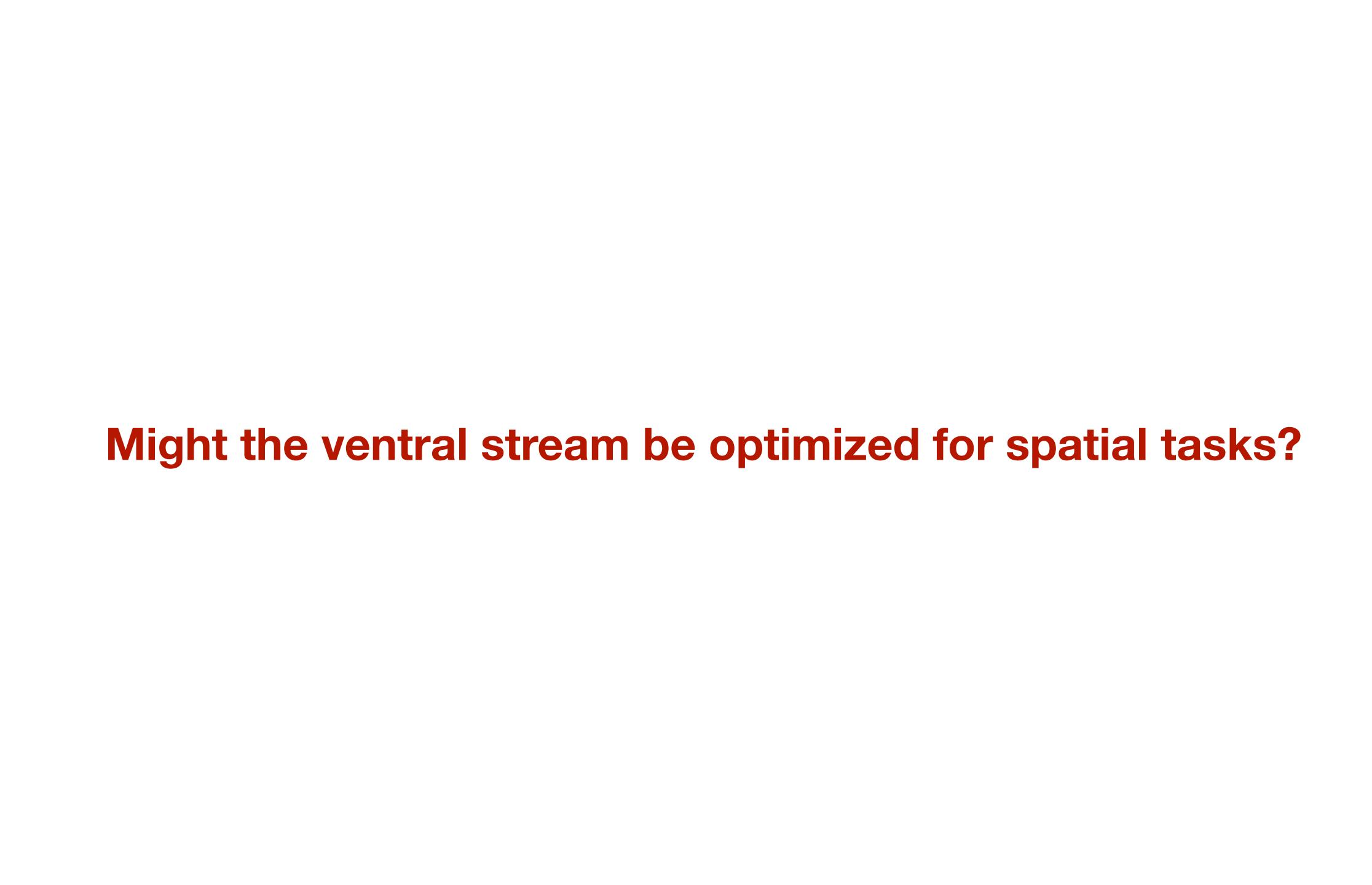
 Most leading ventral stream models are derived by optimizing networks for object categorization.



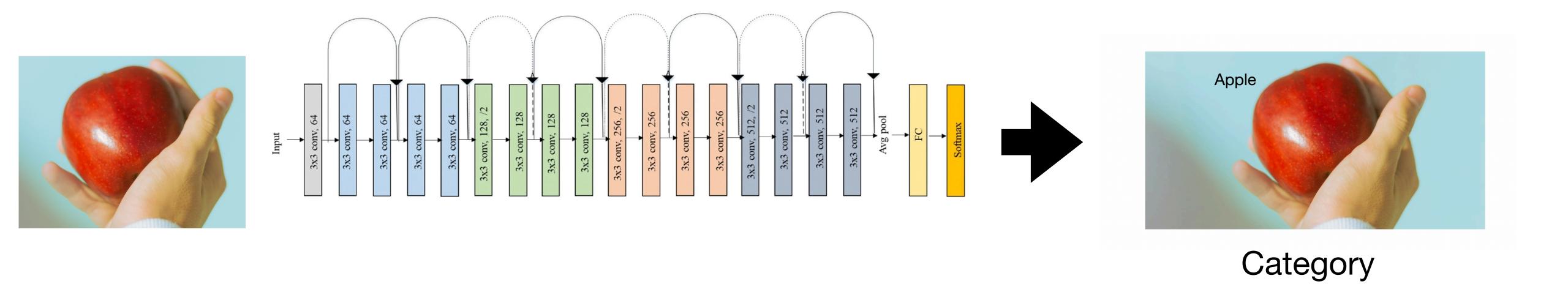
- Most leading ventral stream models are derived by optimizing networks for object categorization.
- Categorization performance strongly correlates with ventral stream alignment.



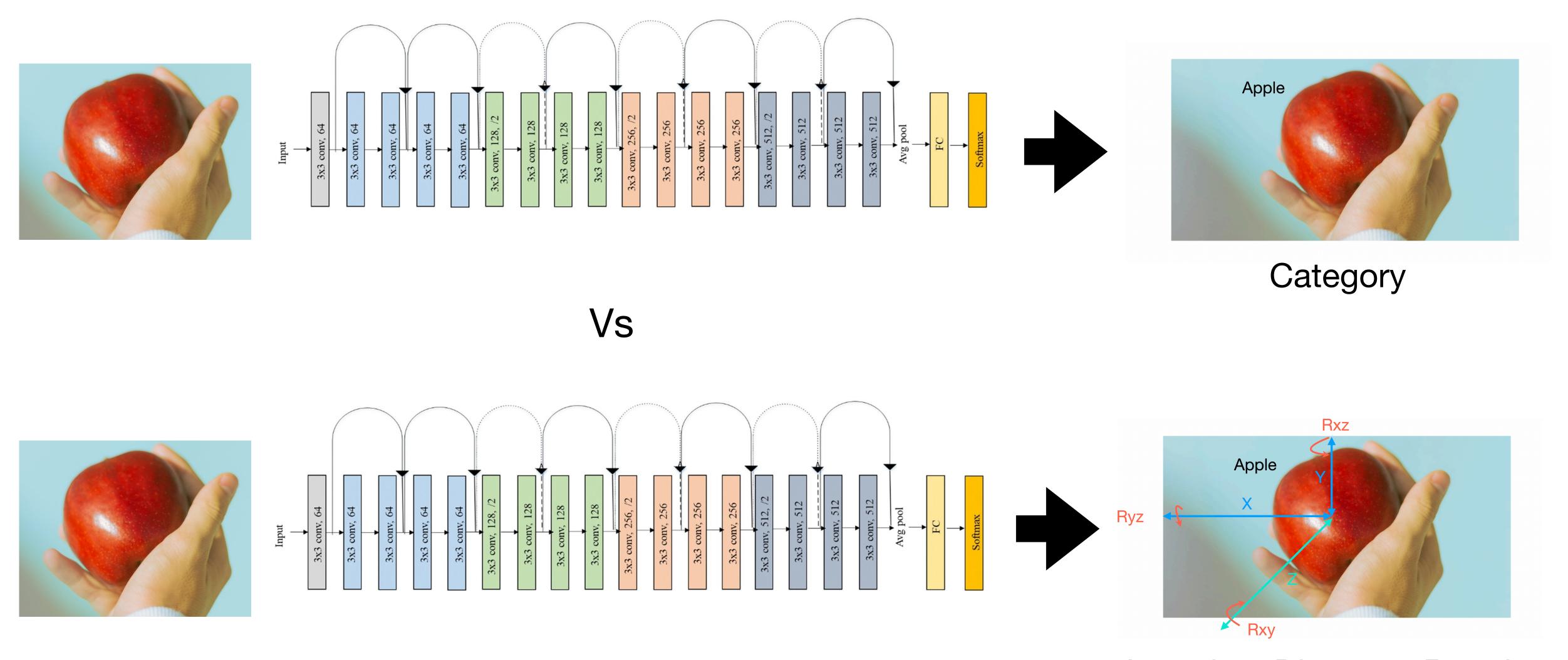
- Most leading ventral stream models are derived by optimizing networks for object categorization.
- Categorization performance strongly correlates with ventral stream alignment.
- This seems to imply that evolution/development derived the ventral stream under the objective of object categorization.



