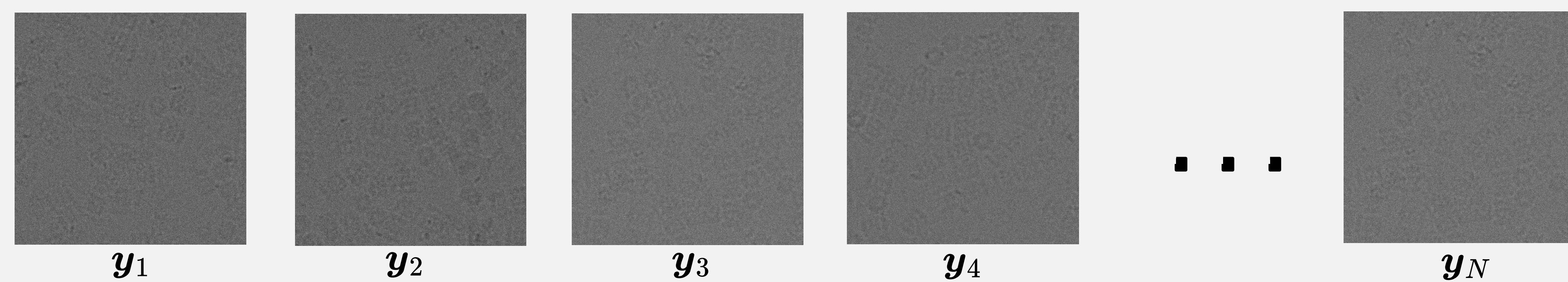


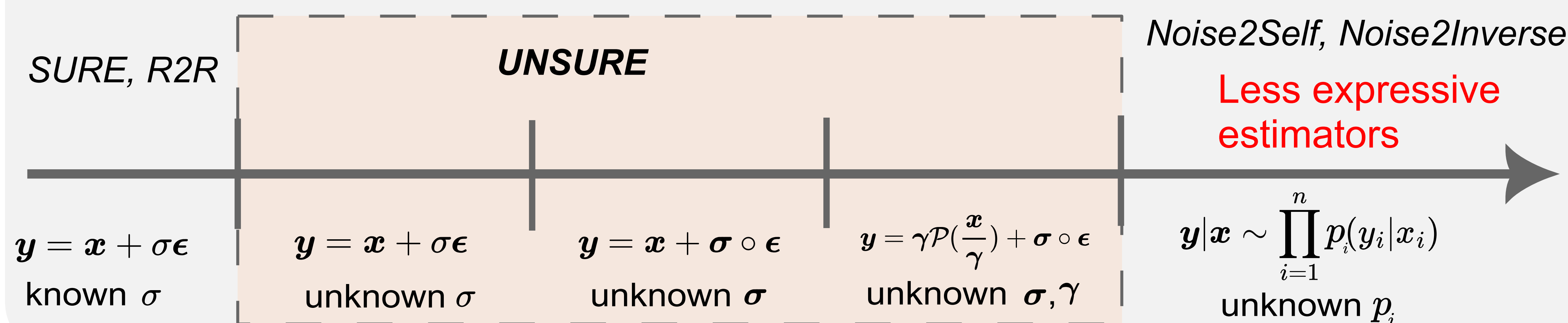
# UNSURE: self-supervised learning with Unknown Noise level Stein's Unbiased Risk Estimate

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**Q.** What can we learn from **noisy images alone**?



