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DICE: Data Influence Cascade in Decentralized Learning

Speaker: Tongtian Zhu



Cascade

Collaborators



Many thanks to collaborators!



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Zhejiang University



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Zhejiang University



Can Wang
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Fengxiang He
The University of Edinburgh

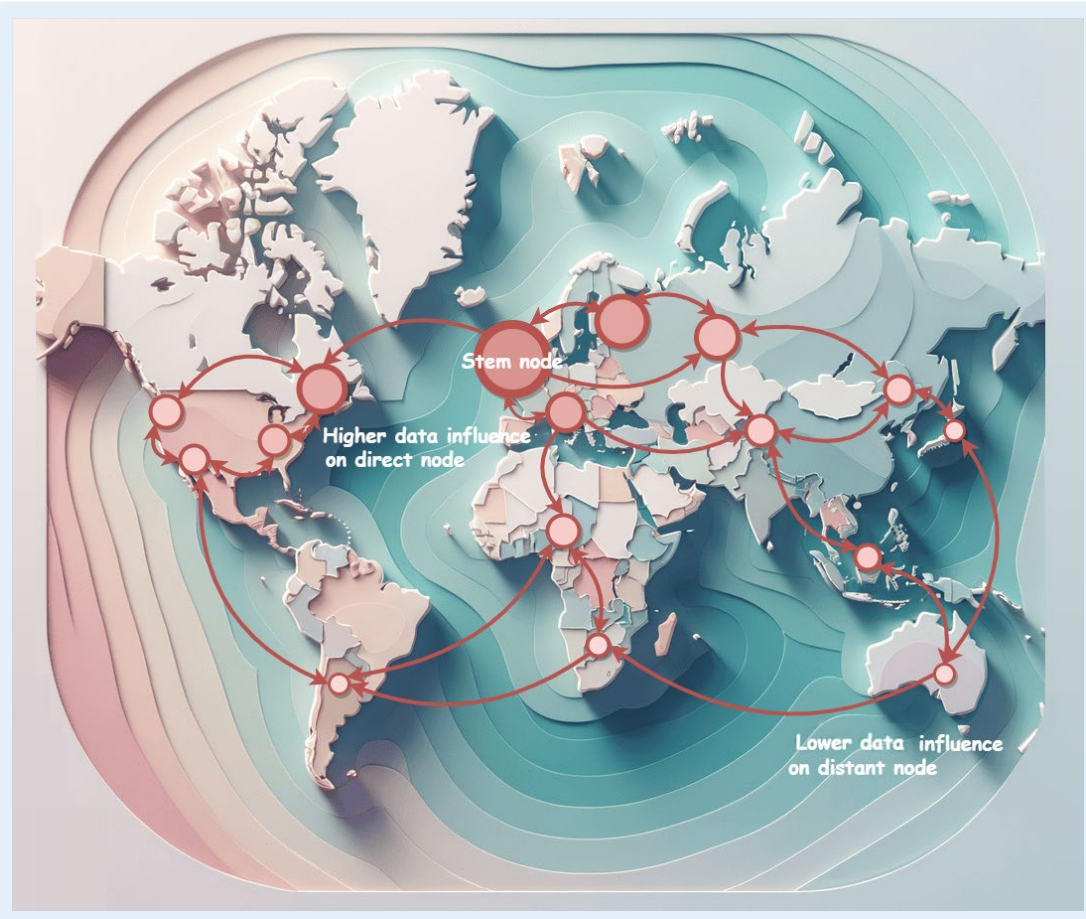
Main Results



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Data Influence Cascade in Decentralized Learning



What scientific problem does this paper study?

Q: In decentralized financial systems, proof of work (PoW) ensures security and consensus through computational effort. How can PoW be formally defined and quantified in the context of decentralized distributed machine learning?

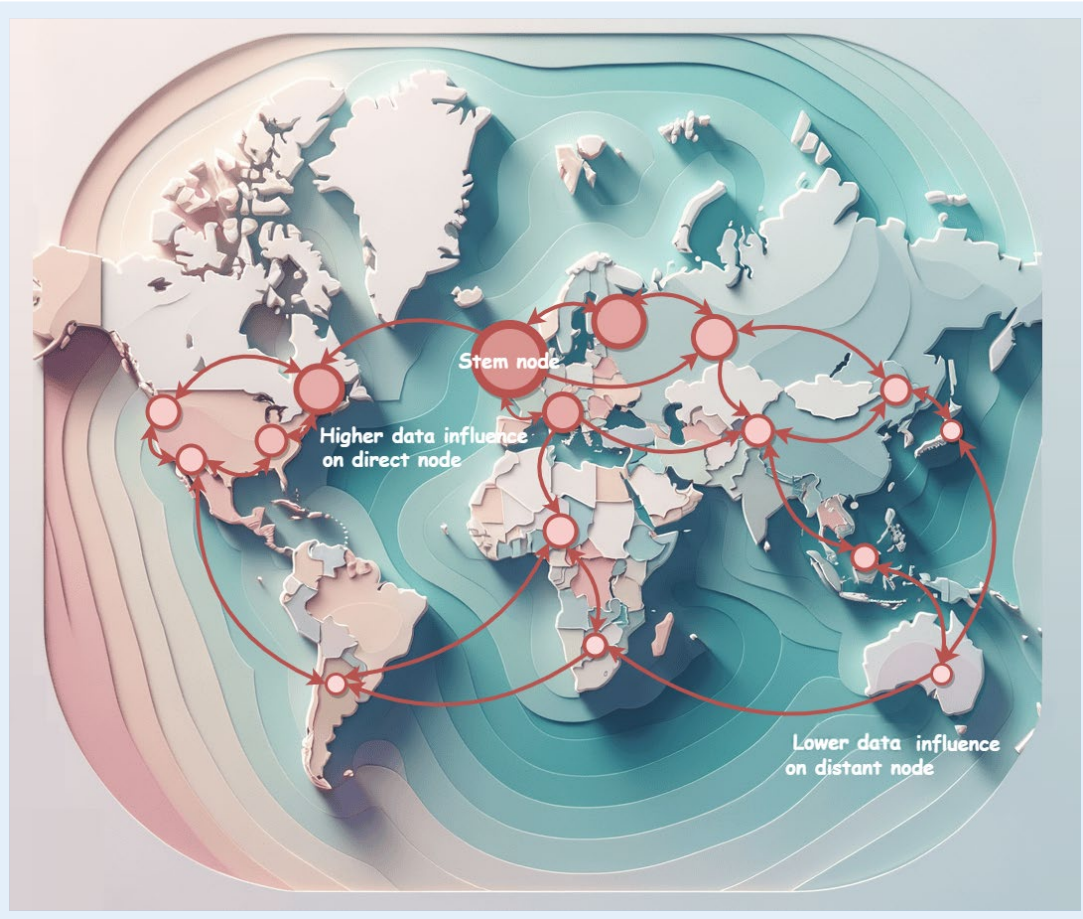
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The influence of data “cascades” through the communication graph, resembling “ripples in water”.