CNN trained to estimate image latents using supervised learning



CNN trained to estimate image latents using supervised learning

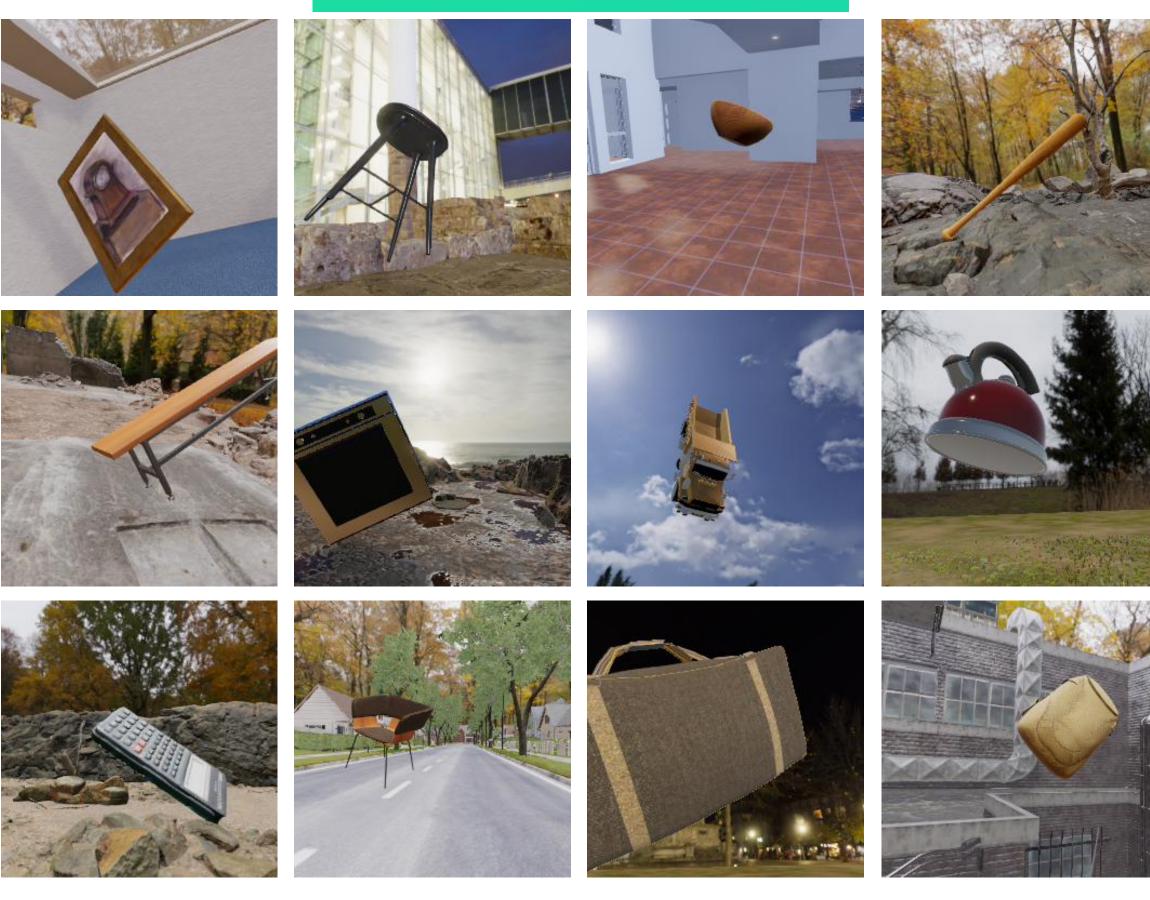


Location, Distance, Rotation

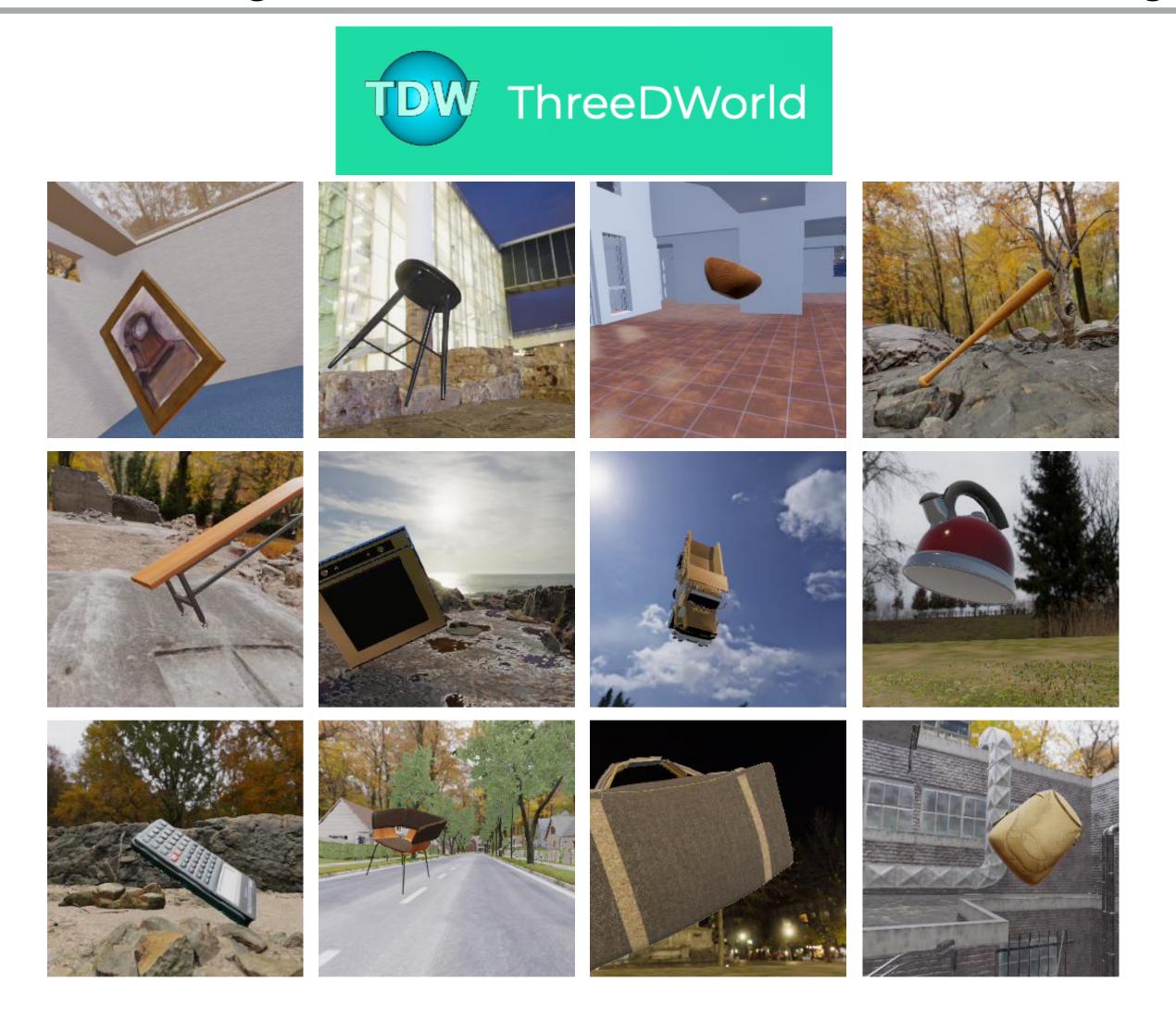
• • •

Synthetic image datasets that contain rich ground-truth latent labels



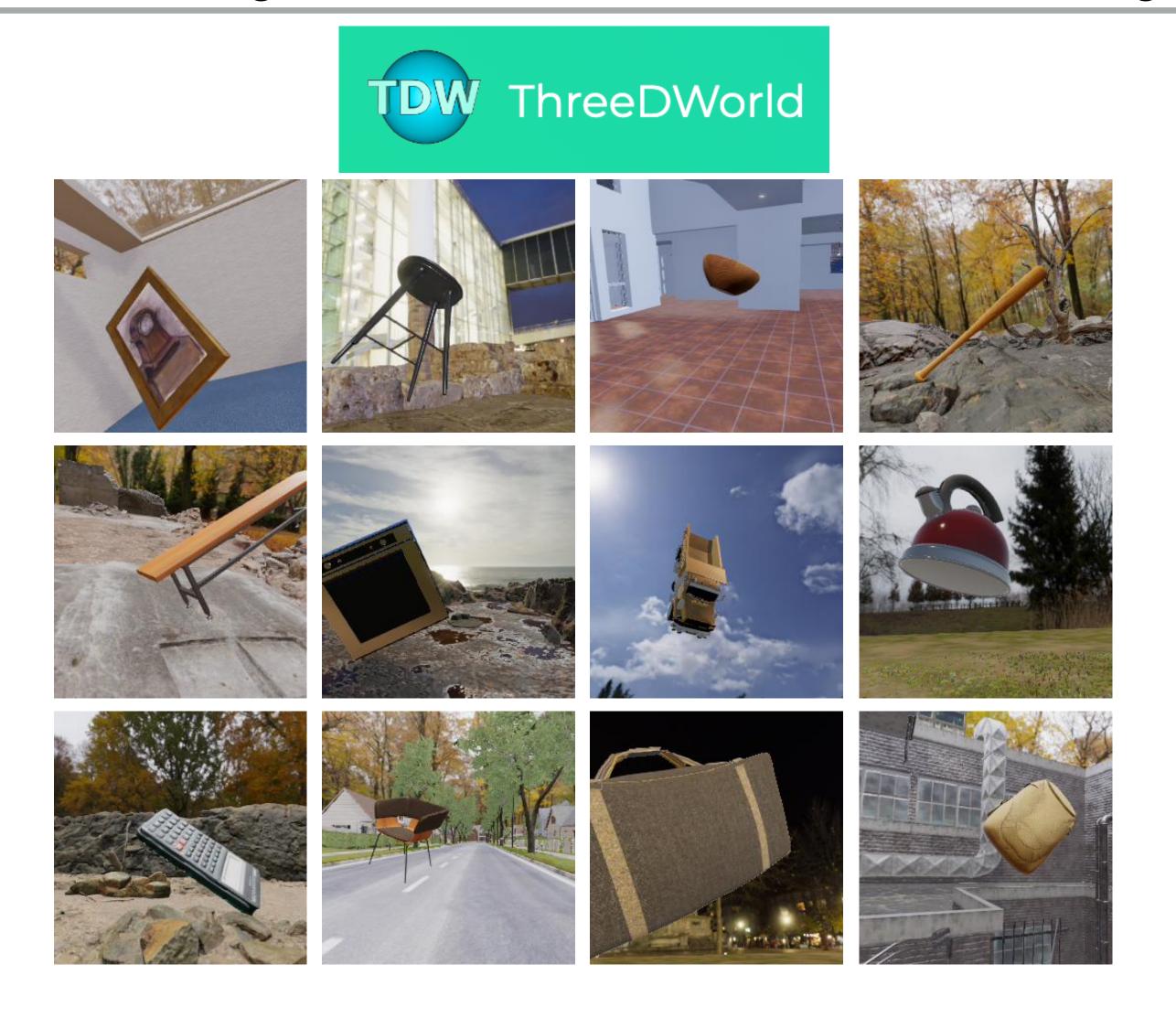


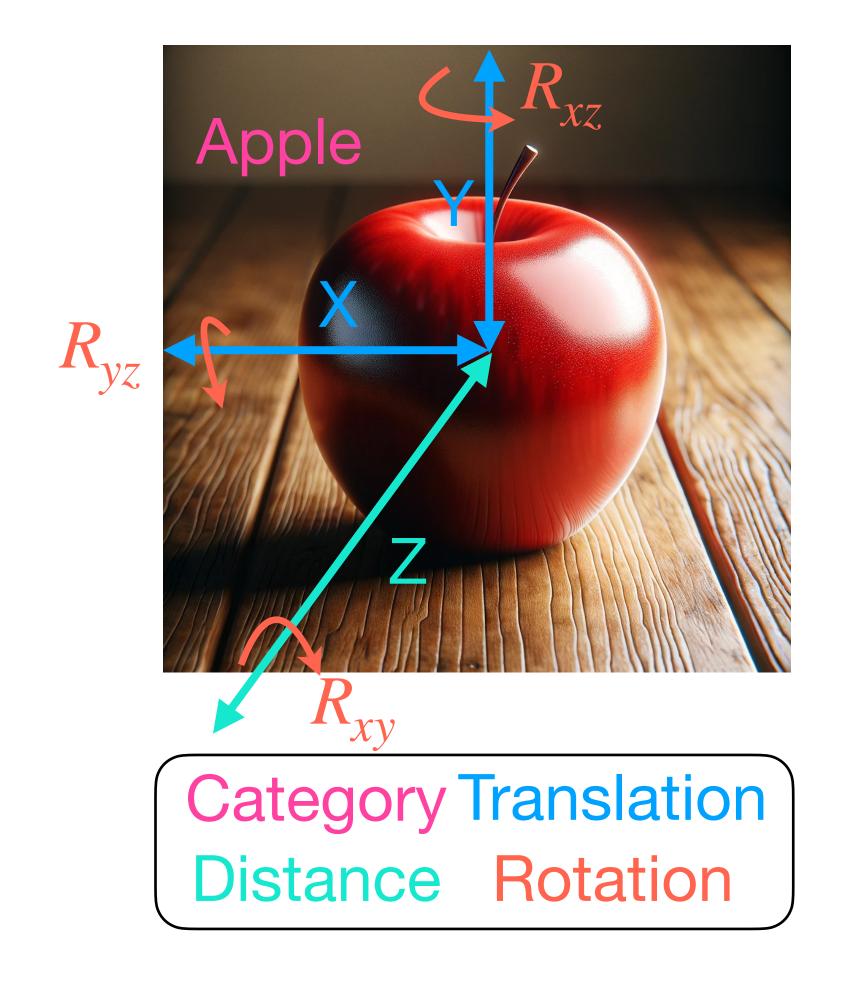
Synthetic image datasets that contain rich ground-truth latent labels



 We used TDW, a 3D graphic engine, to generate large image datasets (up to 100M) that contain rich ground-truth latent labels.

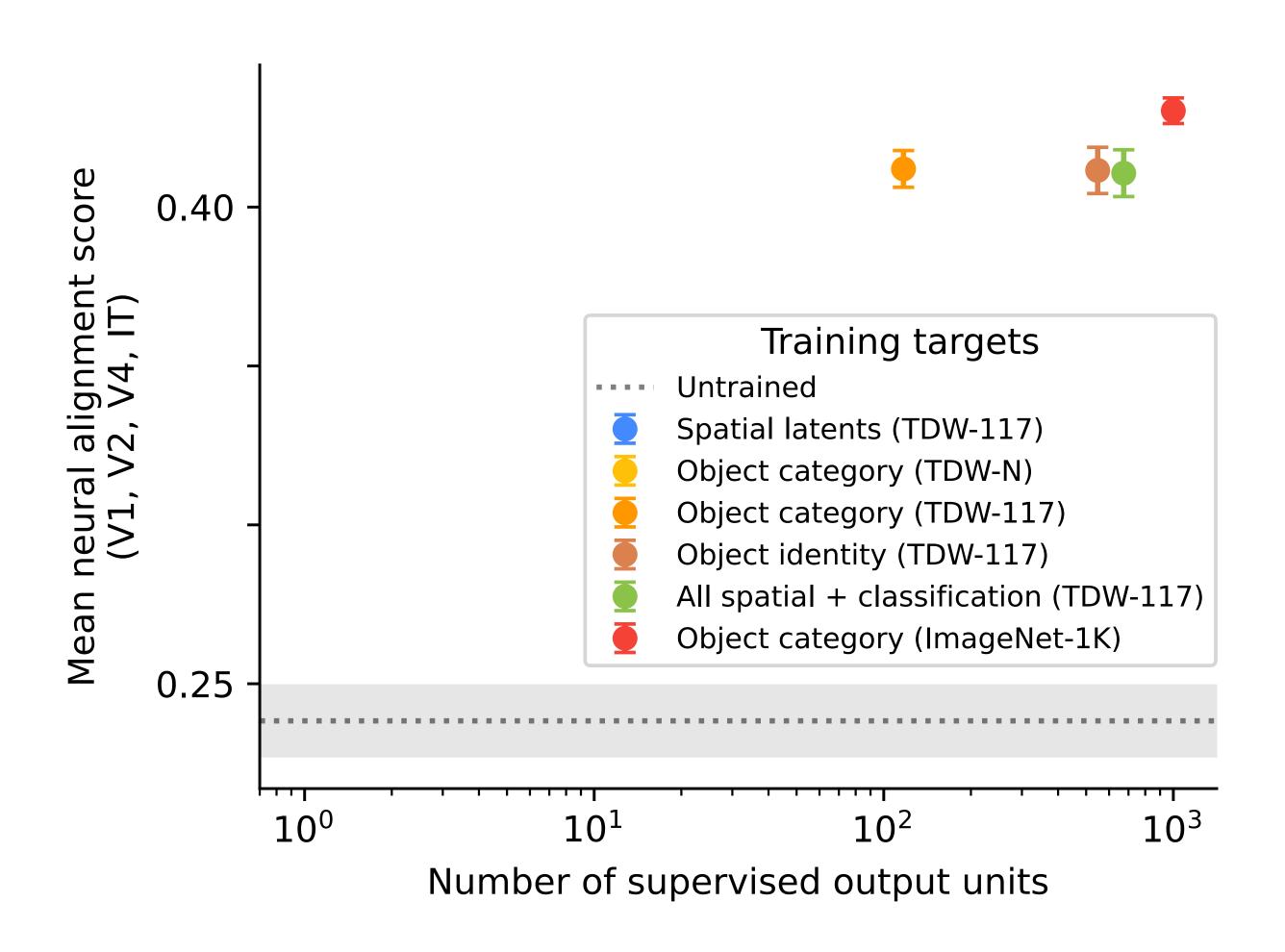
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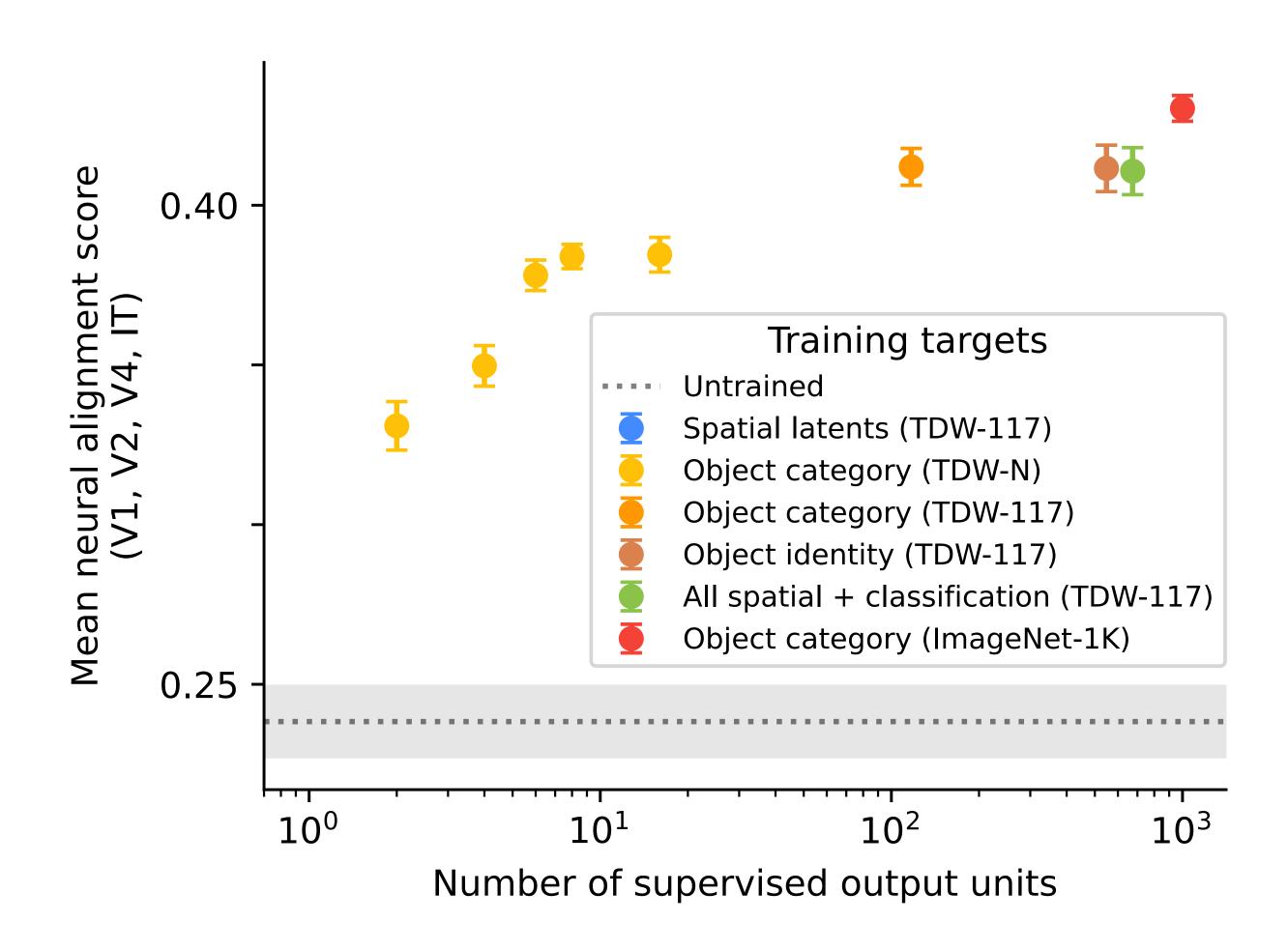


