



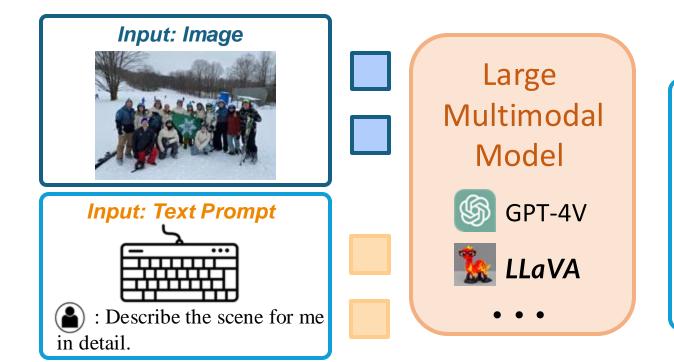
Matryoshka Multimodal Models

Mu Cai^{1,2}, Jianwei Yang², Jianfeng Gao², Yong Jae Lee¹





Most Large Multimodal Models are pretty good at understanding a standard-resolution image:



Output: Text Generation

A: There are a group of people standing in the ski facility, some of them are holding a green flag while other are ...

But this is far from practice



How can such multimodal systems be real-world assistants?



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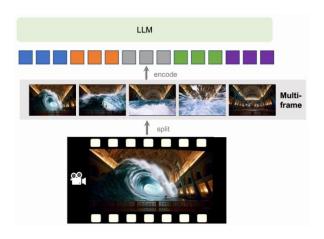


(a) High-resolution images (thousands of tokens)

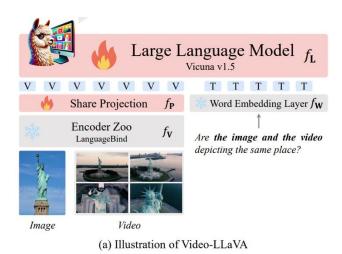


(b) Long videos(millions of tokens)

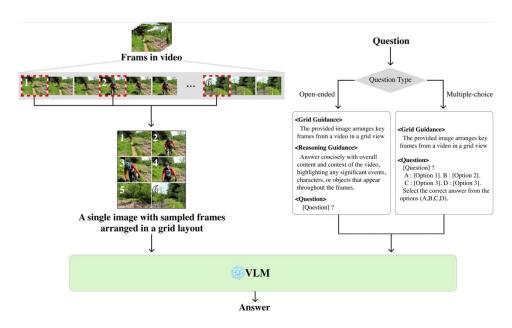
Bottleneck of Current Multimodal Models



(a) LLaVA-OneVision: 6272 visual tokens for 32 frames



(b) Video-LLaVA: 2048 visual tokens for 8 frames

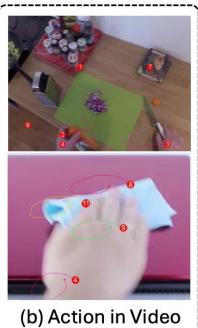


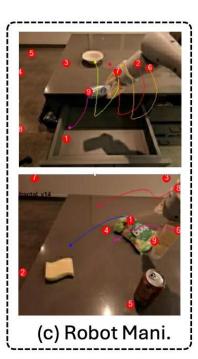
(c) IG-VLM: 2880 visual tokens for 6 frames

Too many tokens is a serious problem, especially for agentic systems.

Because long video understanding is the first step for multimodal agents!







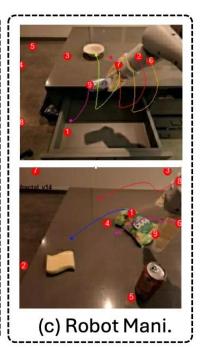


Too many tokens is the bottleneck of current multimodal system!

- **Inefficiency**, especially multimodal agents!
- **Distract** LMMs from focusing on the key information.









Matryoshka Multimodal Models

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Why content representation should be flexible?





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Image Complexity Varies







What do we really want for content representation?

• A versatile, flexible system that can represent visual content in diverse granularities!







What do we really want for content representation?

