

Can Reinforcement Learning Solve Asymmetric Combinatorial-Continuous Zero-Sum Games?

ICLR 2025

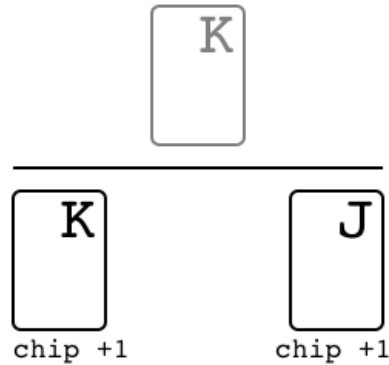
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Motivation



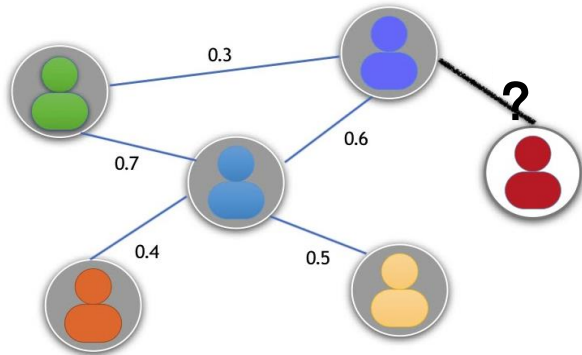
Board Game



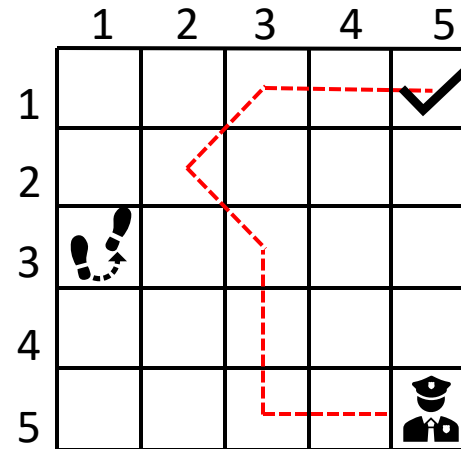
Leduc Poker

		WOMAN	
		Boxing	Shopping
MAN	Boxing	<u>2, 1</u>	0, 0
	Shopping	0, 0	<u>1, 2</u>

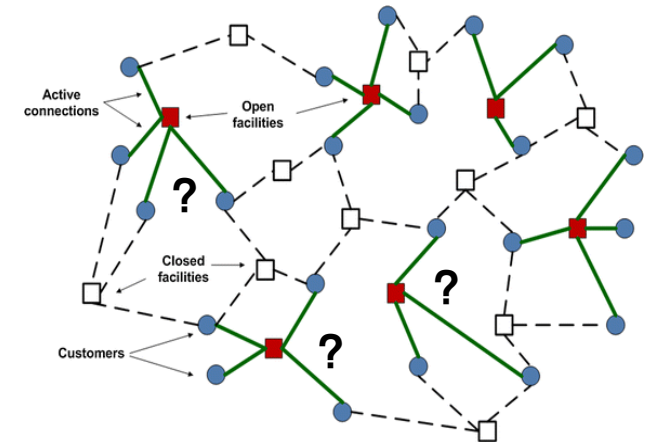
Battle of the Sexes game



Influence Maximization with uncertain weights



Patrolling Game



Facility location under unknown effect

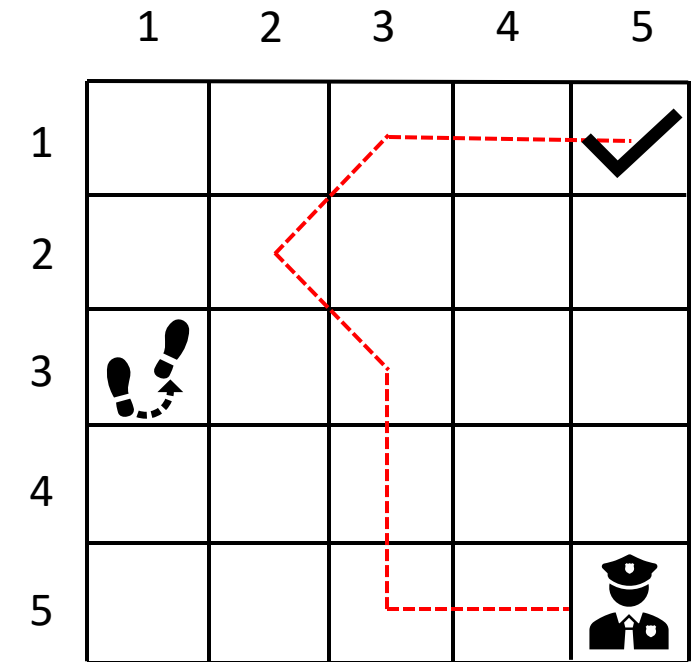
No Game Definition on these games!