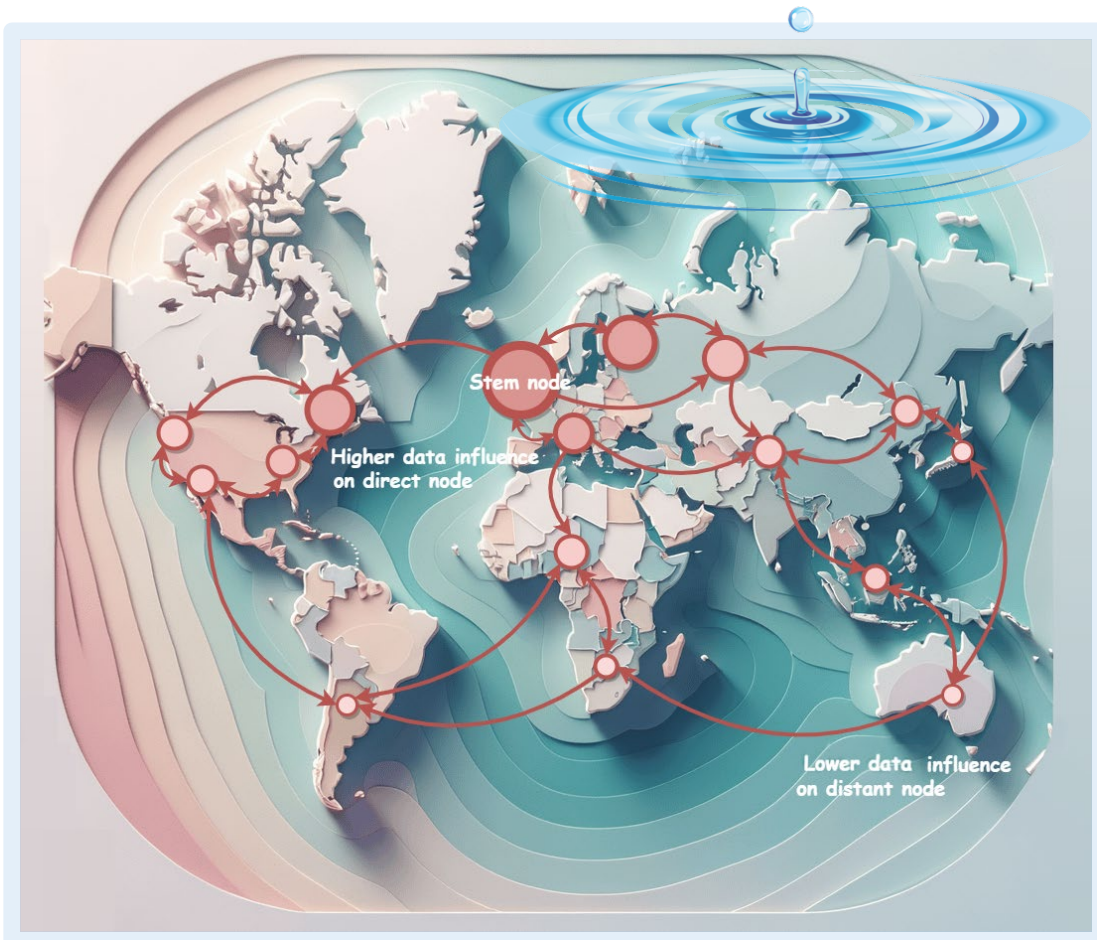
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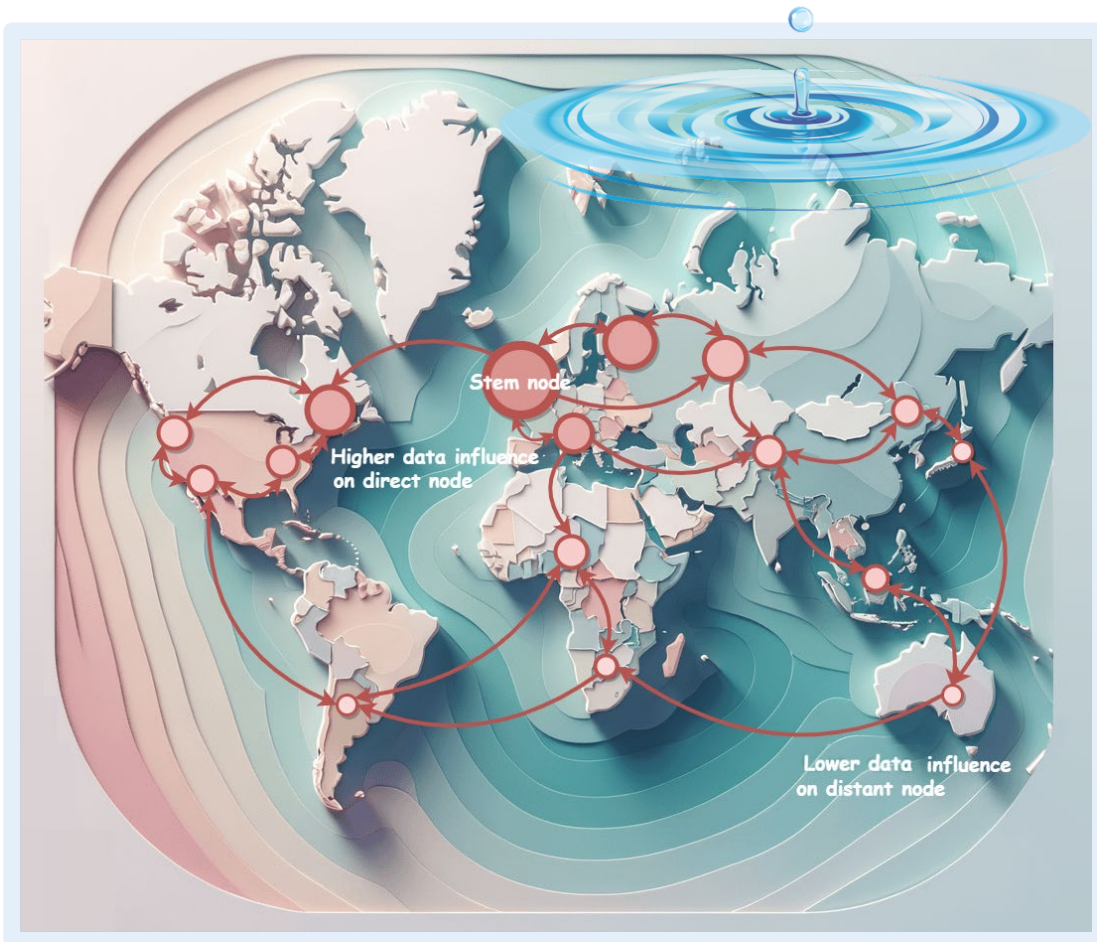
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In decentralized learning, the influence of data “cascades” through the communication graph, resembling “ripples in water”.