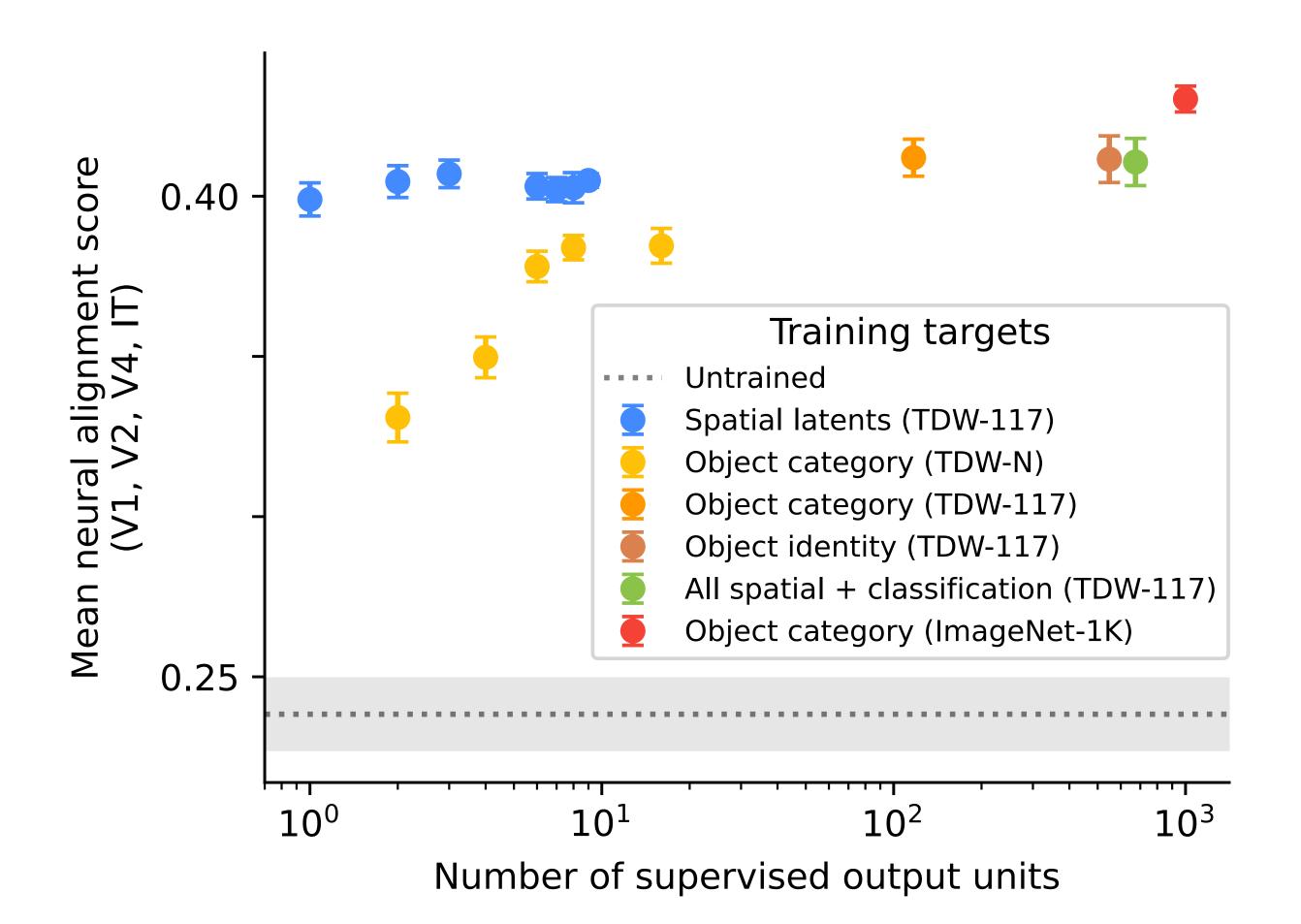


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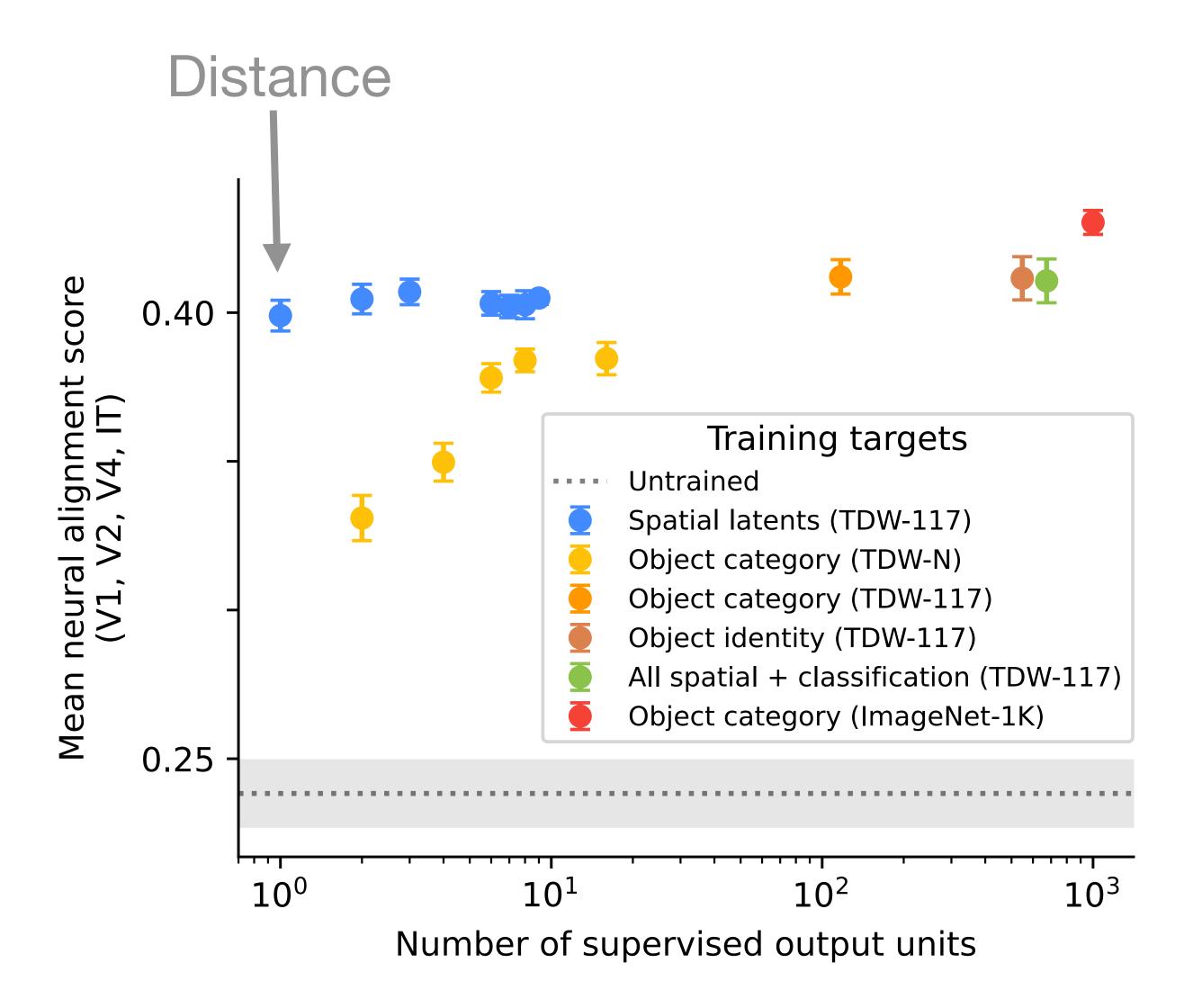




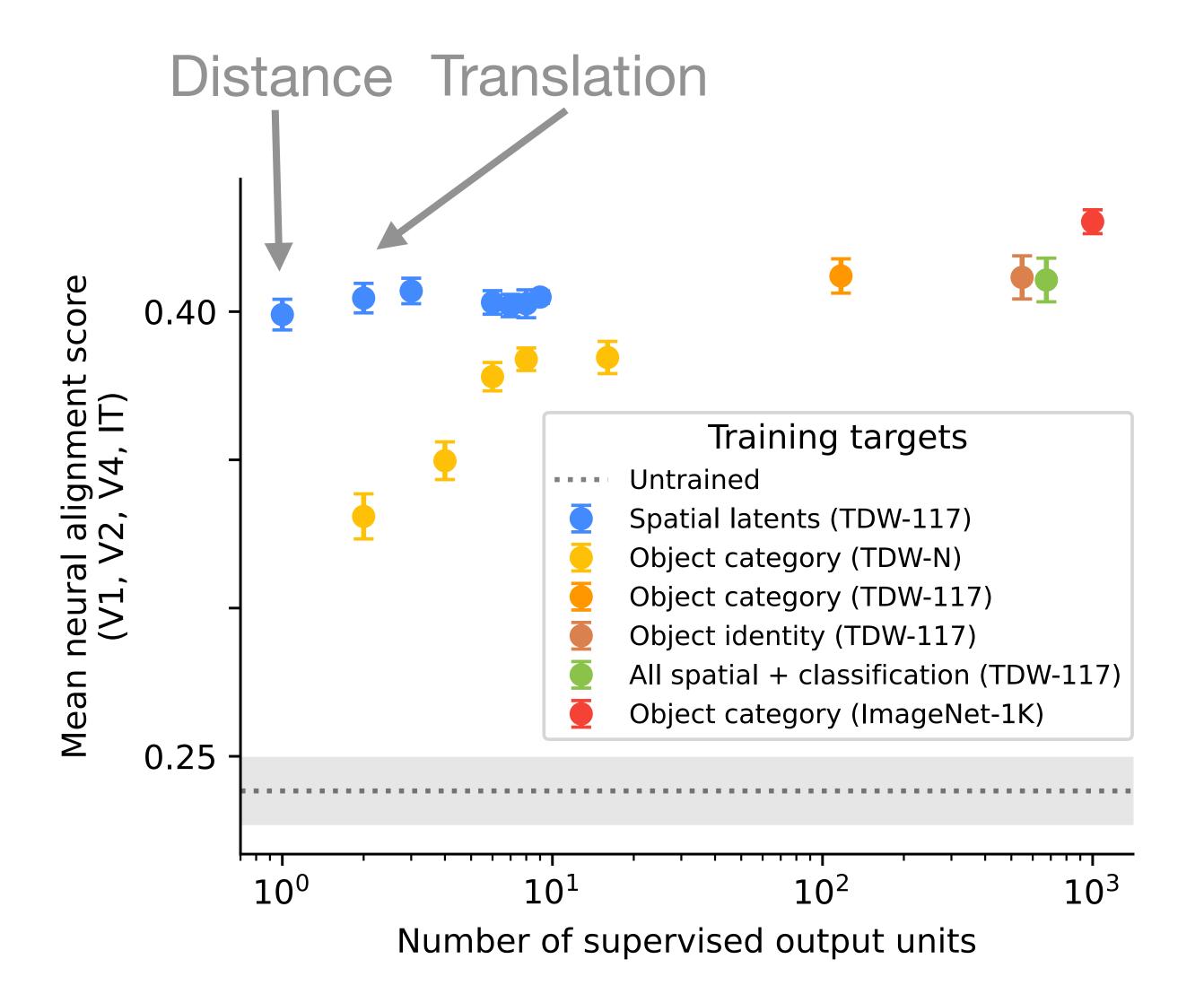




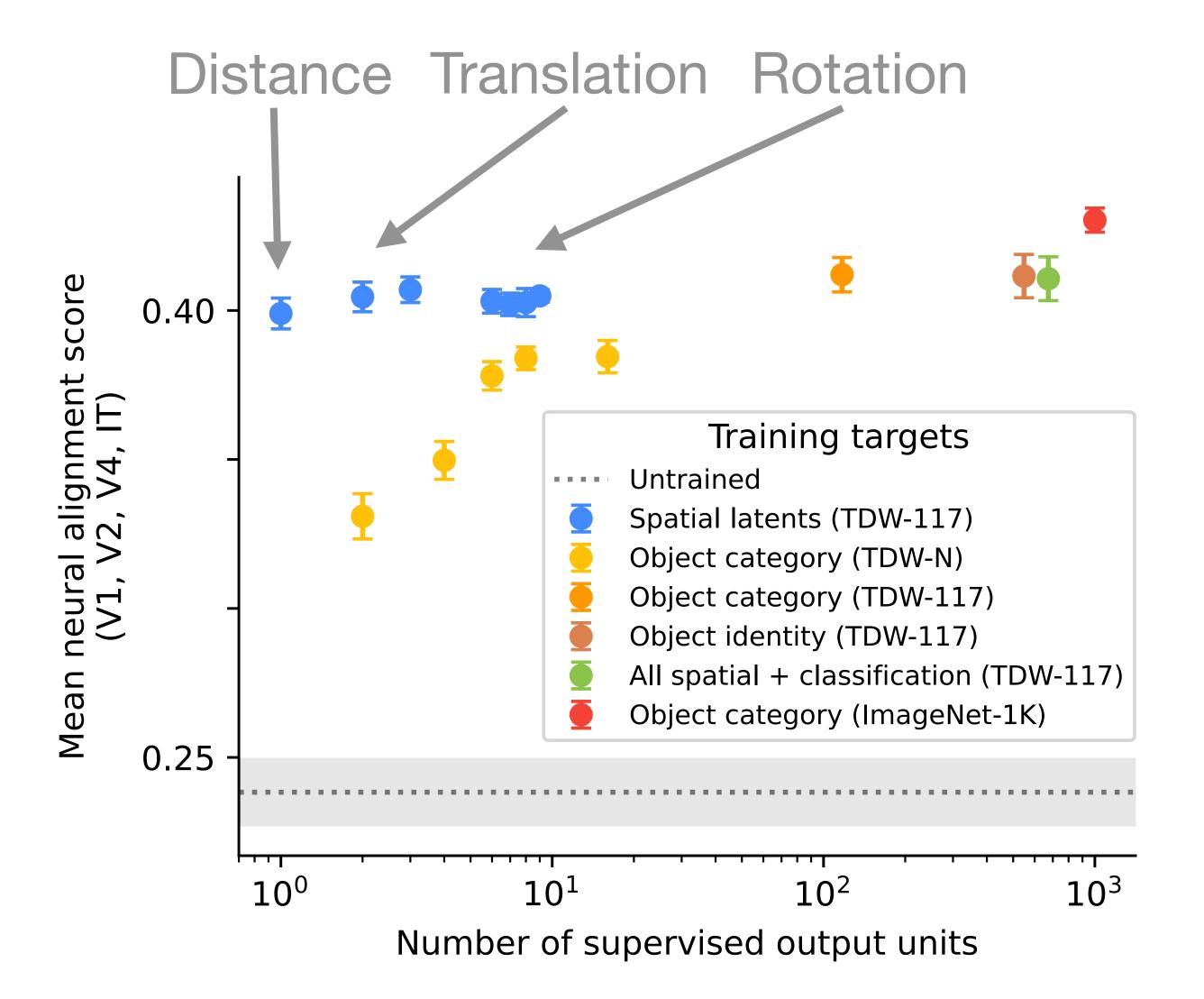
	Training task	# output targets
Spatial latent regression (TDW-117)	Distance regression	1
	Translation regression	2
	Distance + Translation	3
	Rotation regression	6
	Distance + Rotation	7
	Translation + Rotation	8
	Distance + Translation + Rotation	9
Classification (TDW-117)	Object category classification	117
	Object identity classification	548
	All spatial latents + classification	674
Reference	Untrained	NA
	ImageNet-1K classification	1000



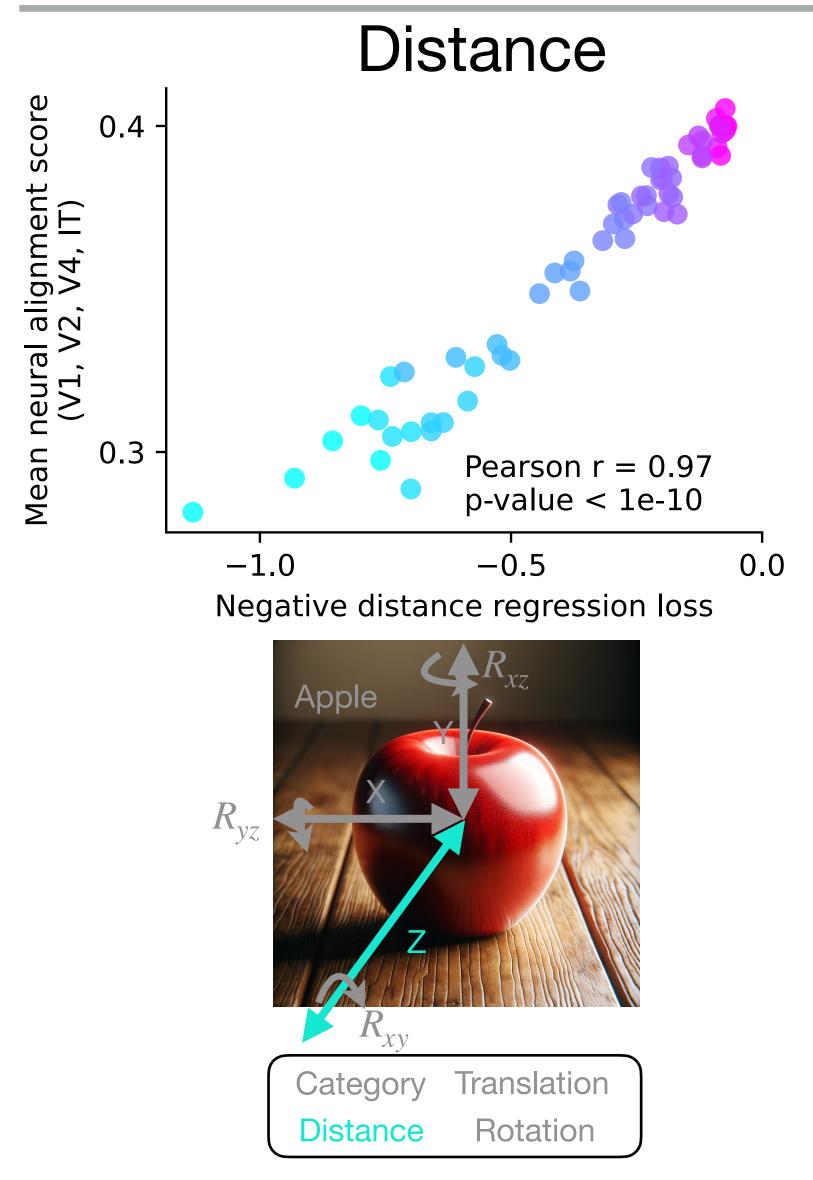
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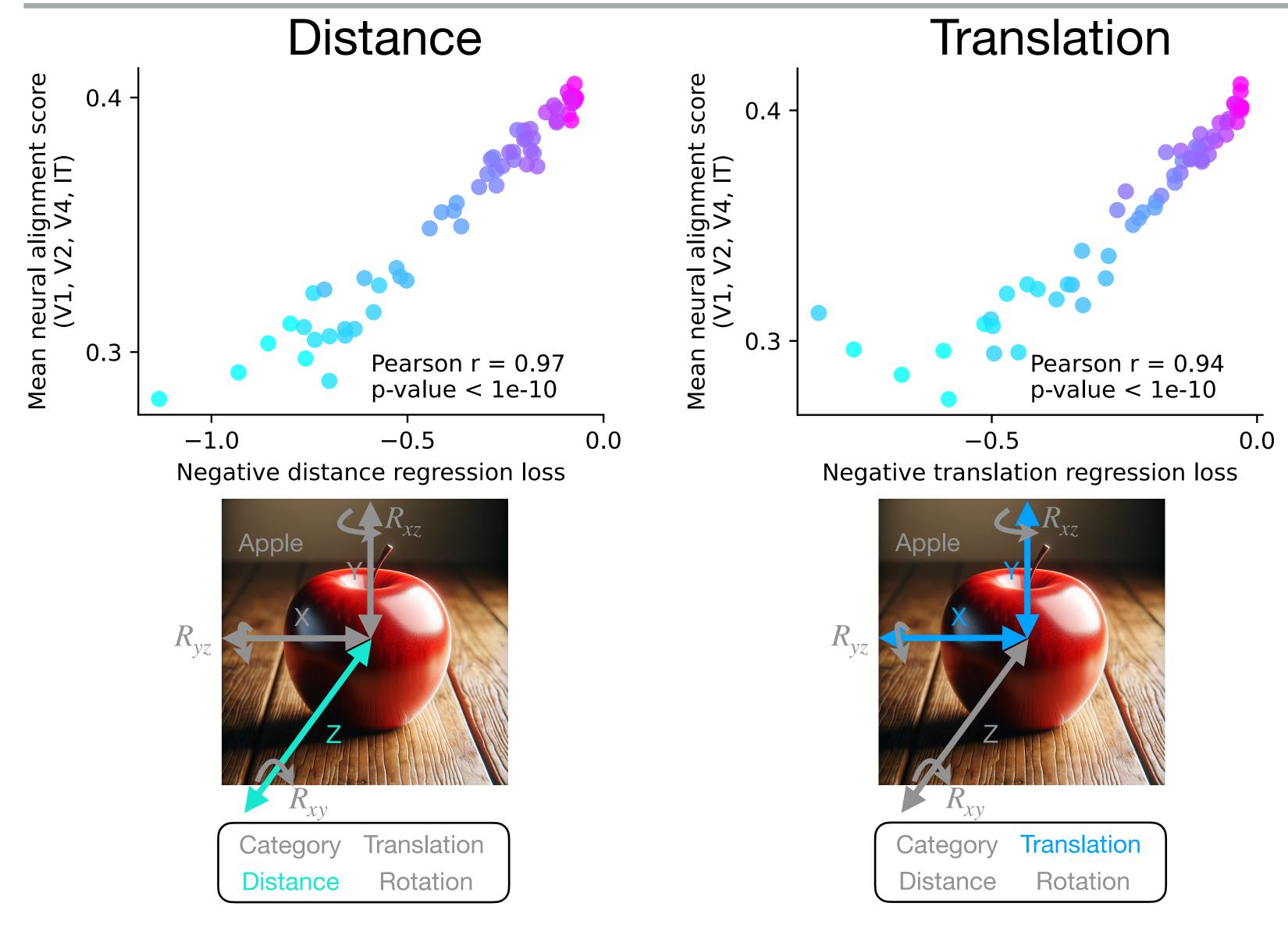