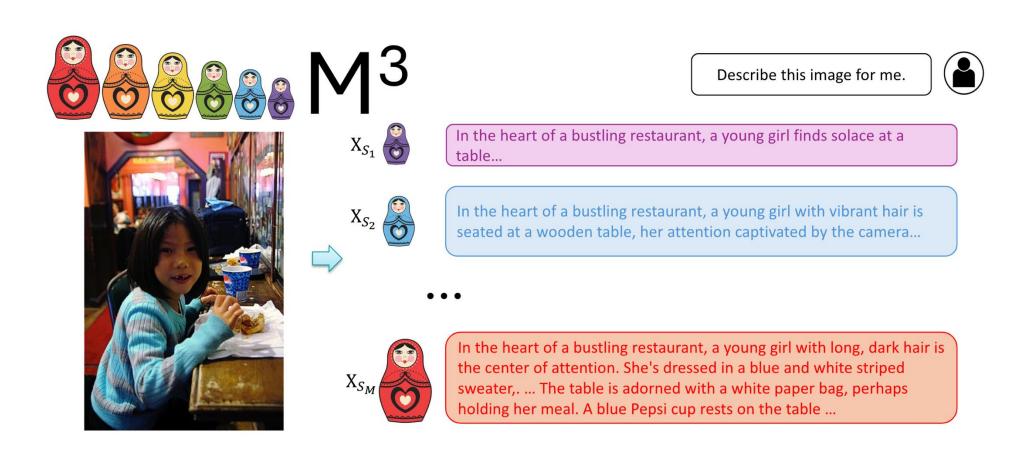
• A versatile, flexible system that can represent visual content in diverse granularities!

Merits:

- Users can manipulate how many tokens to use for a specific task.
- Increase the number of frames for video understanding.

Our Approach

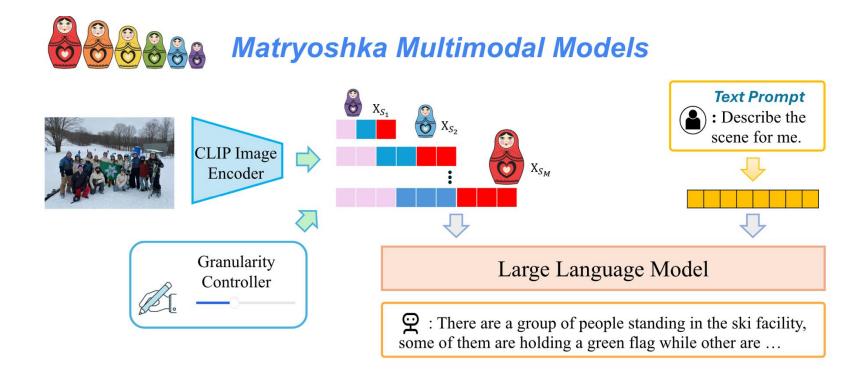
Represent visual features like Matryoshka dolls!



Ou Approach

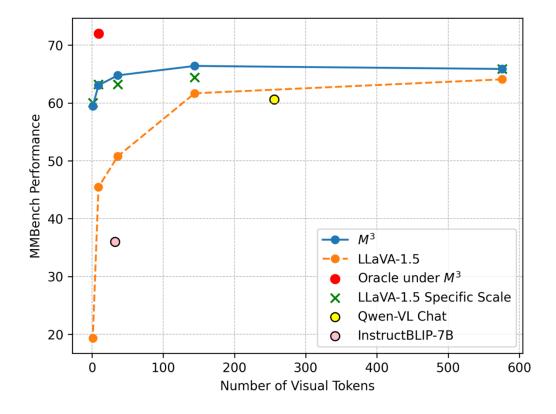
Extremely simple

- Exact LLaVA architecture, but gradually apply average pooling to the [H, W] visual features!
- Resulting in visual features with shape [H, W], $\left[\frac{H}{2}, \frac{W}{2}\right]$, $\left[\frac{H}{4}, \frac{W}{4}\right]$, ..., [1,1].
- Backpropagate the LLM loss upon all scales during training.



Now users can control how many tokens they want!

- In MMBench, we achieve comparable performance using 9 or 36 tokens instead of full tokens.
- We are at least better than the vanilla model (LLaVA) trained at a specific scale.