This influence is determined by both the original data and the **topological position of the data-holding node** within the communication network.

Intuition?

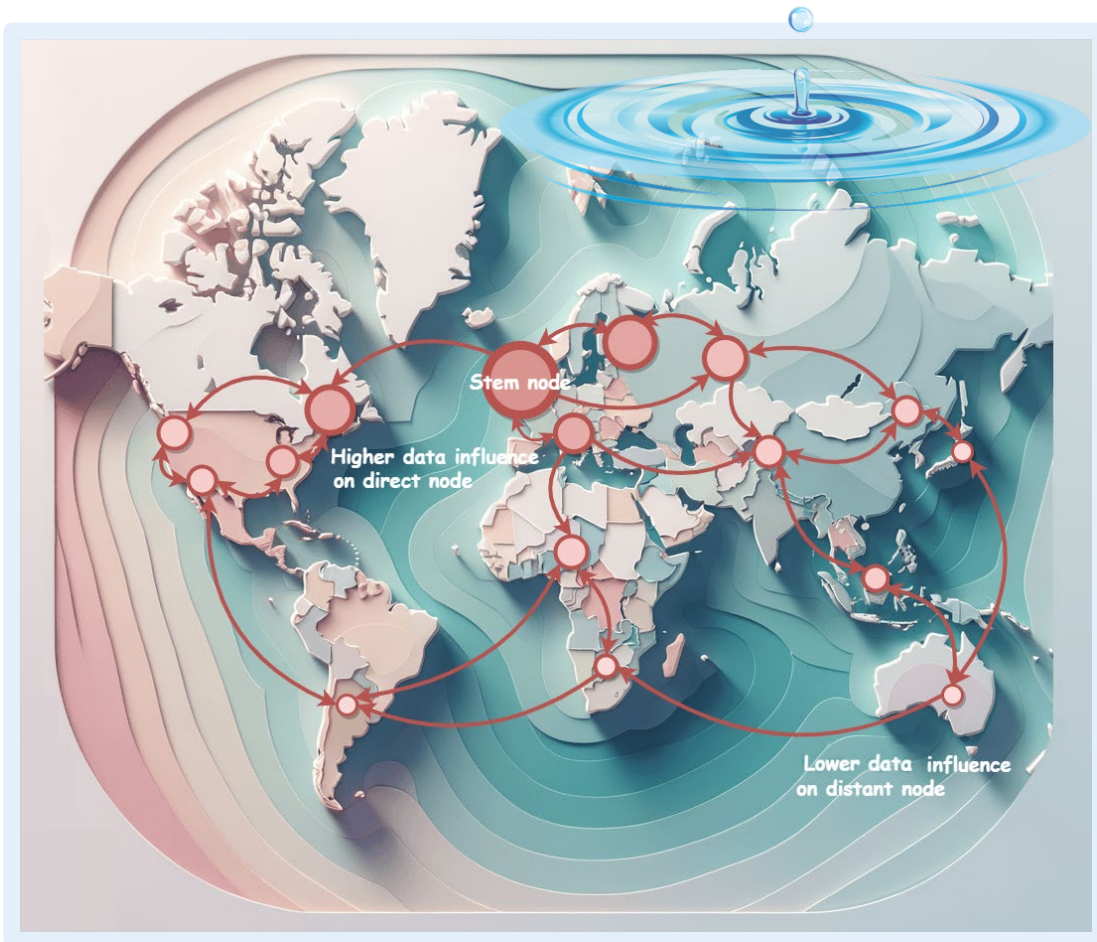
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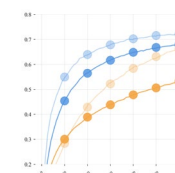


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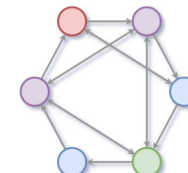
Intuition



