Fengbo: a Clifford Neural Operator pipeline for 3D PDEs in Computational Fluid Dynamics

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Navier-Stokes Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \psi) = 0 \tag{1}$$

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$$\rho \frac{\partial \psi}{\partial t} + \rho (\psi \cdot \nabla) \psi = -\nabla \phi + \mu \nabla^2 \psi + \mathbf{f} \tag{2}$$

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Problem Statement

Estimate pressure field $\phi(\mathbf{x}):\Omega_D\subset\mathbb{R}^3\to\mathbb{R}$ and velocity field $\psi(\mathbf{x}):\Omega_D\subset\mathbb{R}^3\to\mathbb{R}^3$



Geometric Algebra Networks

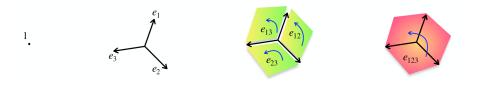


Figure 1: Elements of G(3,0,0), the 3D Euclidean space.

Fengbo

Why Hypercomplex Neural Networks in Geometric Algebra (GA)?

- Compact
- Interpretable
- Lower Complexity
- Better Generalisability

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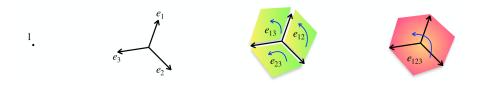


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We embed inputs (i.e. geometry) and outputs (i.e. physical quantities) as objects in G(3,0,0), known as multivectors.



Strategy: multivectors defined over regular grids

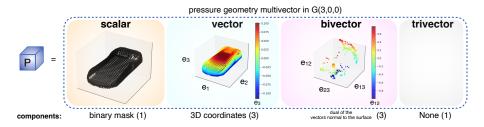


Figure 2: Input multivector P

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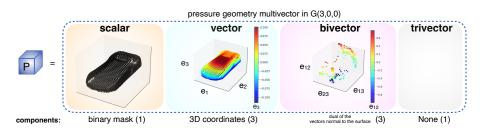


Figure 2: Input multivector P

Input: (geometry) multivector P $P = m_p + \mathbf{p} + B = \underbrace{m_p}_{\text{scalar}} + \underbrace{p_1 e_1 + p_2 e_2 + p_3 e_3}_{\text{vector}} + \underbrace{B_{12} e_{12} + B_{13} e_{13} + B_{23} e_{23}}_{\text{bivector}}$ (3)

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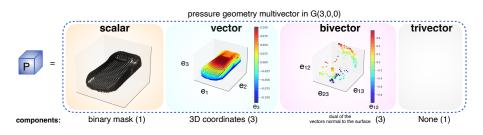


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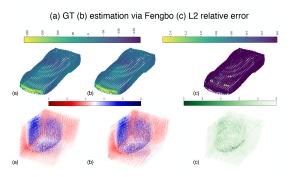


Figure 3: Estimated pressure and velocity fields ϕ, ψ for the *ShapeNet Car* dataset.

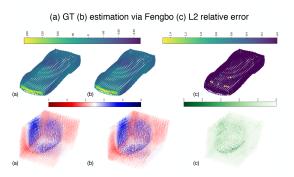
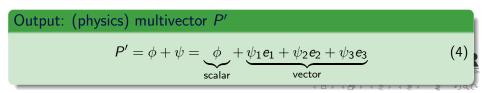


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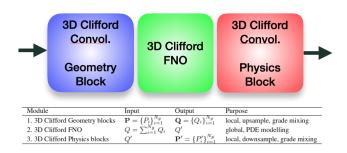


Figure 4: Fengbo $P' = \Xi(P)$

Reduced parameters and computational complexity.



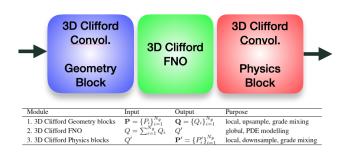


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- Reduced parameters and computational complexity.
- Lower test error than most NOs, robust to discretisation.



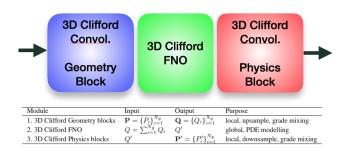


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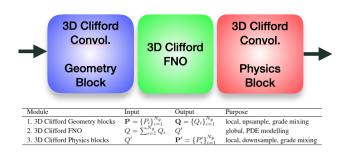


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- End-to-end interpretability.