Different types of data prefer different number of visual tokens

• Documents need more tokens while COCO-style benchmarks need as few as 9~36 tokens.

Table: Performance of M3 on LLaVA-NeXT

| # Tokens Per Grid | Approach | TextVQA | AI2D | ChartQA | DocVQA | MMBench | POPE | ScienceQA | MMMU |
|----------------------|------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|
| 576 | $SS \ M^3$ | 64.53 63.13 | 64.83 66.71 | 59.28 58.96 | 75.40 72.61 | 66.58 67.96 | 87.02 87.20 | 72.29 72.46 | 34.3 34.0 |
| 144 | $SS \ M^3$ | 62.16 62.61 | 65.77 68.07 | 55.28 57.04 | 67.69 66.48 | 67.78 69.50 | 87.66 87.67 | 72.15 72.32 | 36.4 36.1 |
| 36 | $SS \ M^3$ | 58.15 58.71 | 65.90 67.36 | 45.40 50.24 | 56.89 55.94 | 67.01 68.56 | 86.75 87.29 | 71.87 72.11 | 36.2 36.8 |
| 9 | $SS \ M^3$ | 50.95 51.97 | 65.06 66.77 | 37.76 42.00 | 44.21 43.52 | 65.29 67.35 | 85.62 86.17 | 72.37 71.85 | 36.8 35.2 |
| 1 | $SS \ M^3$ | 38.39 38.92 | 63.76 64.57 | 28.96 31.04 | 33.11 31.63 | 61.43 62.97 | 82.83 83.38 | 72.32 71.19 | 35.3 34.8 |
| | | 260/ | | | | _/10/2 | | | |

-26%

Most video benchmarks achieve similar accuracies with 1.6% tokens...

- We can prune visual token more than we imagined
- Using full tokens does not always result in best performance

| Approach | # Tokens | MSVD | MSRVTT | ActivityNet | NextQA | IntentQA | EgoSchema |
|------------------------------|----------|------|--------|-------------|--------|----------|-----------|
| Video-LLaMA [11] | 32 | 51.6 | 29.6 | 12.4 | - | - | - |
| LLaMA-Adapter [62] | _ | 54.9 | 43.8 | 34.2 | - | - | - |
| Video-ChatGPT [63] | 264+ | 64.9 | 49.3 | 35.2 | - | - | - |
| Video-LLaVA [64] | 2048 | 70.7 | 59.2 | 45.3 | - | - | - |
| InternVideo [65] | - | - | - | - | 59.1 | - | 32.1 |
| LLaVA-NeXT-7B [4] | 2880 | 78.8 | 63.7 | 54.3 | 63.1 | 60.3 | 35.8 |
| | 2880 | 78.2 | 64.5 | 53.9 | 63.1 | 58.8 | 36.8 |
| | 720 | 79.0 | 64.5 | 55.0 | 62.6 | 59.6 | 37.2 |
| LLaVA-NeXT-7B-M ³ | 180 | 77.9 | 63.7 | 55.0 | 61.4 | 59.3 | 37.6 |
| | 45 | 75.8 | 63.0 | 53.2 | 59.5 | 58.7 | 38.8 |
| | 5 | 73.5 | 62.7 | 50.8 | 56.5 | 56.7 | 36.2 |

Most video benchmarks achieve similar accuracies with 1.6% tokens...

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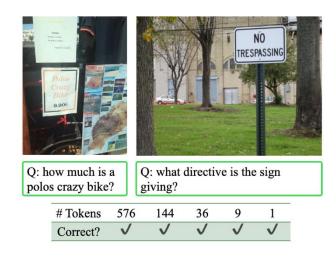
Or such video benchmarks are not really evaluating video understanding?

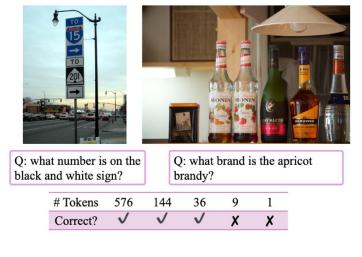


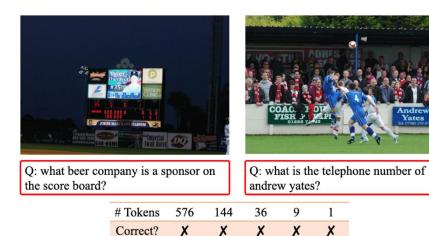
We propose **TemporalBench** and **Vinoground** to solve this problem.