Training data



Make influence



Communication



Cascade

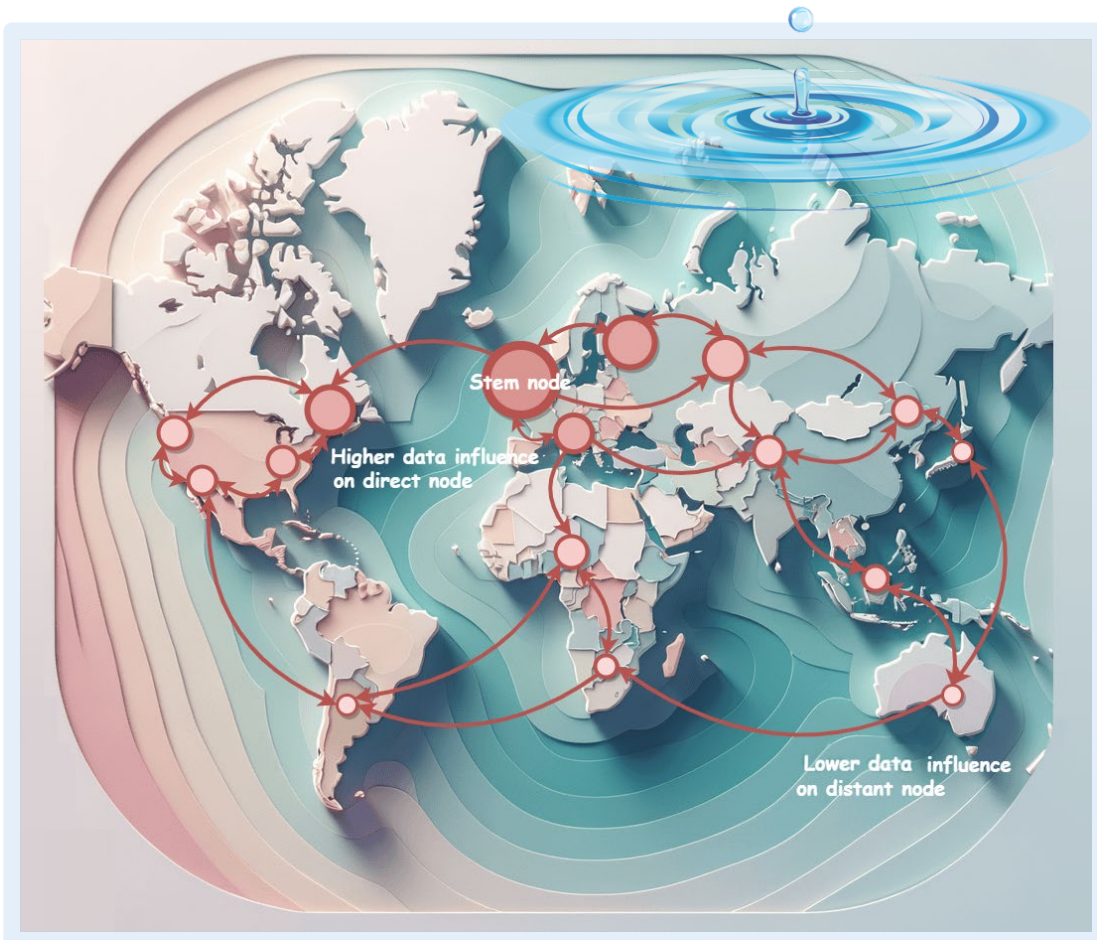
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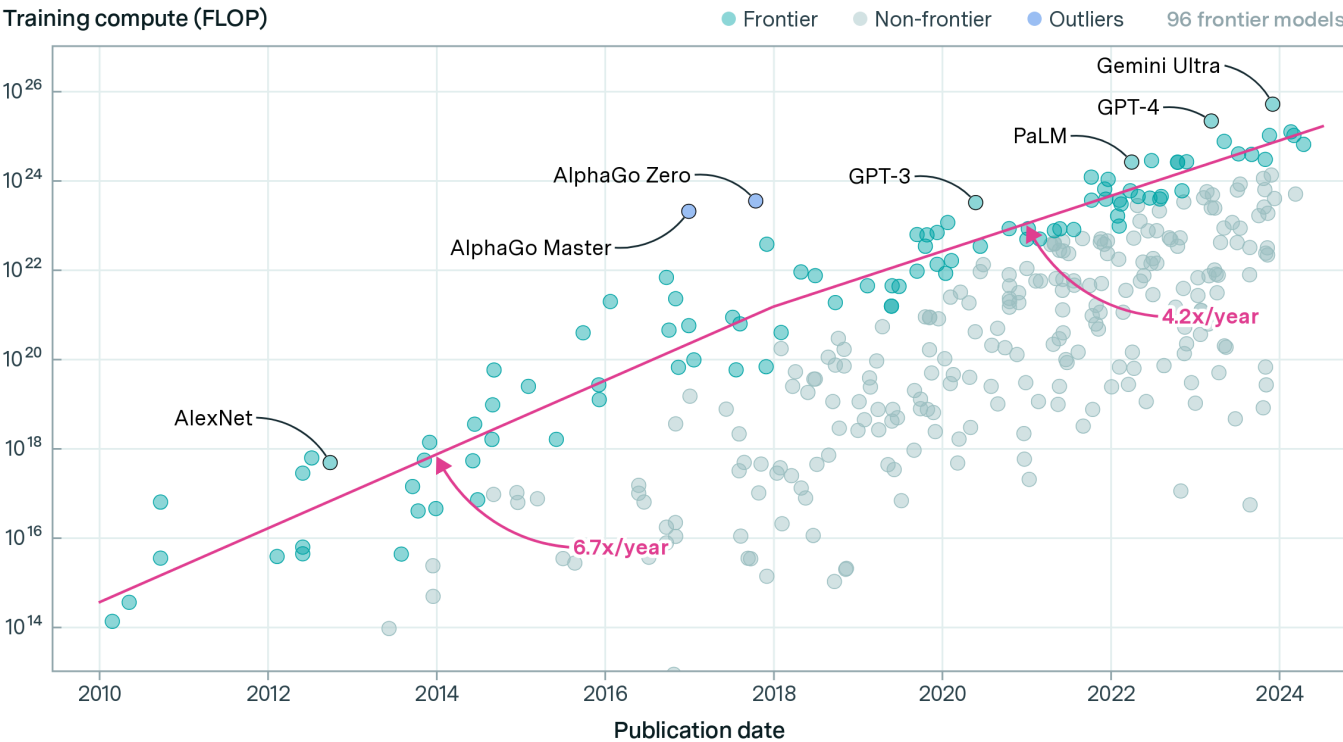
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Formally,

$$\mathcal{I}_{\text{DICE-E}}^{(r)}(z_j^t, z_j') = - \sum_{\rho=0}^r \sum_{(k_1, \dots, k_\rho) \in P_j^{(\rho)}} \eta^t q_{k_\rho} \underbrace{\left(\prod_{s=1}^{\rho} w_{k_s, k_{s-1}}^{t+s-1} \right)}_{\text{communication graph-related term}} \underbrace{\nabla L(\theta_{k_\rho}^{t+\rho}; z_j')^\top}_{\text{test gradient}} \\ \times \underbrace{\left(\prod_{s=2}^{\rho} (I - \eta^{t+s-1} H(\theta_{k_s}^{t+s-1}, z_{k_s}^{t+s-1})) \right)}_{\text{curvature-related term}} \underbrace{\Delta_j(\theta_j^t, z_j^t)}_{\text{optimization-related term}}.$$