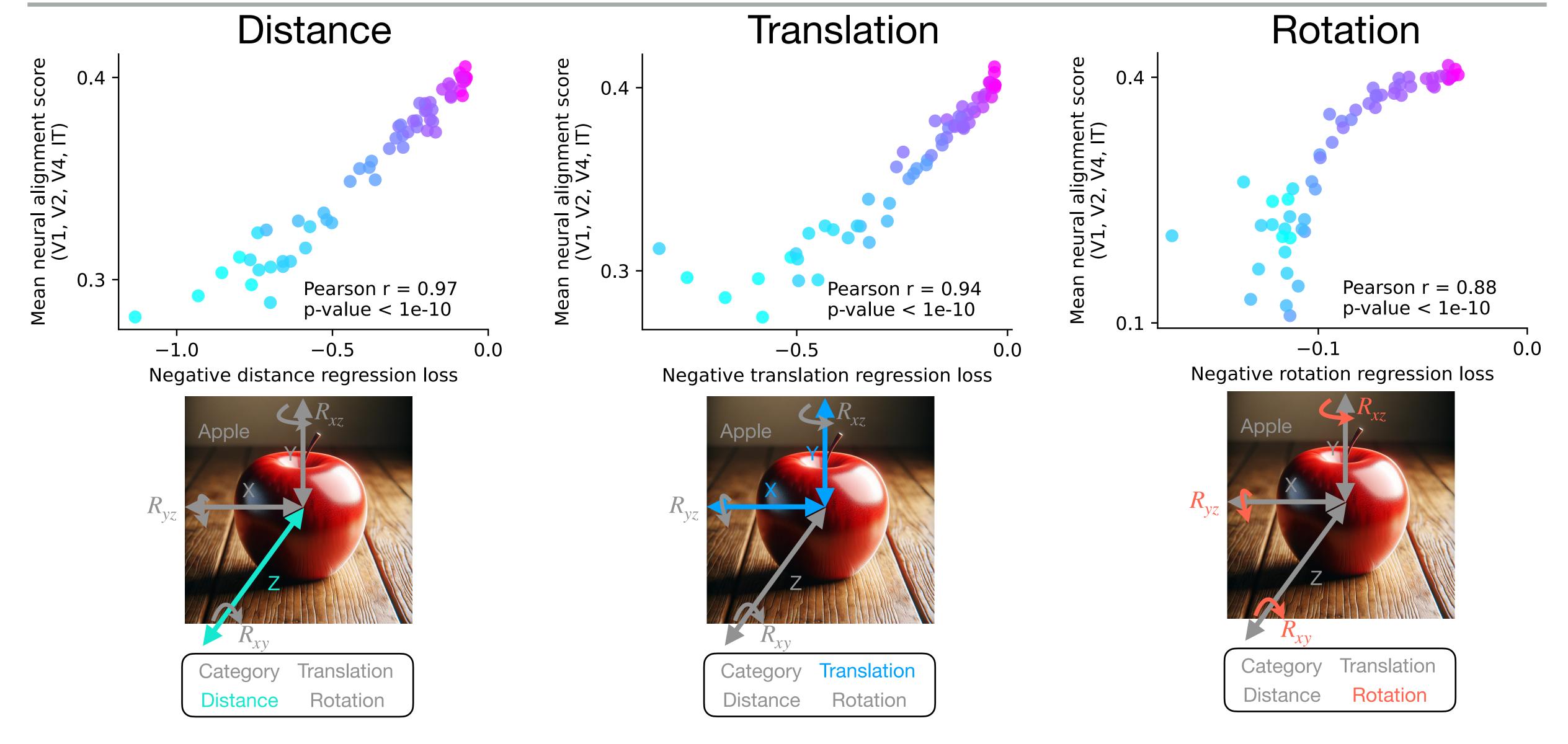
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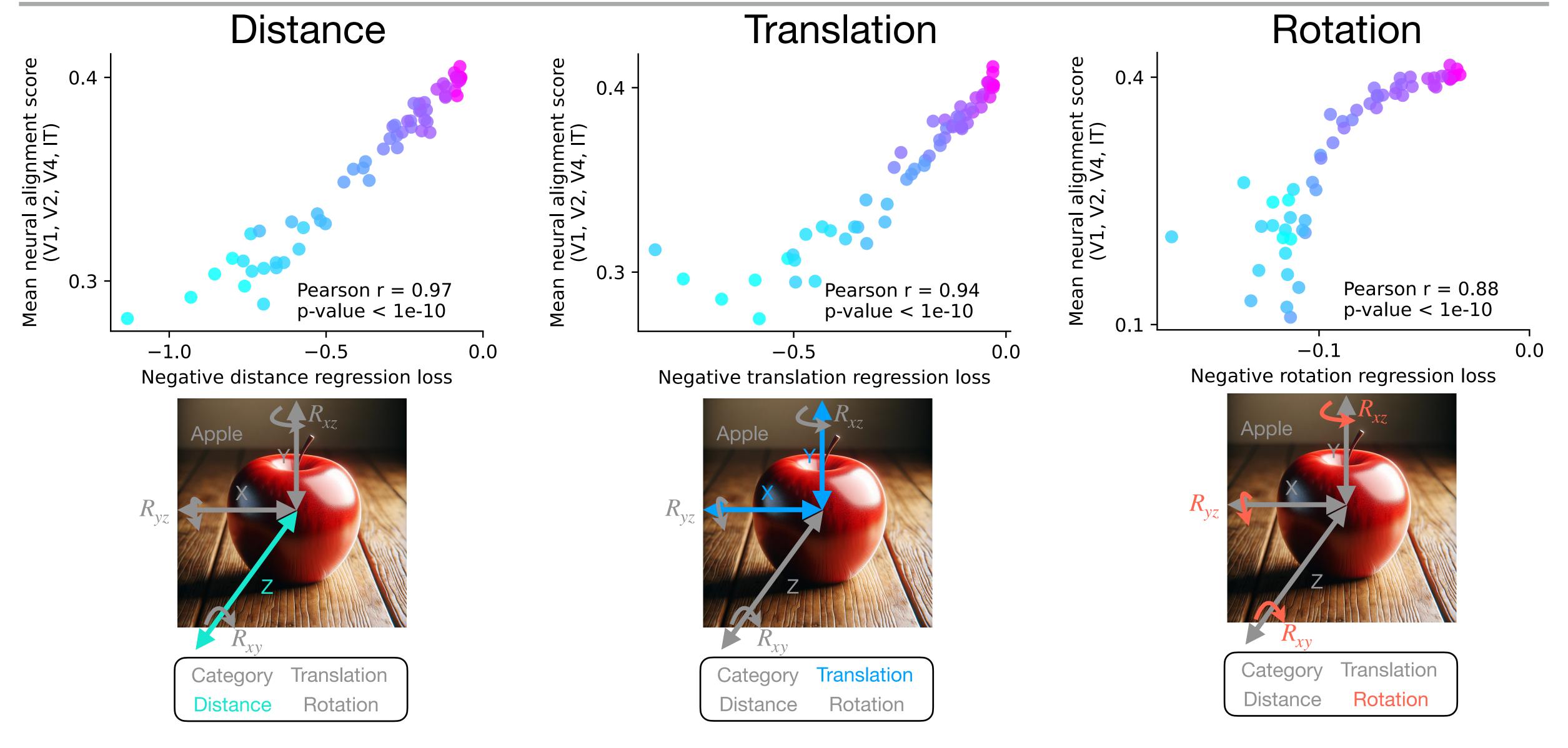


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• The ventral stream function is also to estimate spatial latents

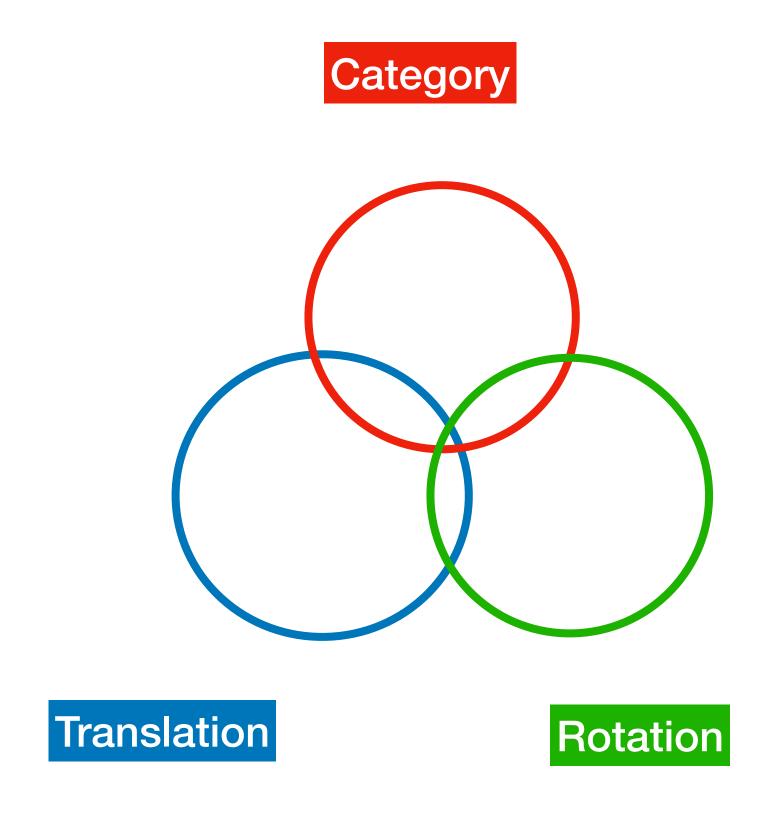
Learning a few spatial latents produced models that has similar neural alignment scores as model trained on categories.

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Why is that so? At least two hypotheses:

Learning a few spatial latents produced models that has similar neural alignment scores as model trained on categories.

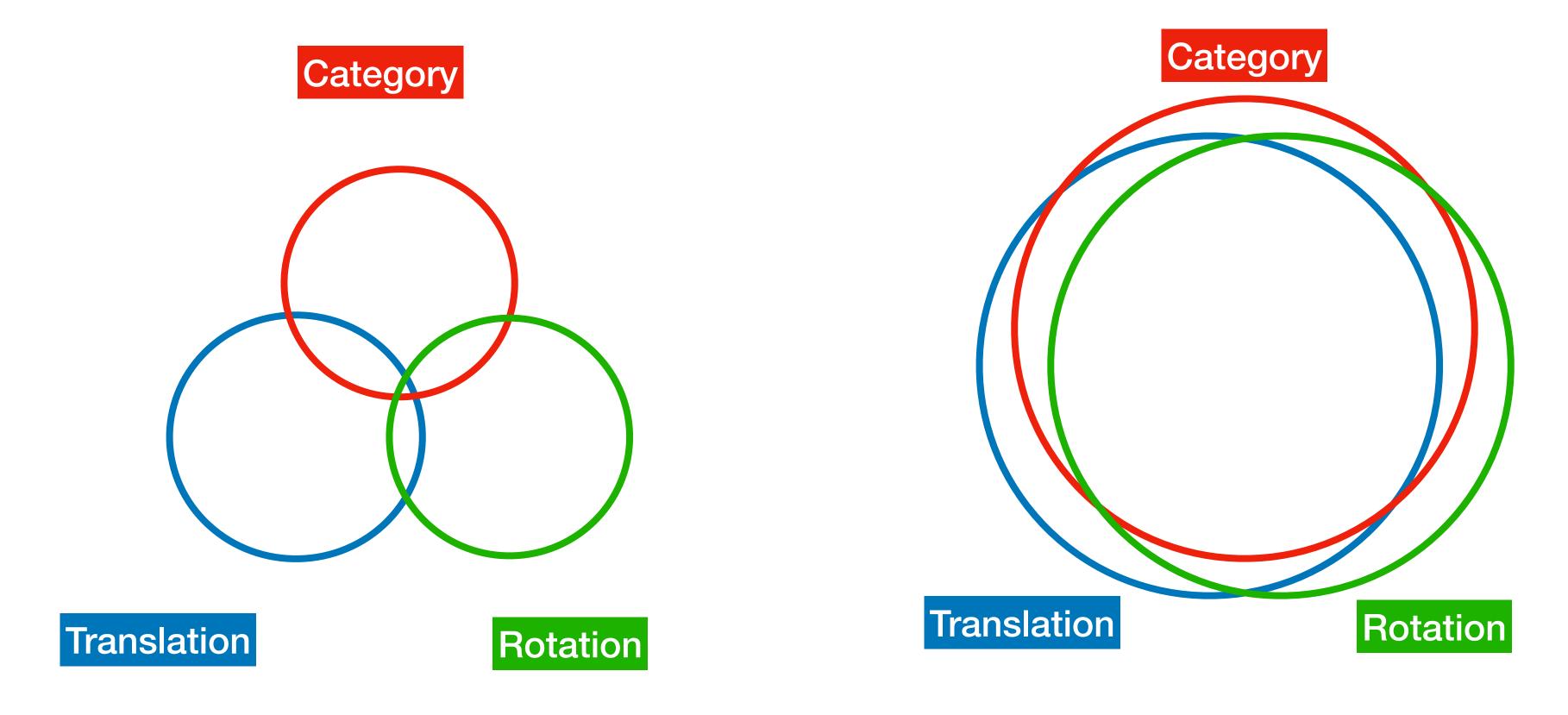
Why is that so? At least two hypotheses:



 Largely dissimilar representations that are equally similar to neural data.