**A.** Depends on knowledge about the **noise distribution**

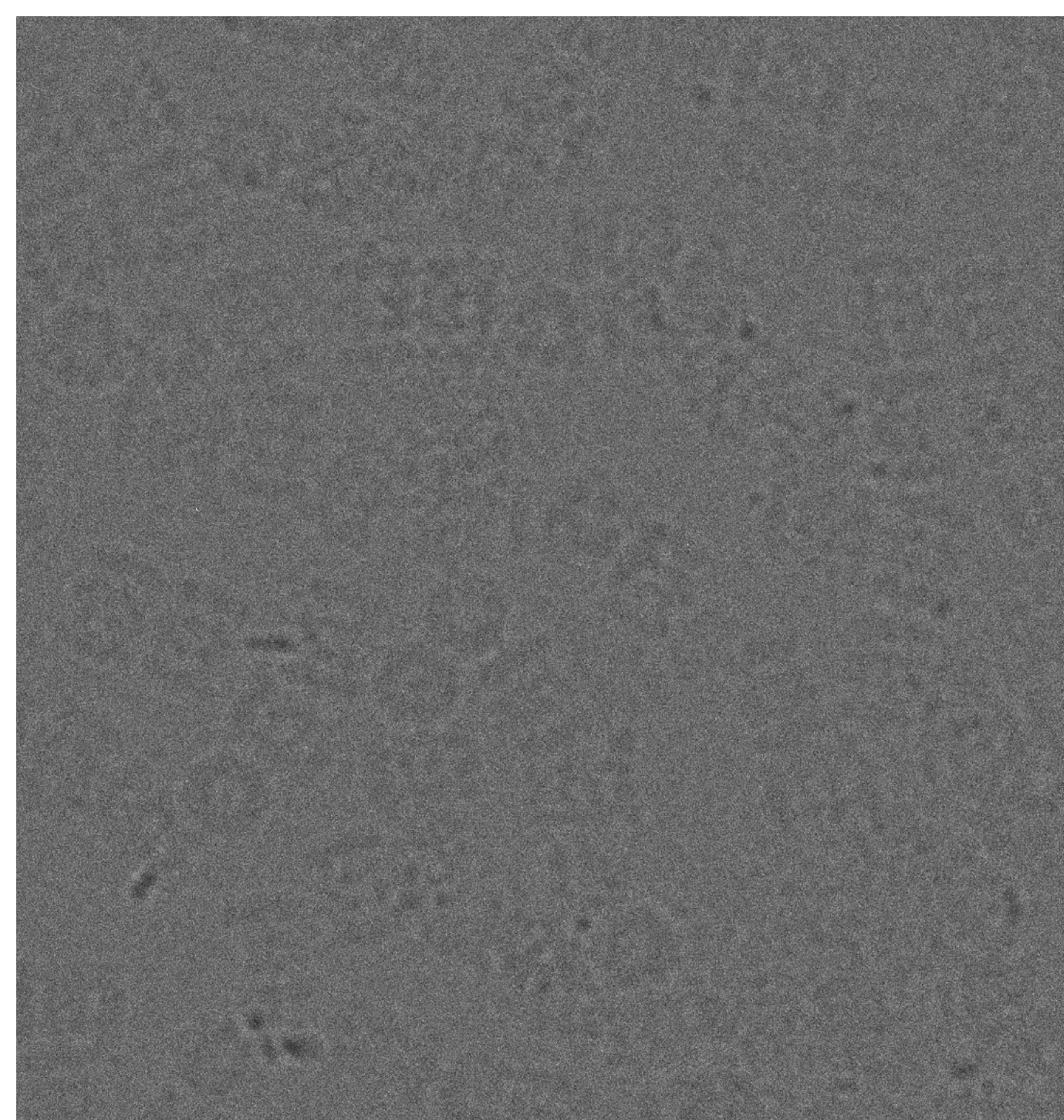


Experiments

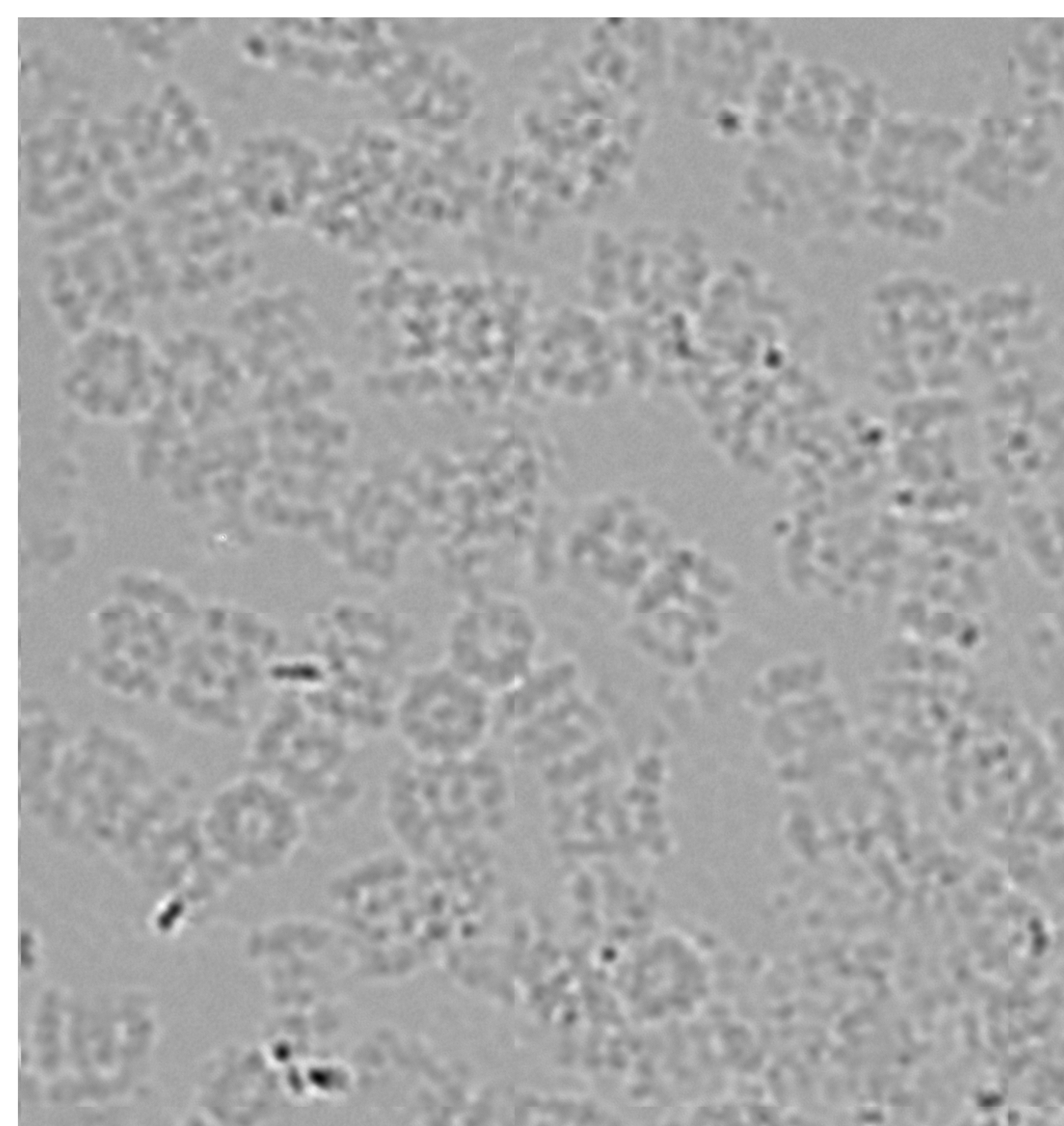


PSNR [dB] in yellow

Real Cryo-EM data



UNSURE



**Q.** What **loss** should I minimize?

**A.** Consistency with constraints

$$\min_f \mathbb{E}_{\mathbf{y}} \|\mathbf{f}(\mathbf{y}) - \mathbf{y}\|^2 \text{ s.t. constraint } \mathbf{f} = 0$$

a) Gaussian noise unknown  $\sigma$

$$\sum_{i=1}^n \mathbb{E}_{\mathbf{y}} \frac{\partial f_i}{\partial y_i}(\mathbf{y}) = 0$$