Training compute of frontier models

EPOCH AI

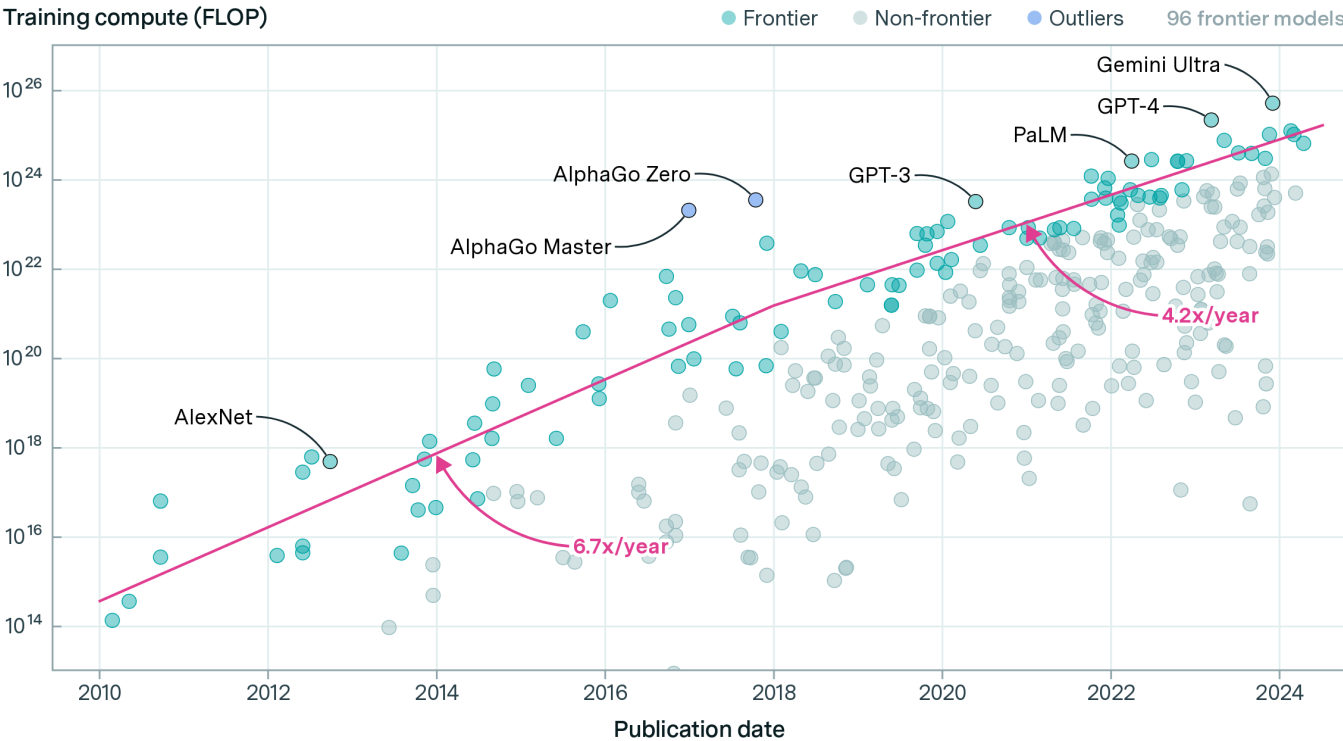


Background



Training compute of frontier models

EPOCH AI



Estimated Compute Cost
GPT-4: \$78 million
Gemini Ultra: \$191 million

Background

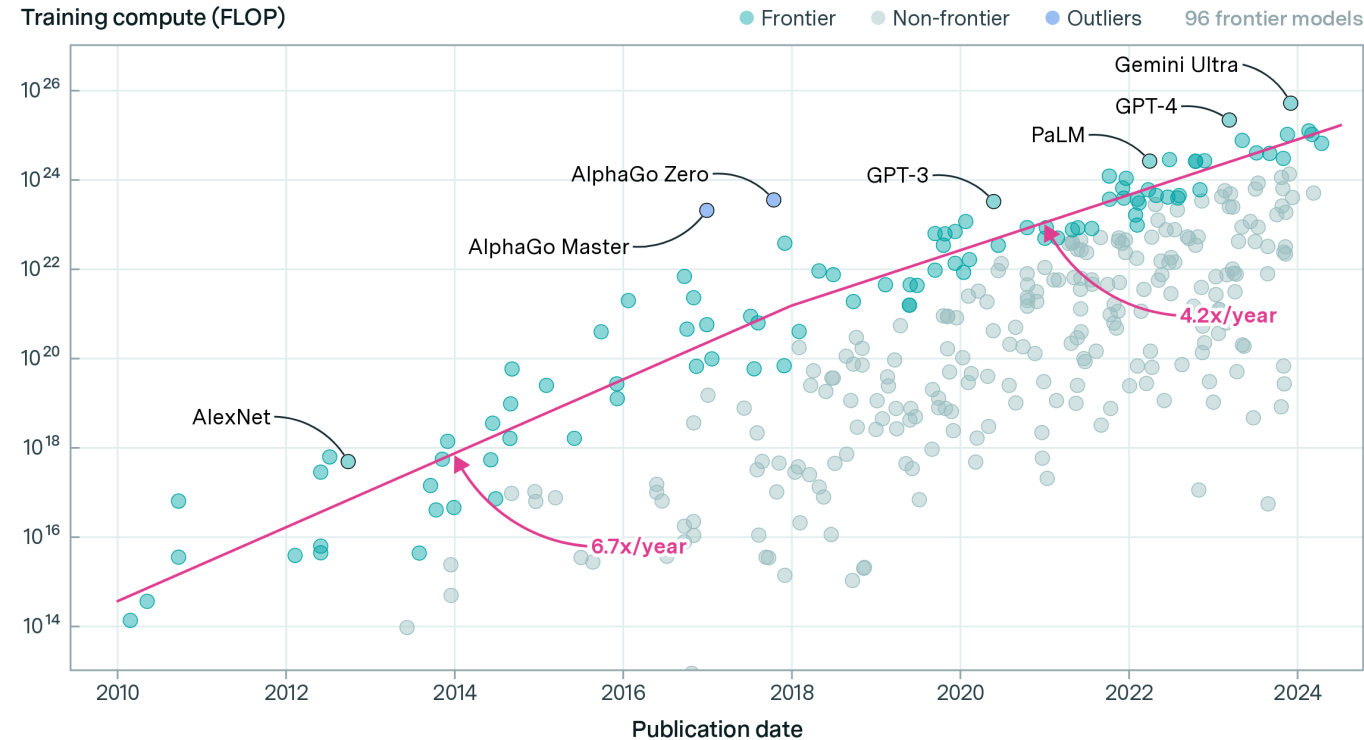


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Training compute of frontier models

EPOCH AI



The exponentially growing compute demands imposes a financial burden far beyond the affordability of academia and individuals.

Training Compute of Frontier AI Models Grows by 4-5x per Year. Epoch AI, 2024.

The AI Index 2024 Annual Report. Institute for Human-Centered AI, Stanford University, 2024.