What's the Asymmetric Combinatorial-Continuous zEro-Sum (ACCES) Game?

- Player 1: **Combinatorial** strategy space
- Player 2: **Infinite and compact** strategy space with a continuous utility function

Ep. Patrolling Game,

- Player 1: defender, choosing a **feasible constrained route** to patrol.
- Player 2: attacker, deciding the **attack probability** for targets.
- Utility function: the expectation of successfully protected target values

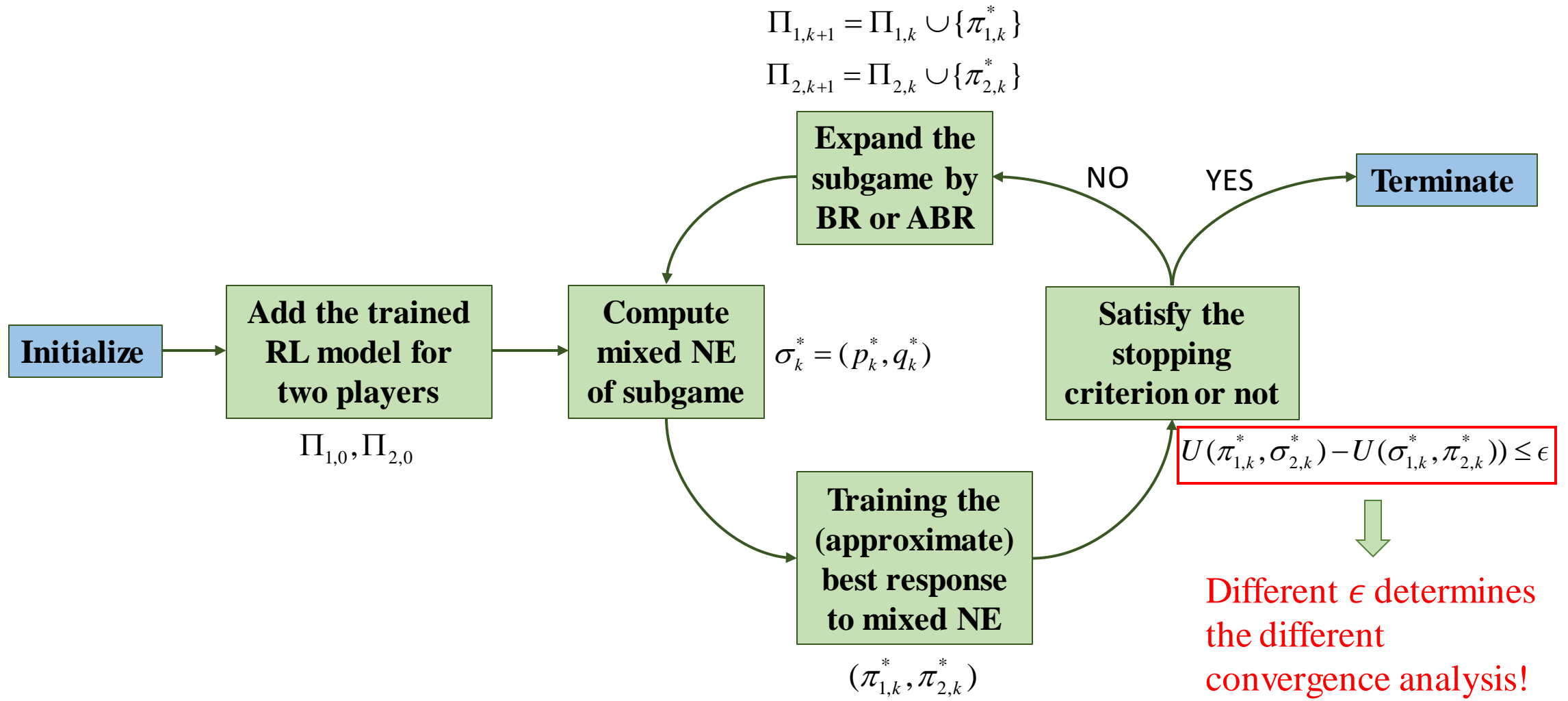


Patrolling Game

Contributions

1. Summarize and define the ACCES game
2. The **existence of mixed NE** in ACCES games
3. **CCDO & CCDO-RL Framework**
 - Novel Convergence Guarantee
 - First practical algorithm to solve ACCES games
4. **Empirical evaluations** on three instances

CCDO & CCDO-RL Framework



CCDO & CCDO-RL Convergence Analysis

- **Existence of NE (Theorem 1):**

The ACCES game has a mixed strategy Nash Equilibrium.

- **CCDO Convergence Analysis (Theorem 2):**

1. When the stopping criterion $\epsilon = 0$, CCDO possibly iterates in an infinite number of iterations. However, every weakly convergent subsequence in the **subgame equilibrium sequence** $\{p_k^*, q_k^*\}$ converges to **the equilibrium of the whole game**.
2. When the stopping criterion $\epsilon > 0$, CCDO converges to an **ϵ -equilibrium** in a finite number of epochs.

CCDO & CCDO-RL Convergence Analysis

- **CCDO-RL Convergence Analysis (Theorem 3):**

1. When the stopping criterion $\epsilon = 0$, if the approximate response oracle for Player 2 has a **uniform lower bound** for every mixed strategy, then CCDO-RL must converge to an $(\epsilon + \epsilon_1 + \epsilon_2)$ -**equilibrium** in a finite iterations.