b) Poisson Gaussian unknown  $(\sigma, \gamma)$

$$\sum_{i=1}^n \mathbb{E}_{\mathbf{y}} \frac{\partial f_i}{\partial y_i}(\mathbf{y}) = 0 \quad \sum_{i=1}^n y_i \frac{\partial f_i}{\partial y_i}(\mathbf{y}) = 0$$

c) Gaussian noise unknown  $\Sigma$

$$\text{Possible covariances: } \{\Sigma = \sum_{j=1}^J \eta_j \Psi_j, \eta \in \mathbb{R}^J\}$$

$$\mathbb{E}_{\mathbf{y}} \text{tr}(\Psi_j \nabla f(\mathbf{y})) = 0 \text{ for } j = 1, \dots, J$$

d) Other models ... (see paper)

**Q.** Why these losses?

**A.** Because of SURE

$$\min_f \mathbb{E}_{\mathbf{y}} \|\mathbf{f}(\mathbf{y}) - \mathbf{y}\|^2 + 2\sigma^2 \sum_{i=1}^n \mathbb{E}_{\mathbf{y}} \frac{\partial f}{\partial y_i}(\mathbf{y})$$

**Q.** What's the **performance**?

**A.** Almost as supervised

a) Generalization of Tweedie

$$\mathbf{f}(\mathbf{y}) = \mathbf{y} + \frac{n \nabla \log p(\mathbf{y})}{\mathbb{E}_{\mathbf{y}} \|\nabla \log p(\mathbf{y})\|^2}$$

b) Expected performance

$$\mathbb{E}_{\mathbf{x}, \mathbf{y}} \frac{1}{n} \|\mathbf{f}(\mathbf{y}) - \mathbf{x}\|^2 = \text{MMSE} + \sigma^2 \sum_{j=2}^{\infty} \left( \frac{\text{MMSE}}{\sigma^2} \right)^j.$$

c) Upper bound noise level

$$\frac{n}{\mathbb{E}_{\mathbf{y}} \|\nabla \log p(\mathbf{y})\|^2} = \frac{\sigma^2}{1 - \frac{\text{MMSE}}{\sigma^2}} \geq \sigma^2$$

**Q.** Implementation?

**A.** Lagrange multipliers

$$\min_f \max_{\eta} \mathbb{E}_{\mathbf{y}} \|\mathbf{f}(\mathbf{y}) - \mathbf{y}\|^2 + 2 \text{tr} \left( \Sigma_{\eta} \frac{\partial f}{\partial \mathbf{y}}(\mathbf{y}) \right)$$

Divergence approximation

$$\mathbf{b} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}) \quad 0 < \tau \ll 1$$

$$\text{tr} \left( \Sigma_{\eta} \frac{\partial f}{\partial \mathbf{y}}(\mathbf{y}) \right) \approx \frac{(\Sigma_{\eta} \mathbf{b})^{\top}}{\tau} (f(\mathbf{y} + \tau \mathbf{b}) - f(\mathbf{y}))$$

**Algorithm 1** UNSURE loss.

**Require:** step size  $\alpha$ , momentum  $\mu$   
 residual  $\leftarrow \|\mathbf{f}_{\theta}(\mathbf{y}) - \mathbf{y}\|^2$   
 $\mathbf{b} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$   
 div  $\leftarrow \frac{(\Sigma_{\eta} \mathbf{b})^{\top}}{\tau} (f_{\theta}(\mathbf{y} + \tau \mathbf{b}) - f_{\theta}(\mathbf{y}))$   
 loss  $\leftarrow$  residual + div  
 $\mathbf{g} \leftarrow \mu \mathbf{g} + (1 - \mu) \frac{\partial \text{div}}{\partial \eta}$  **Added lines vs SURE**  
 $\eta \leftarrow \eta + \alpha \mathbf{g}$   
**return** loss( $\theta$ )

Correlated Gaussian Noise