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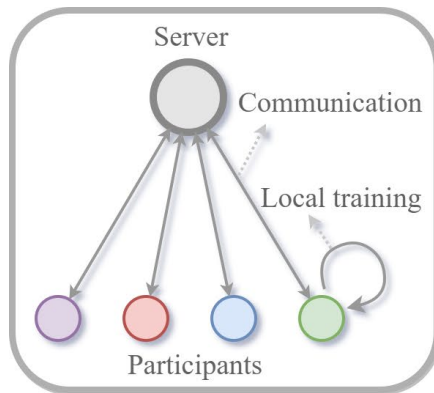


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Large-scale training are primarily performed in costly data centers.



(a) Server-based Learning

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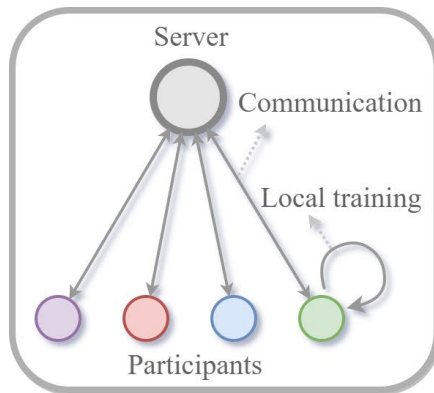


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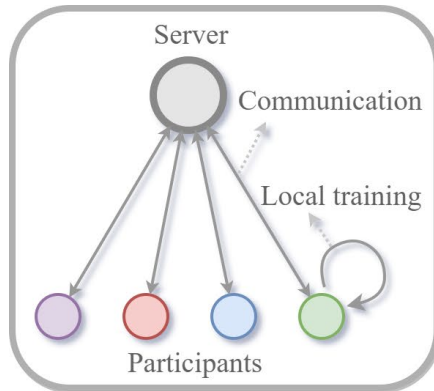


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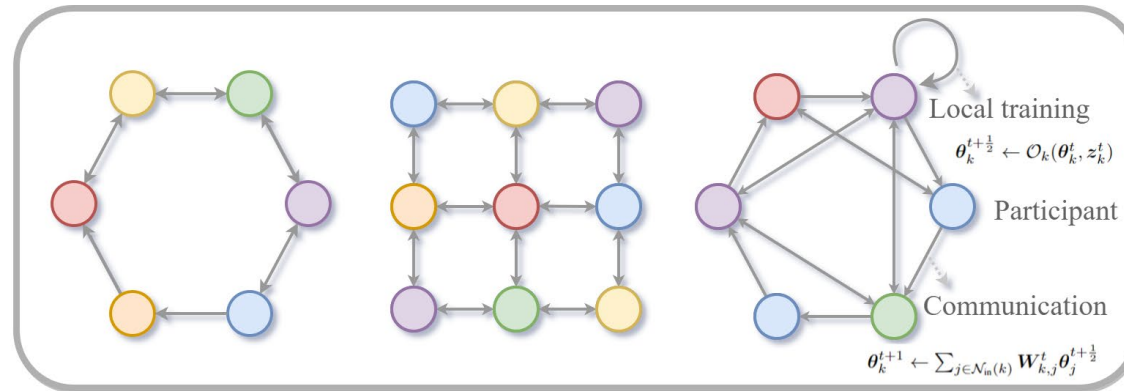


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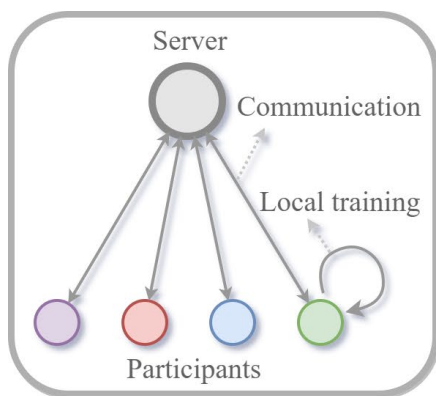


(b) Decentralized Learning

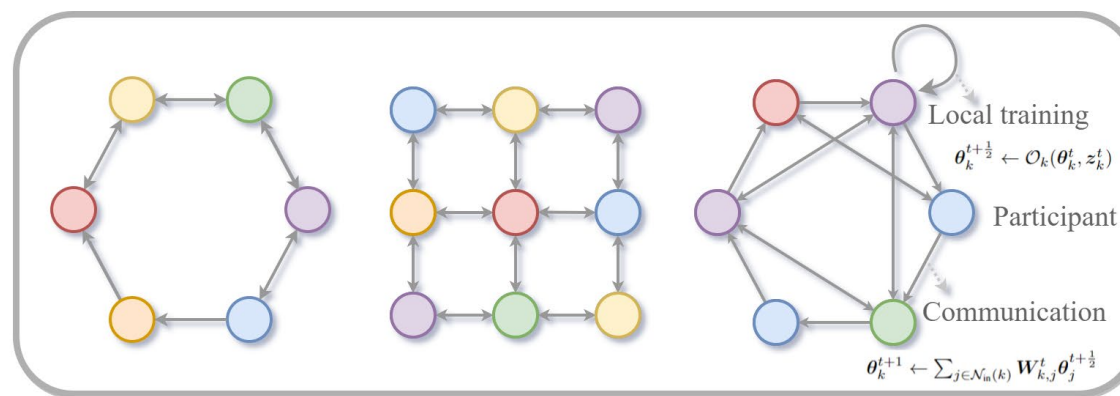
Motivating Question



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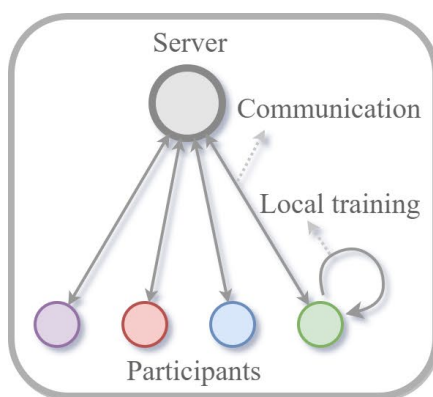