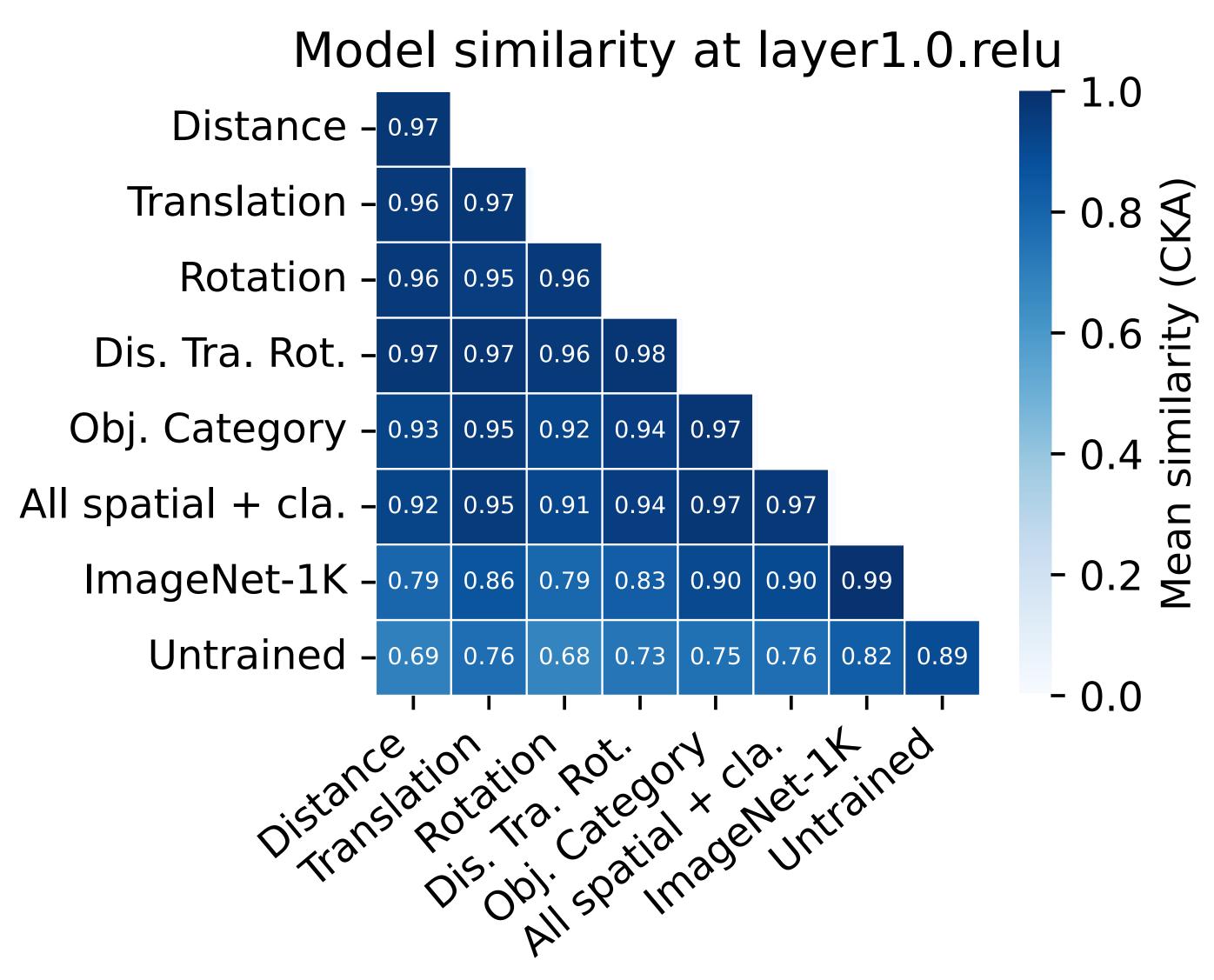
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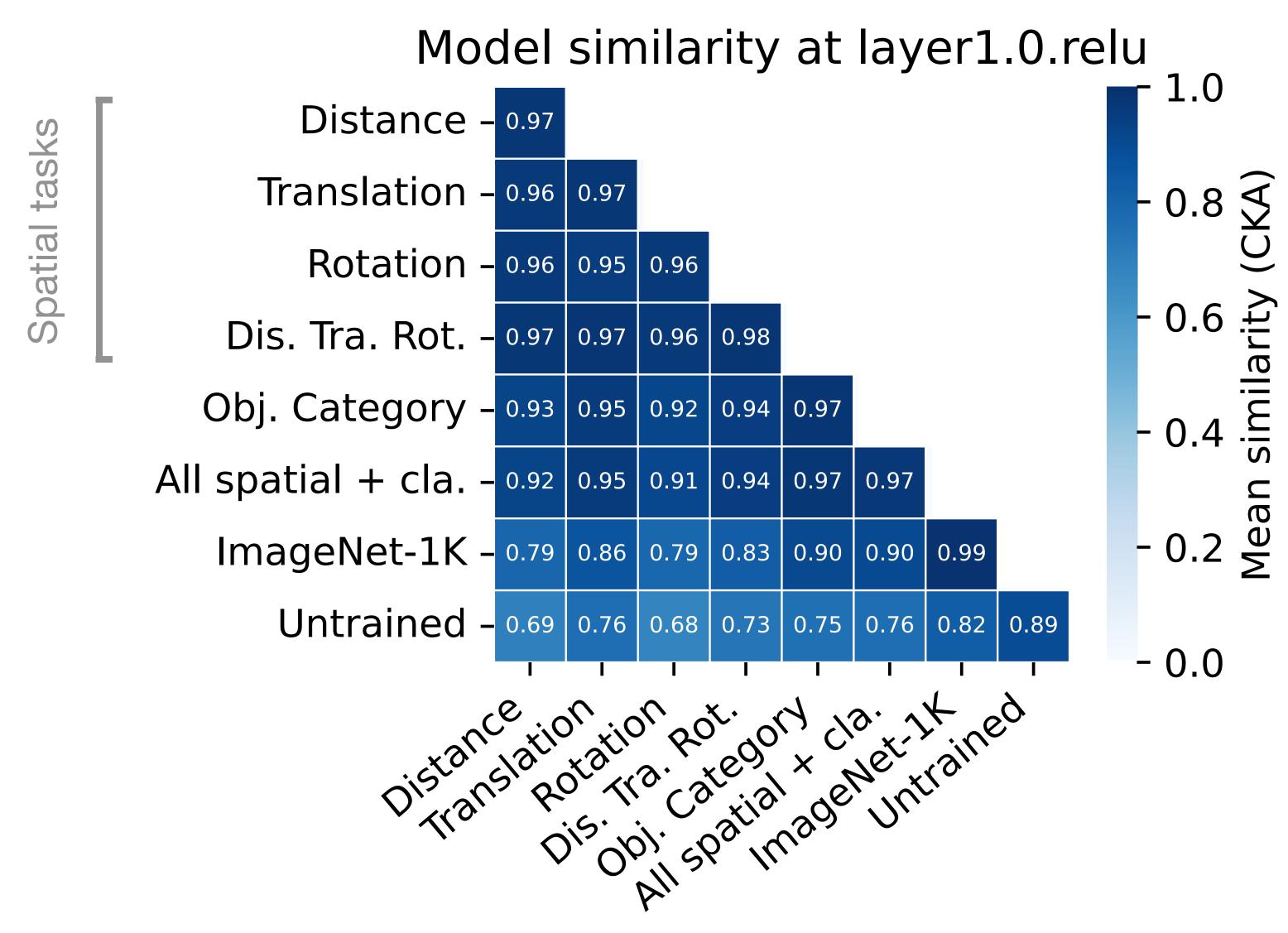
- Largely dissimilar representations that are equally similar to neural data.
- Largely similar representations, thus, similar alignment scores.

Different objectives lead to similar representations in early layers



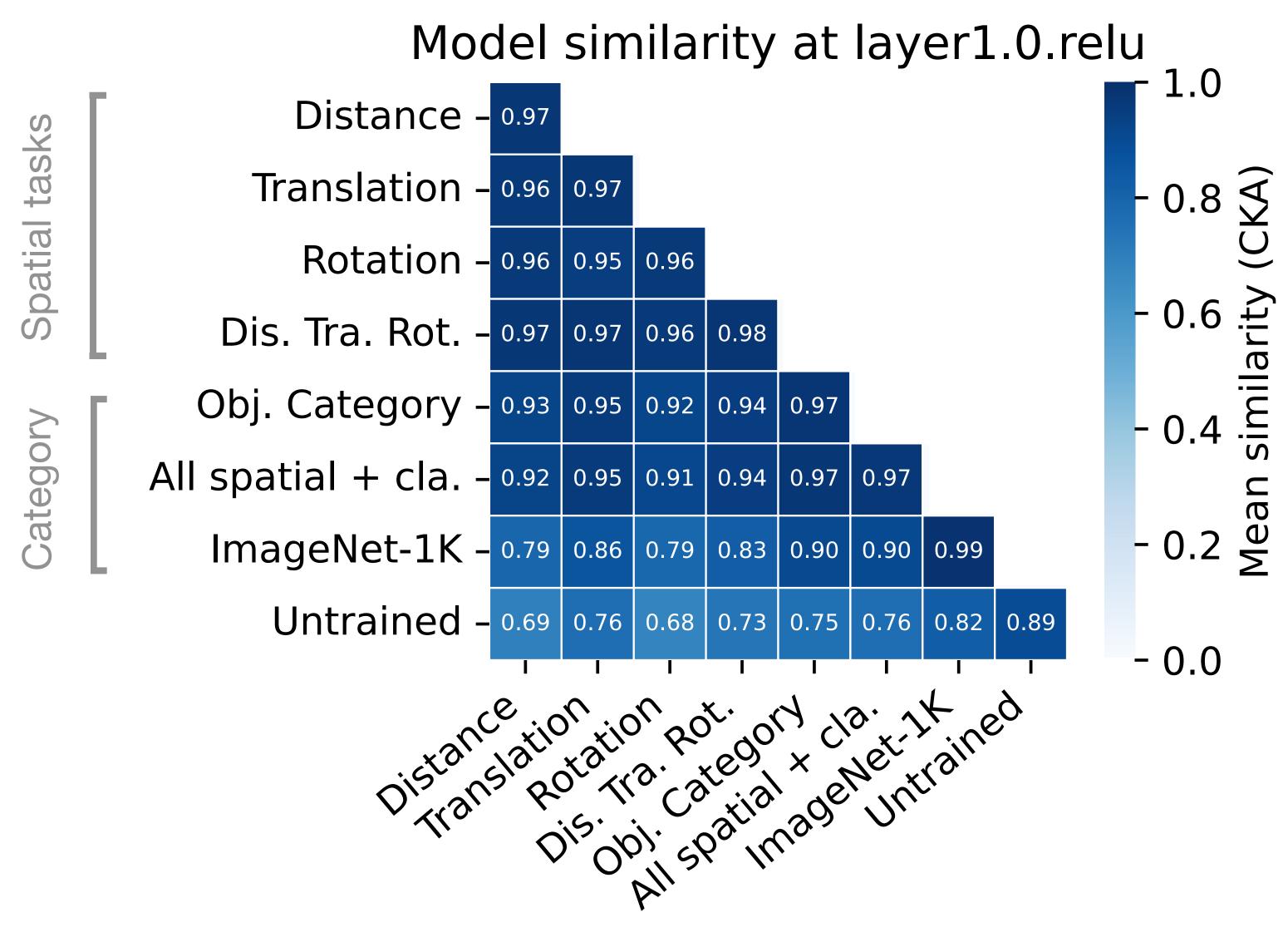
 CKA analysis revealed models learned very similar representations despite trained on very different tasks.

Different objectives lead to similar representations in early layers



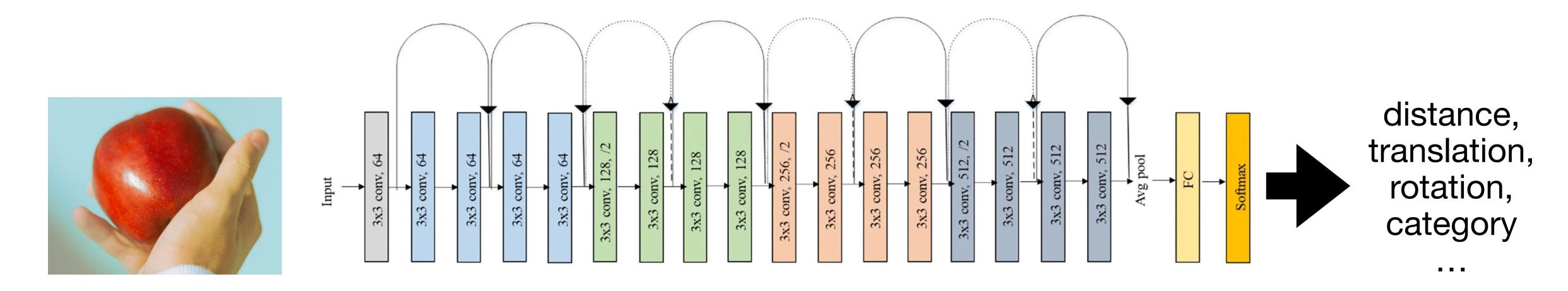
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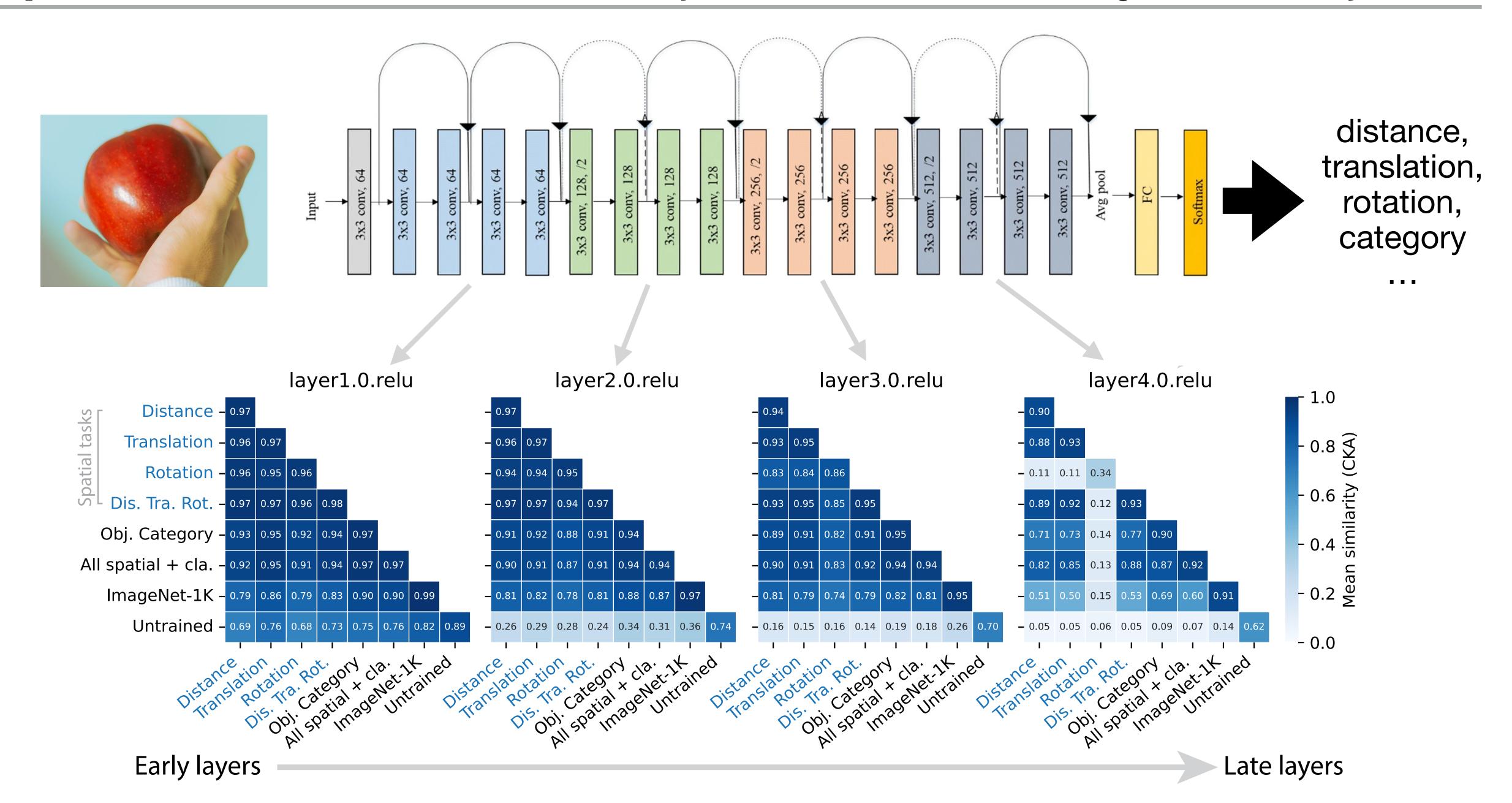


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Representations are similar in early to middle, but diverge at late layers