2. When the stopping criterion $\epsilon = 0$ and CCDO-RL iterates **infinite** rounds, every weakly convergent subsequence converges to an ϵ_1 - **equilibrium**.
3. When the stopping criterion $\epsilon > 0$, CCDO-RL converges to an $(\epsilon + \epsilon_1 + \epsilon_2)$ -**equilibrium** in a finite number of epochs.

ϵ_1 and ϵ_2 are the approximate error bound of approximate best responses for Player 1 and 2 respectively.

Experiments

In three instances under two types of adversary,

CCDO-RL and stochastic adversary, CCDO-RL has

- **Better average reward on seen graphs.**
- **Greater generalizability on unseen graphs.**

Table 1: Average reward against CCDO-RL's adversary (on seen graphs)

method	ACSP (Mean±Std)		ACVRP (Mean±Std)		PG (Mean±Std)	
	20 nodes	50 nodes	20 nodes	50 nodes	20 nodes	50 nodes
Heuristic	6.13±1.20	7.55±1.42	7.65±1.23	13.38±1.70	2.64±1.03	4.53±1.84
RL against Stoc	3.50±0.47	4.55±0.62	7.55±1.16	13.90±1.63	2.71±0.90	4.80±2.18
CCDO-RL	3.25±0.42	4.31±0.51	7.42±1.21	13.28±1.52	2.75±0.87	5.01±1.91

Table 2: Generalizability against CCDO-RL's adversary (on unseen graphs)

method	ACSP (Mean±Std)		ACVRP (Mean±Std)		PG (Mean±Std)	
	20 nodes	50 nodes	20 nodes	50 nodes	20 nodes	50 nodes
Heuristic	6.20±1.33	7.60±1.37	7.64±1.30	13.27±1.87	2.43±0.98	4.19±1.69
RL against Stoc	3.56±0.37	4.57±0.58	7.67±1.30	13.85±1.53	2.50±0.95	4.26±2.17
CCDO-RL	3.31±0.35	4.39±0.52	7.55±1.28	13.15±1.59	2.56±0.92	4.70±1.94

¹ For the average reward of ACSP and ACVRP, smaller is better while for that of PG larger is better.