(b) Decentralized Learning

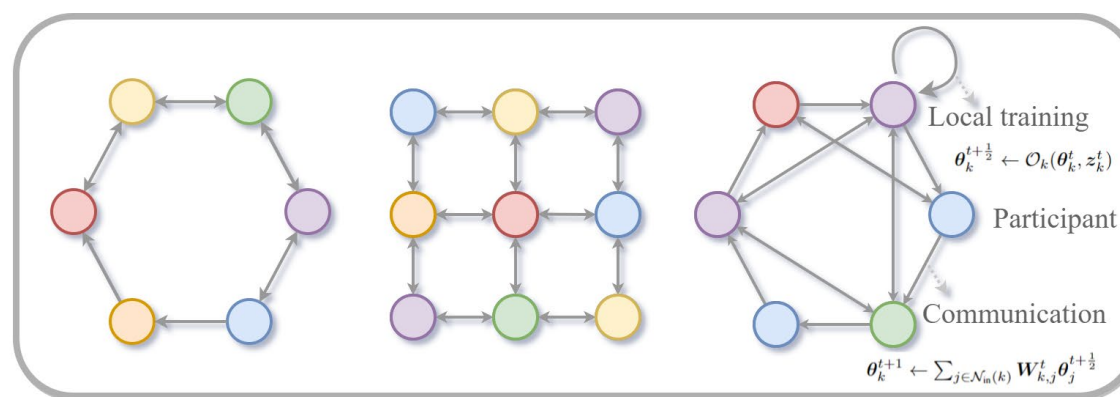
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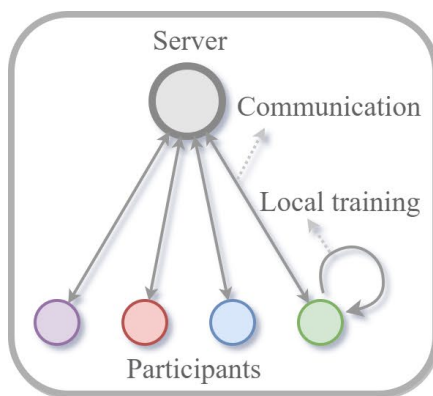
(b) Decentralized Learning

Q: What motivates edge participants to engage in decentralized learning?

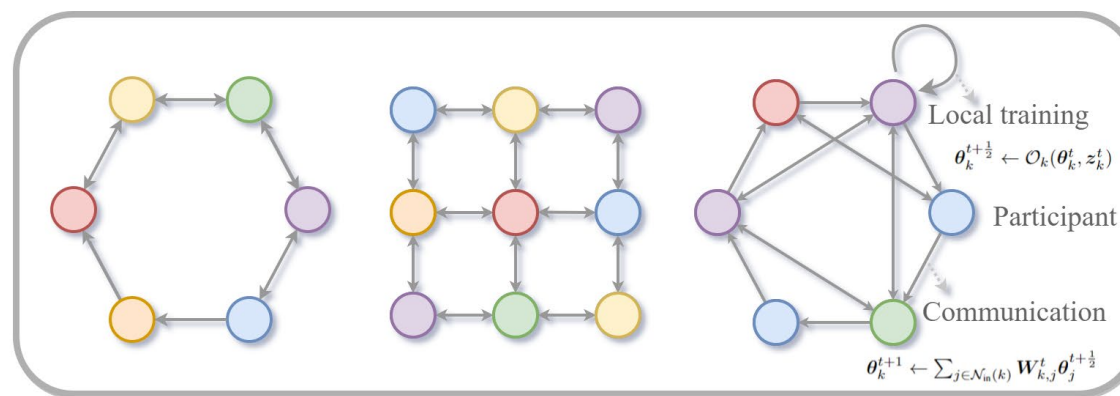
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(b) Decentralized Learning

Q: What motivates edge participants to engage in decentralized learning?

Q: Can we quantify individual contributions in decentralized learning?
How can a proof-of-work mechanism be designed in this context?

How to Answer This Question?



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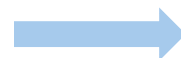


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parameter-level contribution



data-level contribution



We consider a general *personalized distributed optimization problem* over a graph $G = (V, E)$

$$\min_{\theta = \{\theta_k \in \mathbb{R}^d\}_{k \in V}} [L(\theta) \triangleq \sum_{k \in V} q_k L_k(\theta_k)].$$

Here each local objective $L_k(\theta_k) = \mathbb{E}_{z_k \sim D_k}[L(\theta_k; z_k)]$, where D_k denotes the local data distribution. Empirical risk minimization involves optimizing the sample average approximation:

$$\hat{L}(\theta) = \sum_{k \in V} q_k \hat{L}_k(\theta_k) \text{ where } \hat{L}_k(\theta_k) = \frac{1}{n_k} \sum_{i=1}^{n_k} L(\theta_k; z_{k_i}).$$



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↓

model parameters

↓

set of all participants

↓

loss on local model and data

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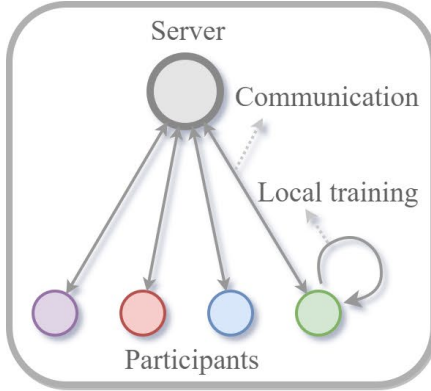
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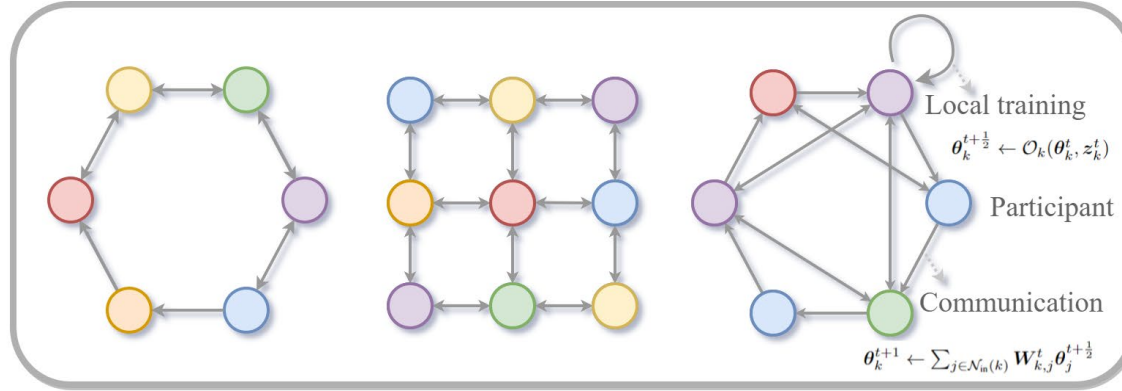
Setup