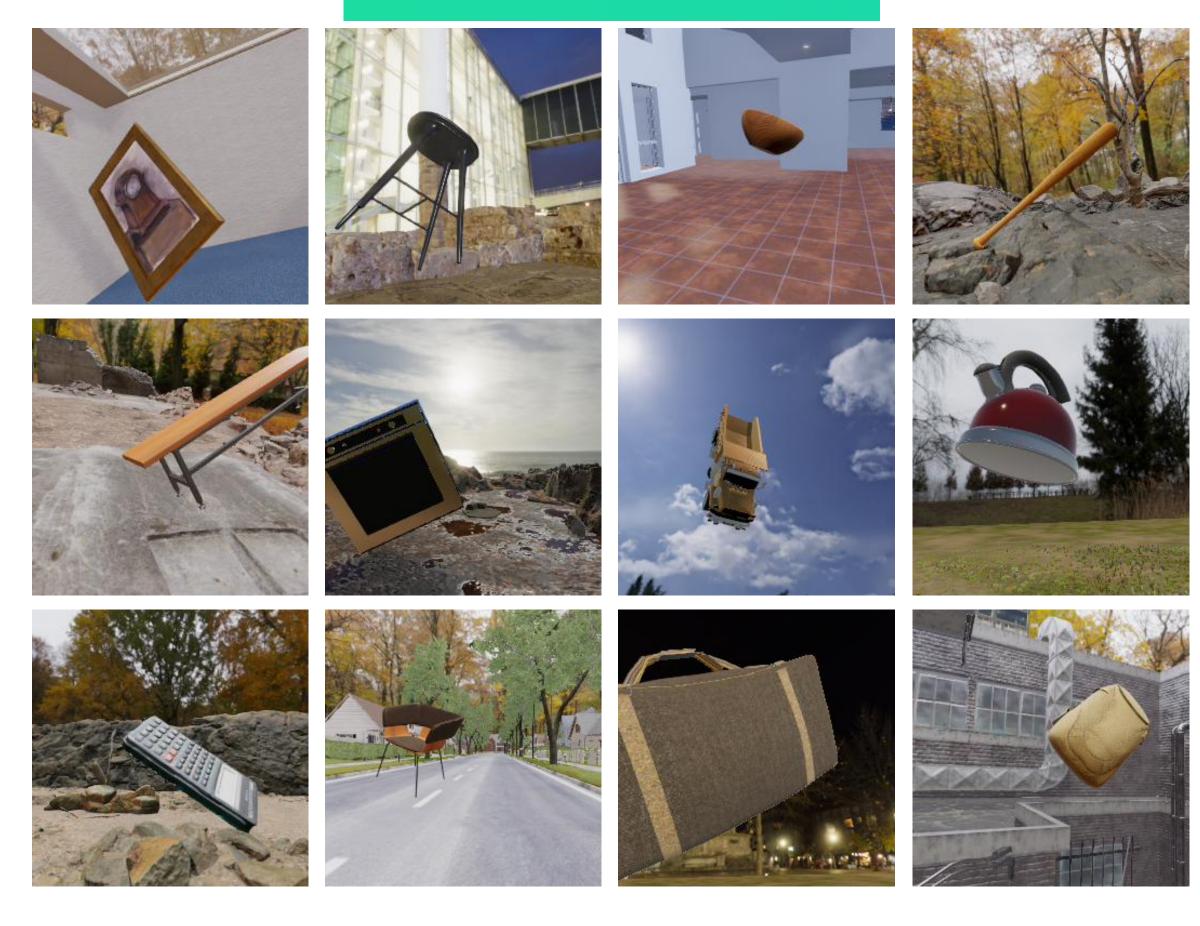


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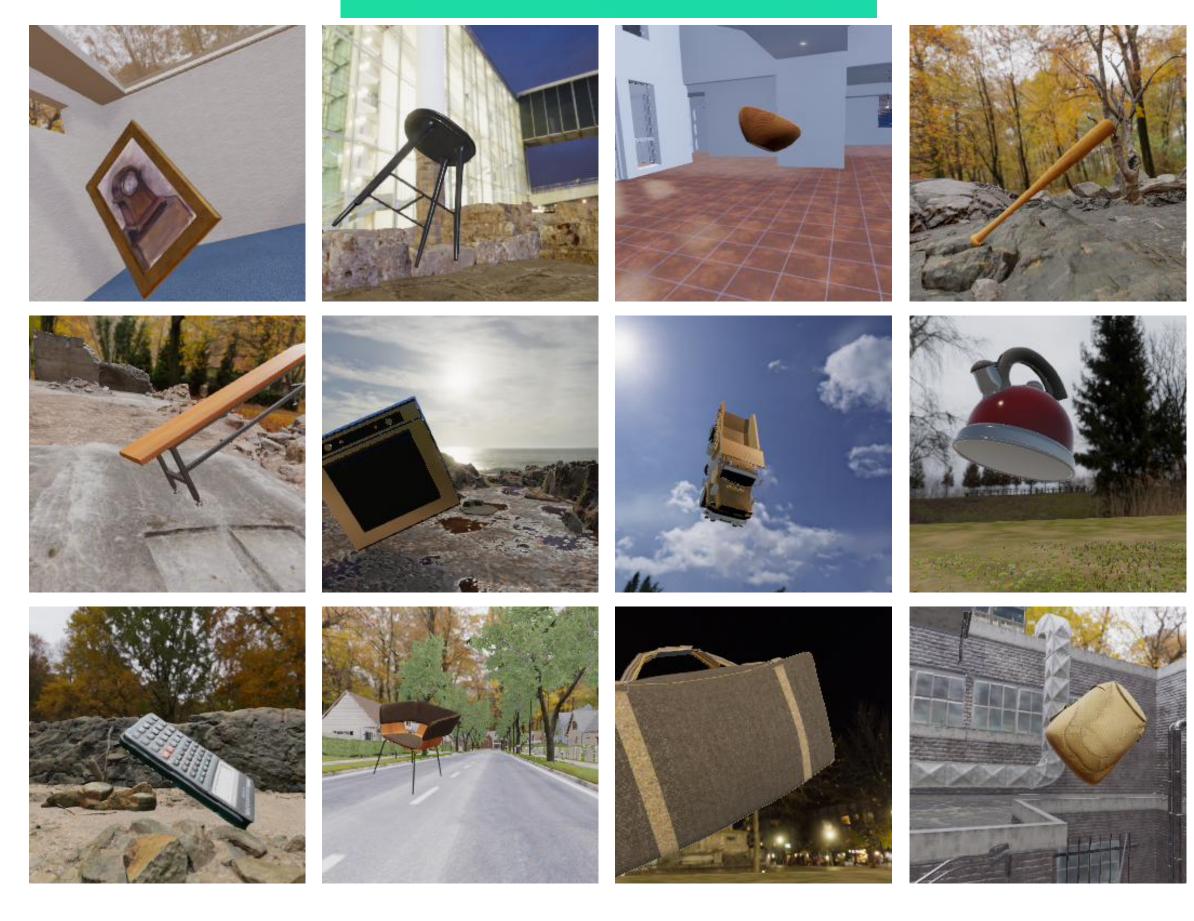
Why do models learn similar representations? (Despite being trained on very different tasks)

TDW ThreeDWorld

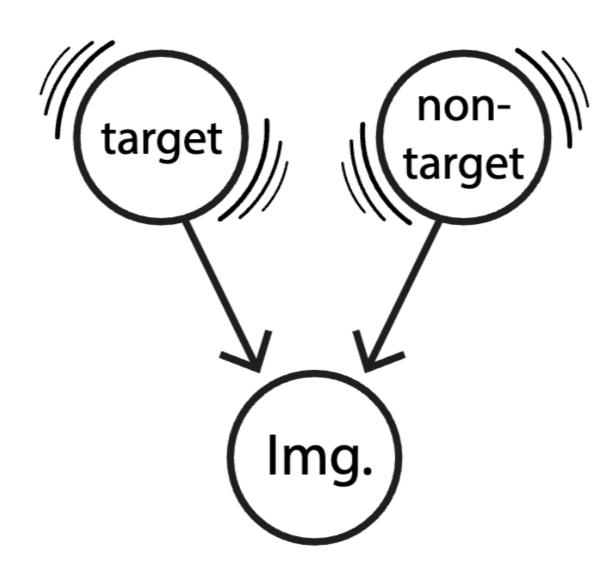


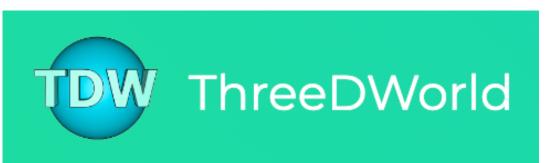
• Models are trained on the same dataset although different tasks.

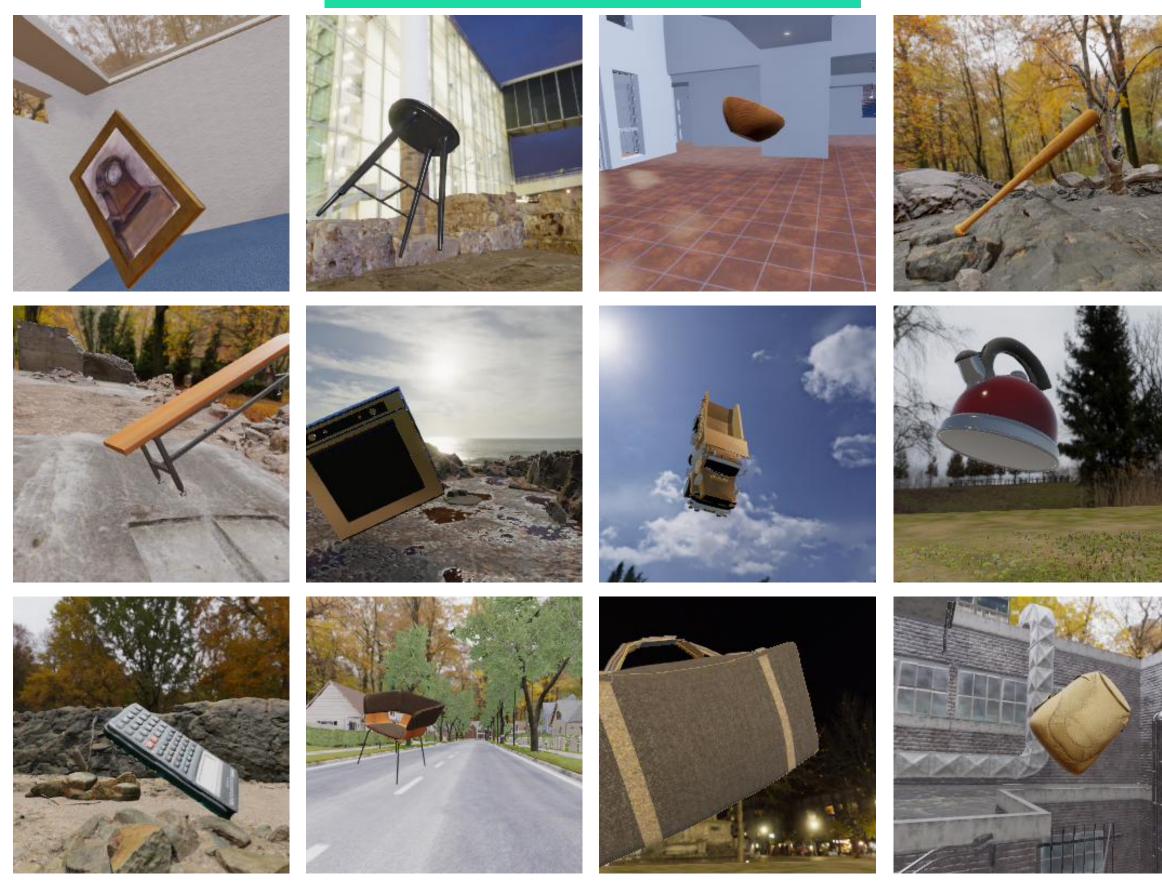
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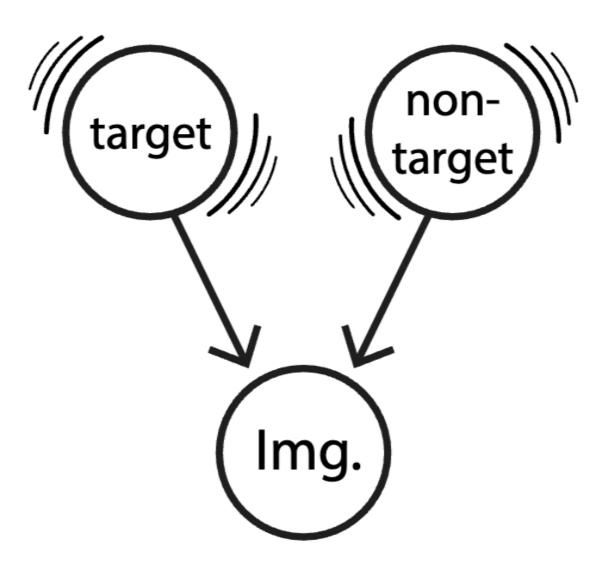
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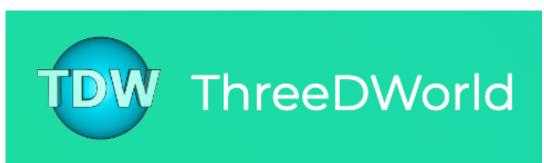


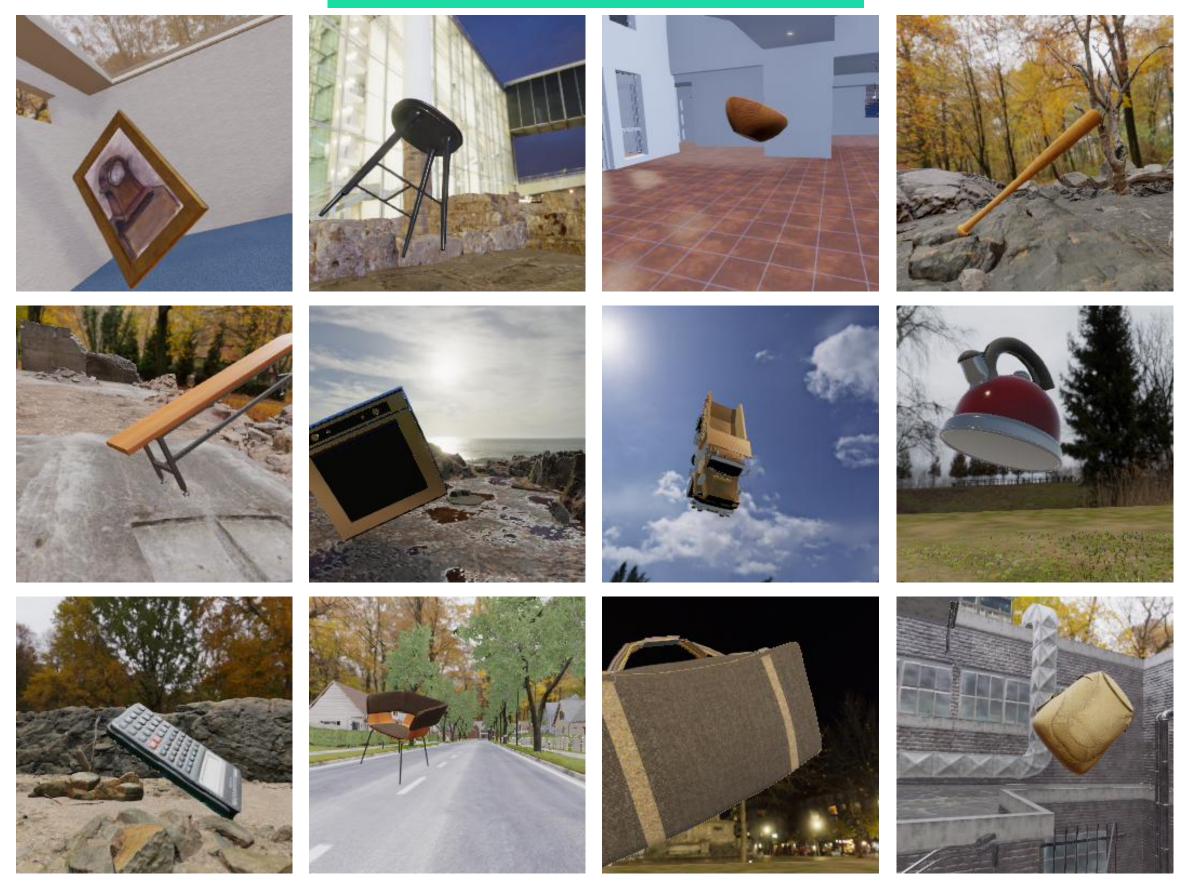




Our hypothesis:

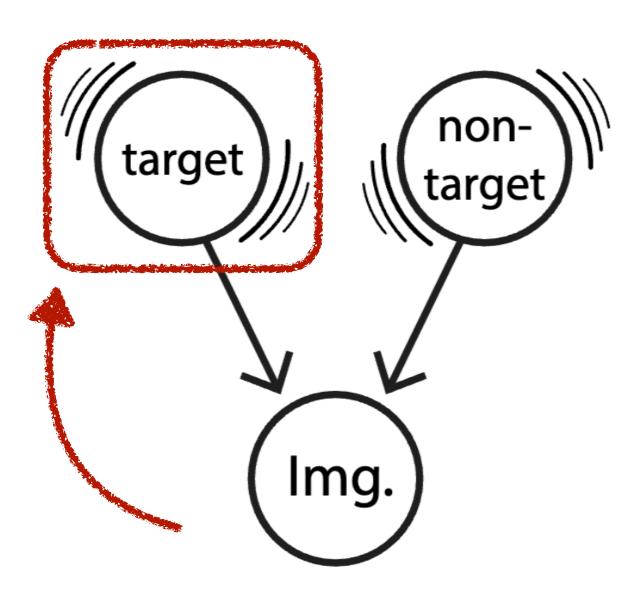


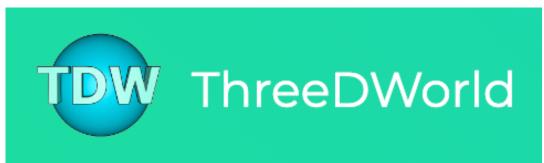




Our hypothesis:

learn the target latent

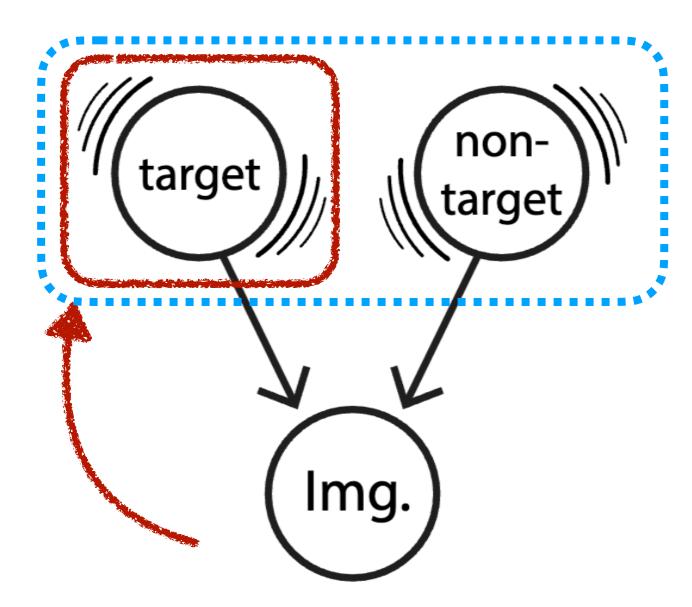


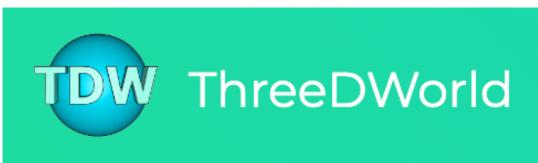


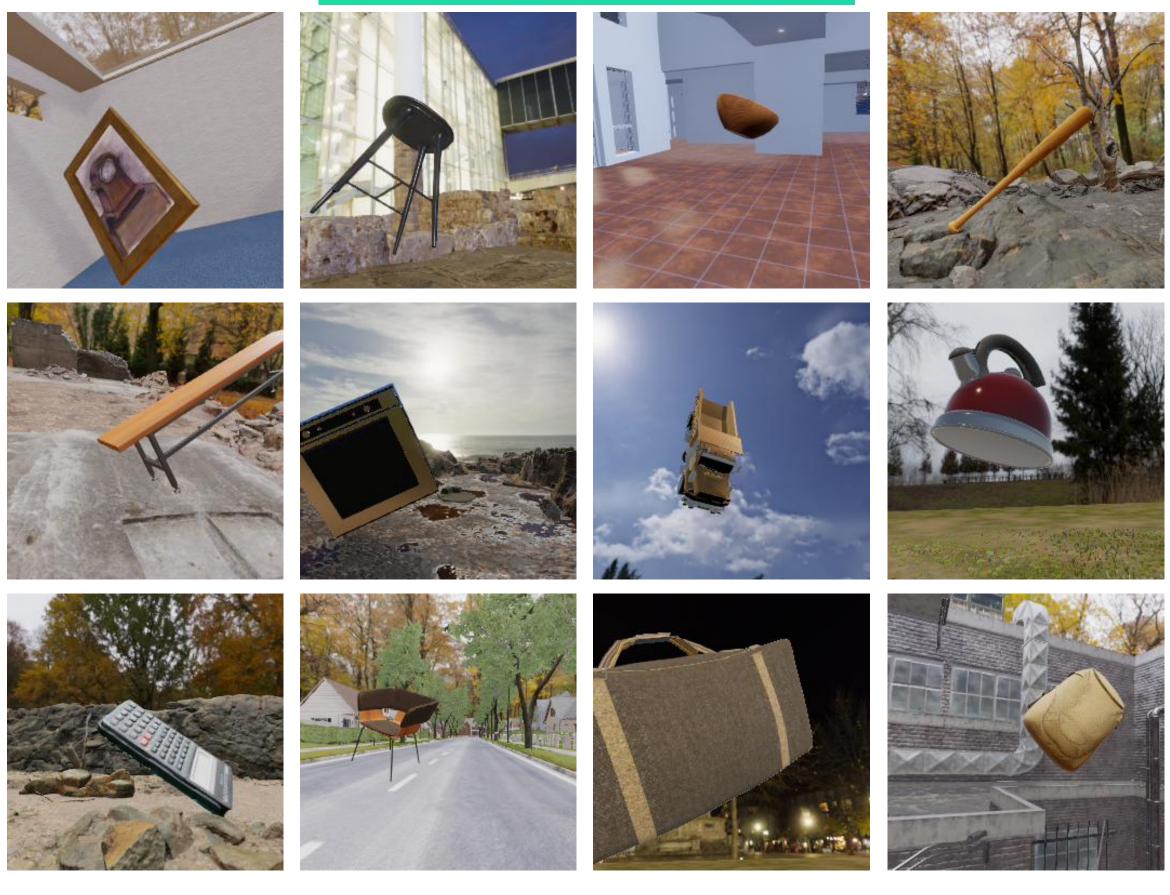


Our hypothesis:

- learn the target latent
- inadvertently learned non-target latents due to their variability.

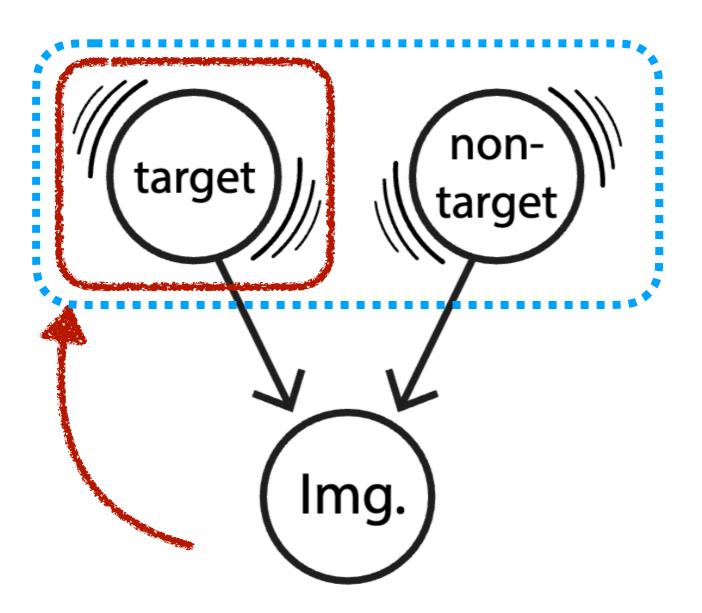




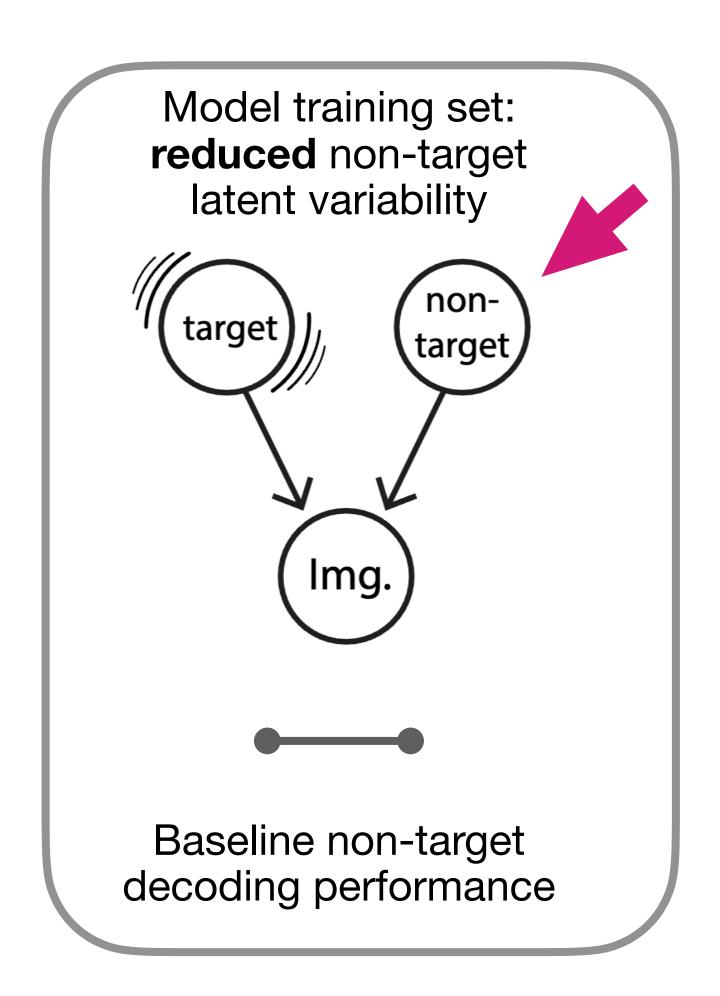


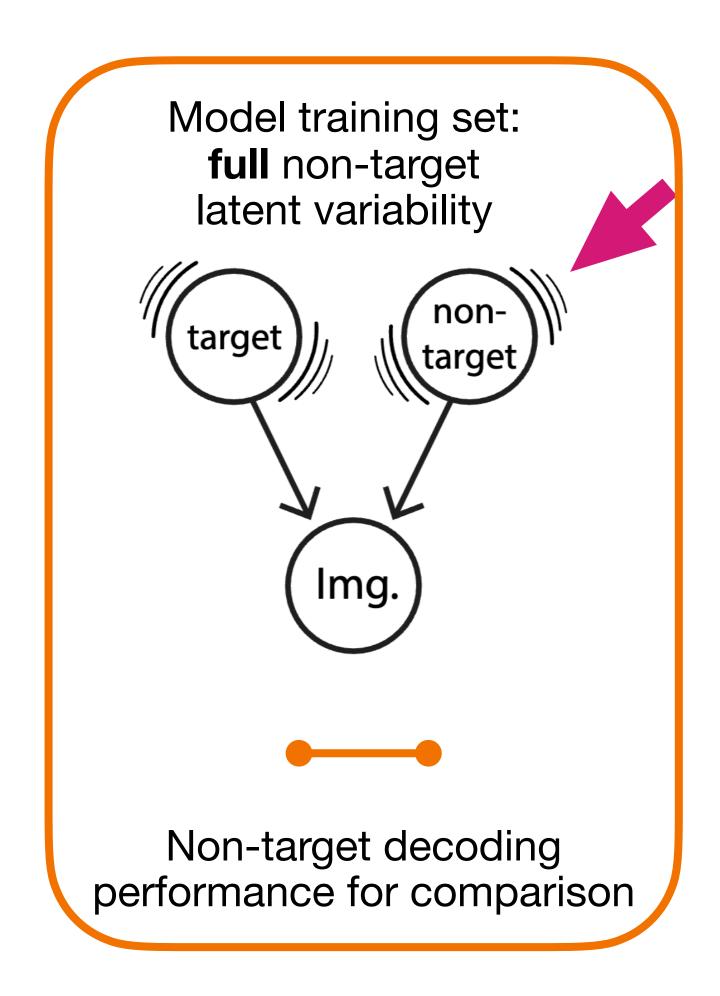
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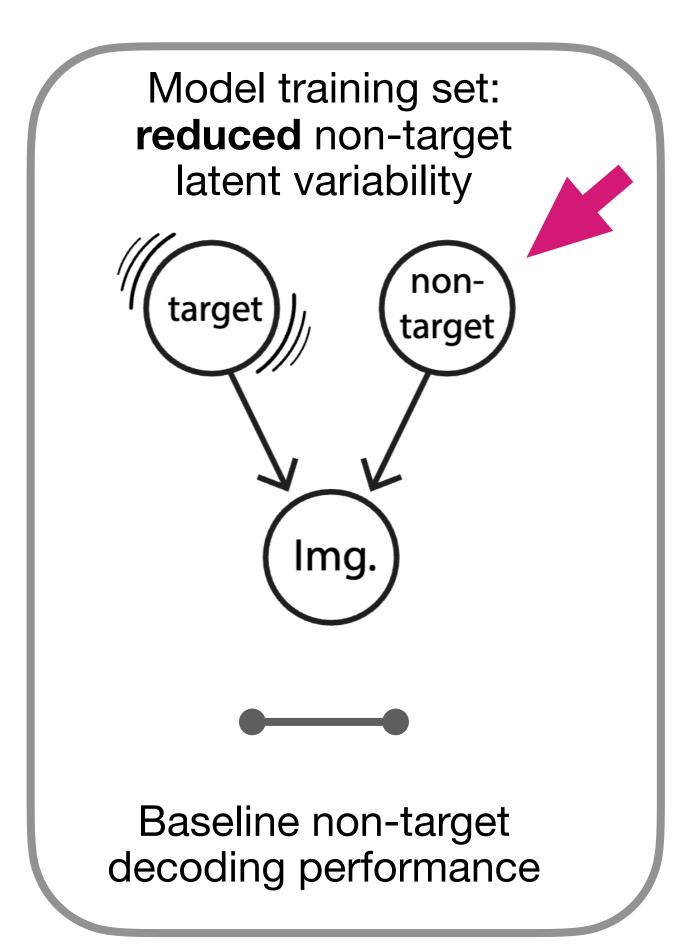
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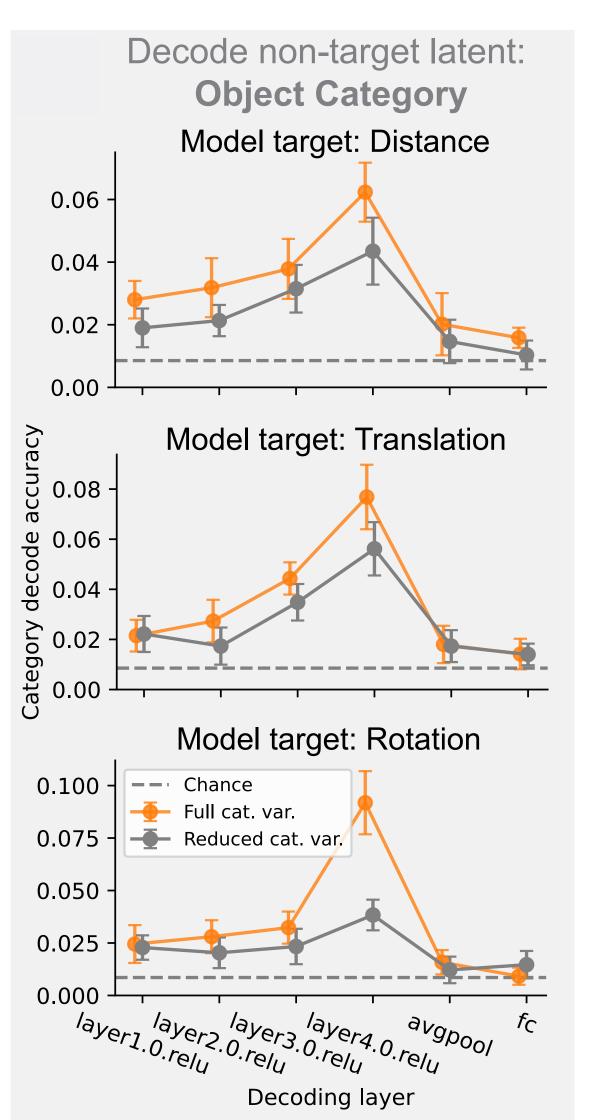


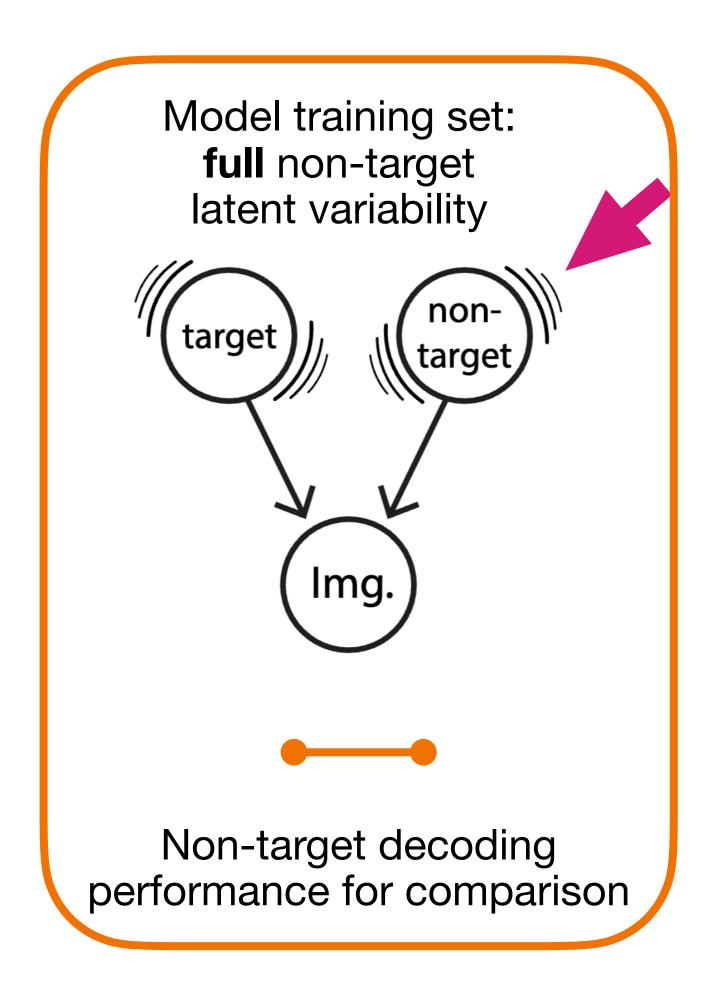
 As a model learns a single task, it simultaneously learns the structure of the world.