Good side-effect:

• M3 serving as an image complexity evaluator.



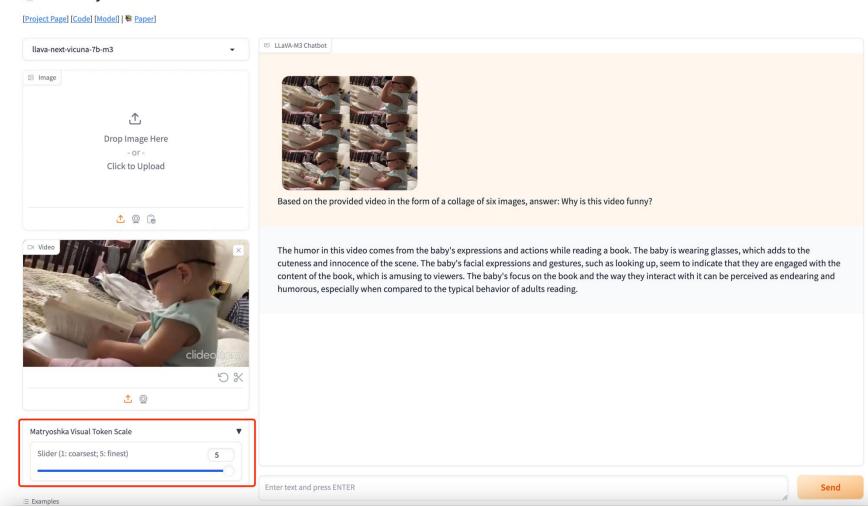




Demo

https://pages.cs.wisc.edu/~mucai/matryoshka-mm.html

M3: Matryoshka Multimodal Models



Impact

Matryoshka has already ignited many interesting tasks, such as (1) Matryoshka VQVAE.

ADAPTIVE LENGTH IMAGE TOKENIZATION VIA RECURRENT ALLOCATION

Shivam Duggal Phillip Isola Antonio Torralba William T. Freeman MIT CSAIL

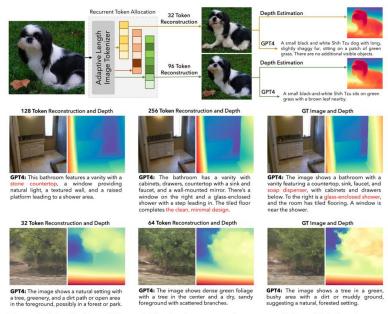


Figure 1: Adaptive Length Image Tokenization maps an image to multiple variable-length representations through a recurrent token allocation process, enabling task-specific sampling. We learn the tokenizer via image reconstruction as a self-supervised objective. While a compressed representation can be optimized for specific tasks (e.g., fewer tokens for "dog", "leaf", "grass" may suffice for a VLM task), reconstruction objective supports learning a universal, task-agnostic tokenizer.

CAT: Content-Adaptive Image Tokenization

Junhong Shen^{1*} Kushal Tirumala² Michihiro Yasunaga² Ishan Misra² Luke Zettlemoyer² Lili Yu^{2†} Chunting Zhou^{†‡}

¹ Carnegie Mellon University ² Meta

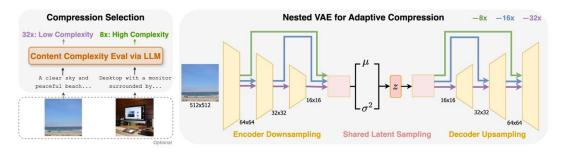


Figure 1. **Content-Adaptive Tokenization.** CAT uses an LLM to evaluate the content complexity and determine the optimal compression ratio based on the image's text description. The image is processed by a nested VAE architecture that dynamically routes the input according to the selected compression ratio. The resulting latent representations thus have varying spatial dimensions. Images shown in the figure are taken from COCO 2014 [9].



Thanks for Listening!

Looking forward to any comment!



THANK YOU!

Mu CAI, UW-Madison CS