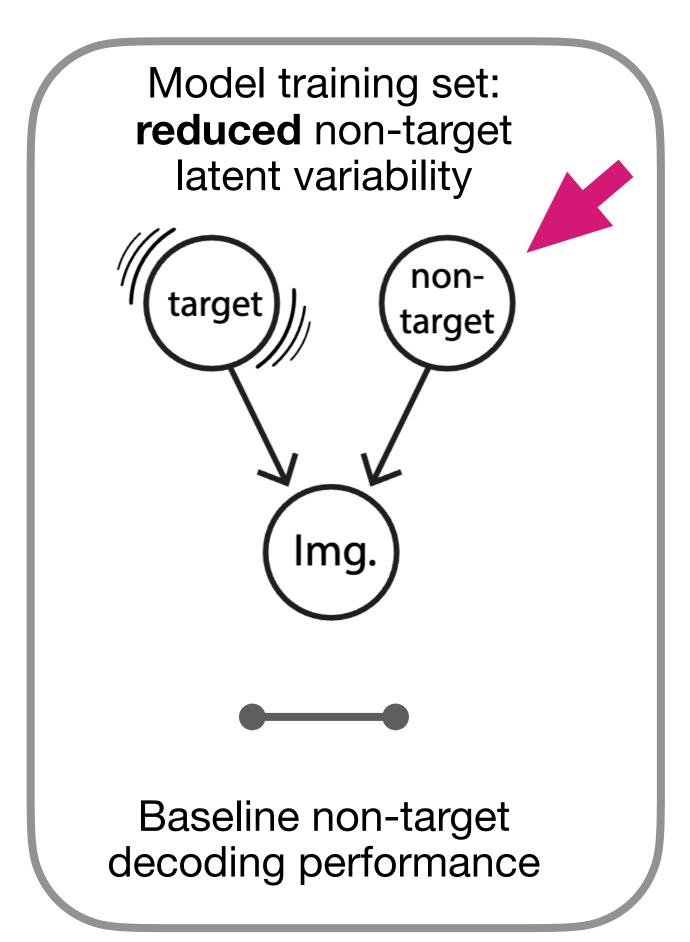


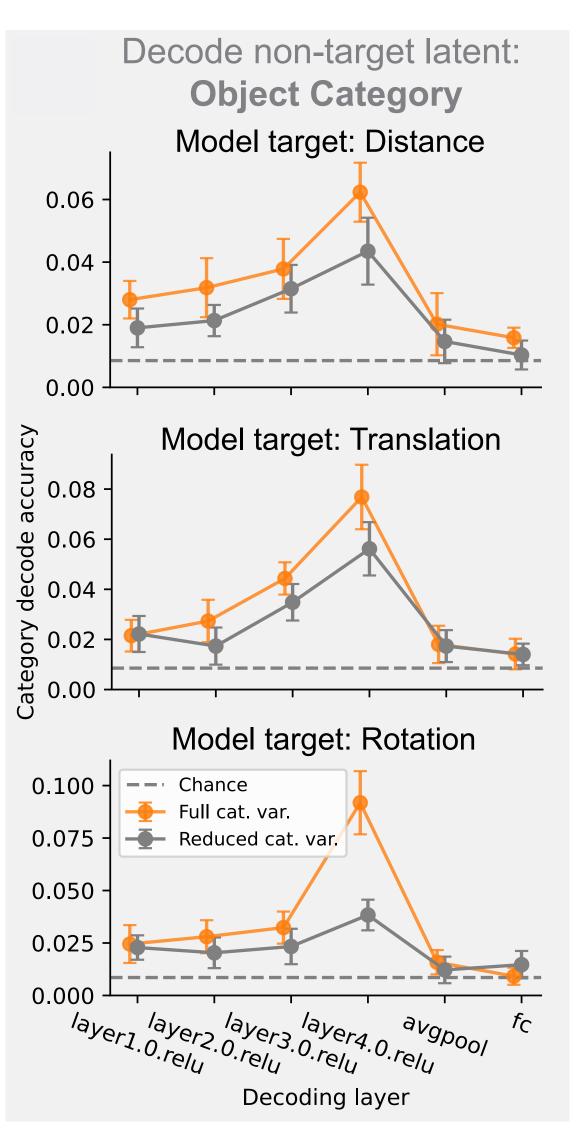


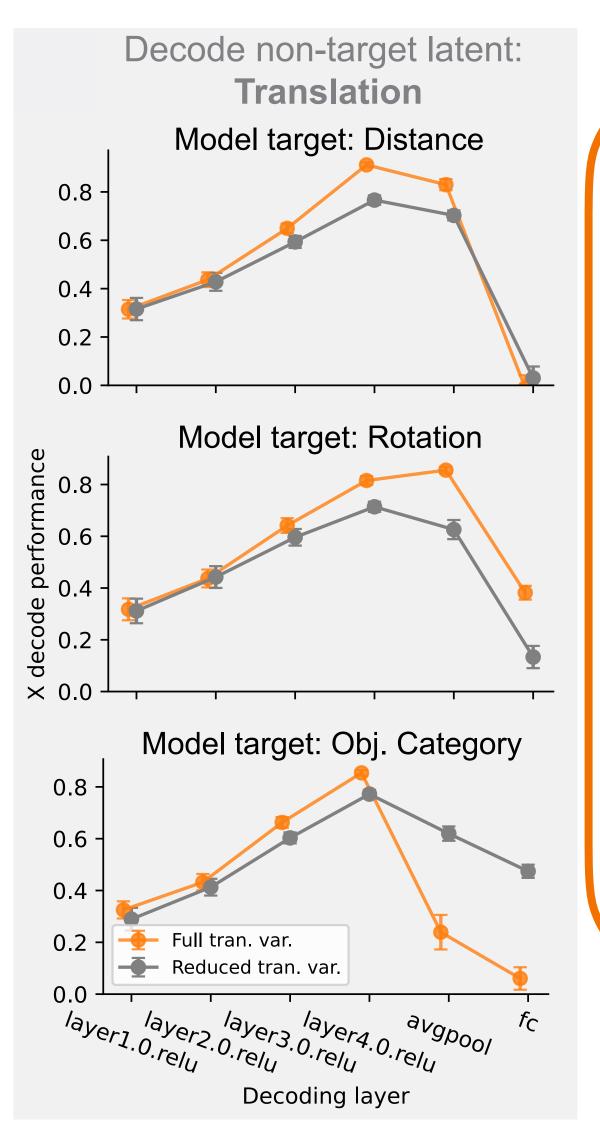


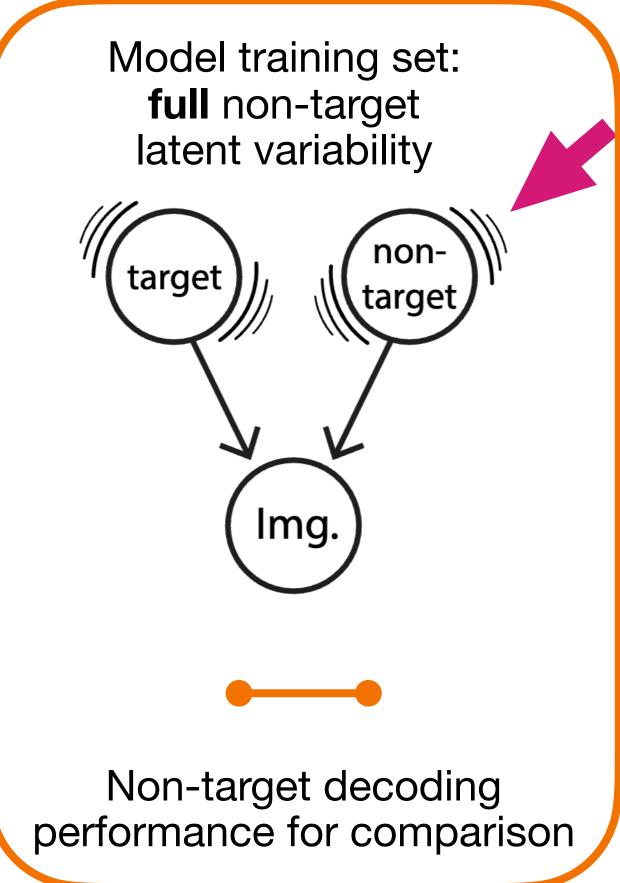


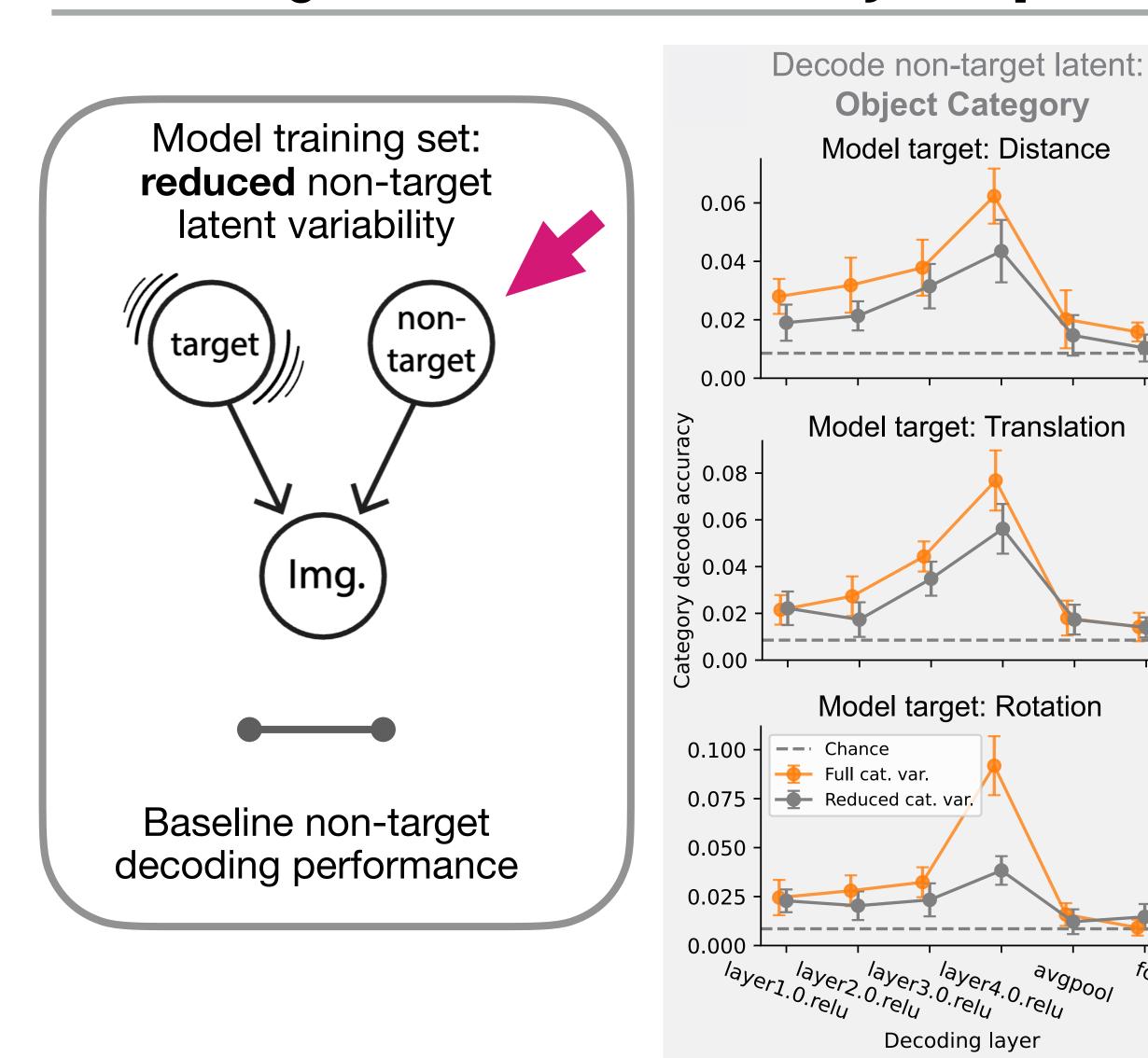


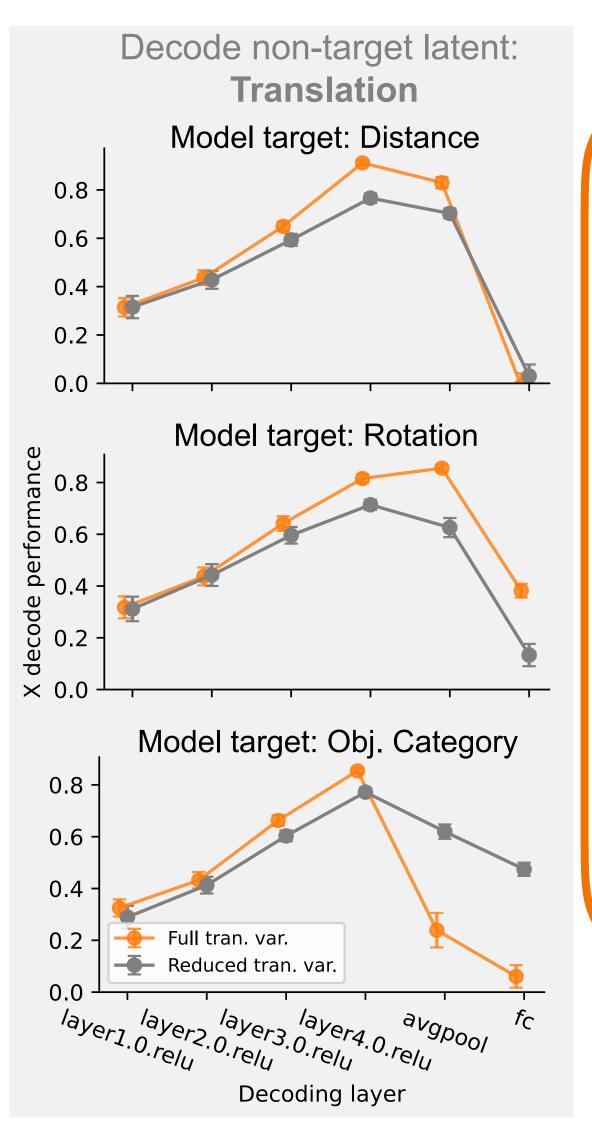


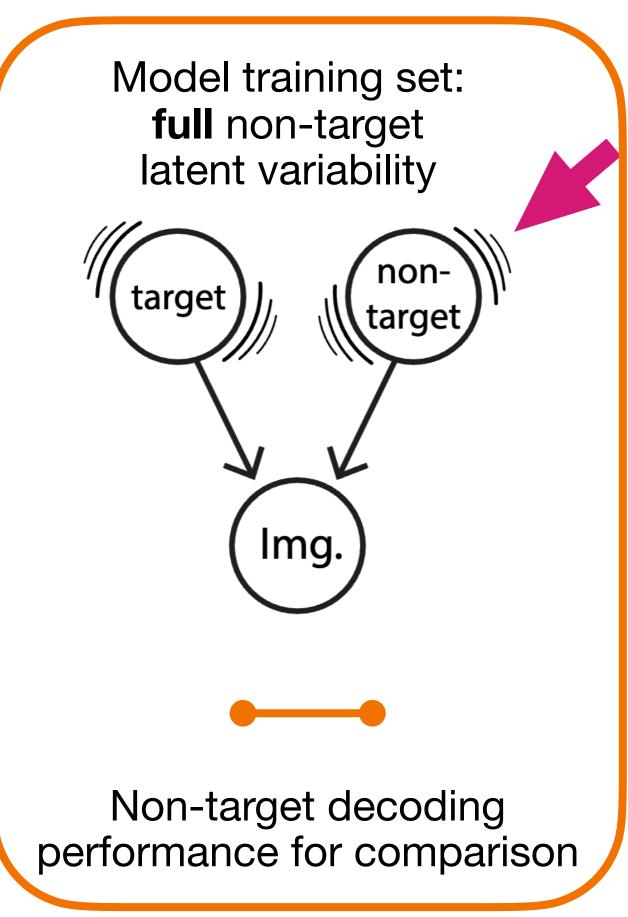












 Added variability of non-target latent helps models learn a better representation of non-target latents.

Acknowledgement



Weichen Huang



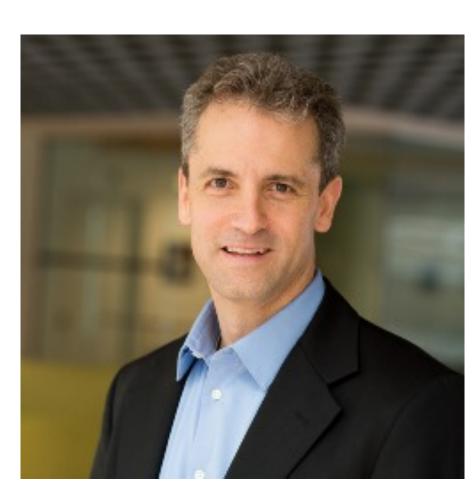
Esther Alter



Jeremy Schwartz



Josh Tenenbaum



James DiCarlo