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(a) Server-based Learning



(b) Decentralized Learning

Algorithm 1 Decentralized Learning with Flexible Gossip and Optimization

Require: $G = (\mathcal{V}, \mathcal{E})$, $\{\theta_k^0\}_{k \in \mathcal{V}}$, optimizer \mathcal{O}_k , number of communication rounds T , and mixing matrix distributions \mathcal{W}^t ($\forall t \in [T]$)

1: **for** $t = 1$ to T **do in parallel for all** participants $k \in \mathcal{V}$

2: **Local Update:**

3: Sample $z_k^t \sim \mathcal{D}_k$, update parameters with optimizer \mathcal{O}_k : $\theta_k^{t+\frac{1}{2}} \leftarrow \mathcal{O}_k(\theta_k^t, z_k^t)$

4: **Gossip Averaging:**

5: Send $\theta_k^{t+\frac{1}{2}}$ to $\{l \mid W_{l,k} > 0\}$ and receive $\theta_j^{t+\frac{1}{2}}$ from $\{j \mid W_{k,j} > 0\}$.

6: Sample $W^t \sim \mathcal{W}^t$, perform gossip averaging: $\theta_k^{t+1} \leftarrow \sum_{j \in \mathcal{N}_{in}(k)} W_{k,j}^t \theta_j^{t+\frac{1}{2}}$

End for



Definition 1 (Leave-one-out Influence).

$$\mathcal{I}_{\text{LOO}}(z, z') = L(\theta^*; z') - L(\theta_{\setminus z}^*; z'),$$

where z denotes the training data instance under influence assessment, z' is the loss-evaluating instance, θ^* and $\theta_{\setminus z}^*$ are the models trained on the entire dataset \mathcal{S} and $\mathcal{S} \setminus \{z\}$, respectively.



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Understanding Black-box Predictions via Influence Functions

Pang Wei Koh¹ Percy Liang¹

$$\mathcal{I}_{\text{LOO}}(z, z') \approx -\nabla_{\theta} L(z', \theta^*)^{\top} H_{\theta^*}^{-1} \nabla_{\theta} L(z, \theta^*)$$



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Question: what makes decentralized learning different?

1. The presence of multiple local models trained on Non-IID data, which may lead to **diverse local optima**.
2. The concept of “neighbors” plays a crucial role, as model parameters are exchanged only among neighboring nodes, allowing for the indirect propagation of data influence.



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Key observations: *In decentralized learning,*

- 1) neighbors who serves as customers hold the rights to determine data influence;*
- 2) data influence is not static but spreads across participants through gossips during training.*



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Key observations: *In decentralized learning,*

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Unfortunately, the original formulation of data influence **cannot** account for these two key characteristics of decentralized learning.



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Definition 2 (One-hop Ground-truth Influence). The one-hop DICE-GT value quantifies the influence of a data instance z_j^t from participant j on a loss-evaluating instance z' within itself and its immediate neighbors. Formally, for a given participant $j \in \mathcal{V}$:

$$\mathcal{I}_{\text{DICE-GT}}^{(1)}(z_j^t, z') = \underbrace{q_j \left(L(\theta_j^{t+\frac{1}{2}}; z') - L(\theta_j^t; z') \right)}_{\text{direct marginal contribution of } z_j^t \text{ to } j} + \underbrace{\sum_{k \in \mathcal{N}_{\text{out}}^{(1)}(j)} q_k \left(L(\theta_k^{t+1}; z') - L(\theta_{k \setminus z_j^t}^{t+1}; z') \right)}_{\text{indirect marginal contribution of } z_j^t \text{ to one-hop neighbors}}.$$

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Proposition 1 (Approximation of One-hop DICE-GT). The one-hop DICE-GT value (see [Definition 2](#)) can be linearly approximated as follow:

$$\mathcal{I}_{\text{DICE-E}}^{(1)}(z_j^t, z') = -q_j \nabla L(\theta_j^t; z')^\top \Delta_j(\theta_j^t, z_j^t) - \sum_{k \in \mathcal{N}_{\text{out}}^{(1)}(j)} q_k \mathbf{W}_{k,j}^t \nabla L(\theta_k^{t+1}; z')^\top \Delta_j(\theta_j^t, z_j^t),$$

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Definition 3 (Multi-hop Ground-truth Influence). The multi-hop DICE-GT value quantifies the cumulative influence of a data instance z on a loss-evaluating instance z' across all nodes within r -hop neighborhoods of participant j . Formally, for a given participant $j \in \mathcal{V}$:

$$\mathcal{I}_{\text{DICE-GT}}^{(r)}(z_j^t, z') = q_j \left(L(\theta_j^{t+\frac{1}{2}}; z') - L(\theta_j^t; z') \right) + \sum_{s=1}^r \sum_{k \in \mathcal{N}_{\text{out}}^{(s)}(j)} q_k \left(L(\theta_k^{t+s}; z') - L(\theta_{k \setminus z_j^t}^{t+s}; z') \right).$$



Theorem 2 (Approximation of r -hop DICE-GT). The r -hop DICE-GT influence $\mathcal{I}_{\text{DICE-GT}}^{(r)}(\mathbf{z}_j^t, \mathbf{z}')$ (see [Definition 3](#)) can be approximated as follows:

$$\begin{aligned} \mathcal{I}_{\text{DICE-E}}^{(r)}(\mathbf{z}_j^t, \mathbf{z}') = & - \sum_{\rho=0}^r \sum_{(k_1, \dots, k_\rho) \in P_j^{(\rho)}} \eta^t q_{k_\rho} \underbrace{\left(\prod_{s=1}^{\rho} \mathbf{w}_{k_s, k_{s-1}}^{t+s-1} \right)}_{\text{communication graph-related term}} \underbrace{\nabla L(\boldsymbol{\theta}_{k_\rho}^{t+\rho}; \mathbf{z}')^\top}_{\text{test gradient}} \\ & \times \underbrace{\left(\prod_{s=2}^{\rho} (\mathbf{I} - \eta^{t+s-1} \mathbf{H}(\boldsymbol{\theta}_{k_s}^{t+s-1}; \mathbf{z}_{k_s}^{t+s-1})) \right)}_{\text{curvature-related term}} \underbrace{\Delta_j(\boldsymbol{\theta}_j^t, \mathbf{z}_j^t)}_{\text{optimization-related term}}. \end{aligned}$$

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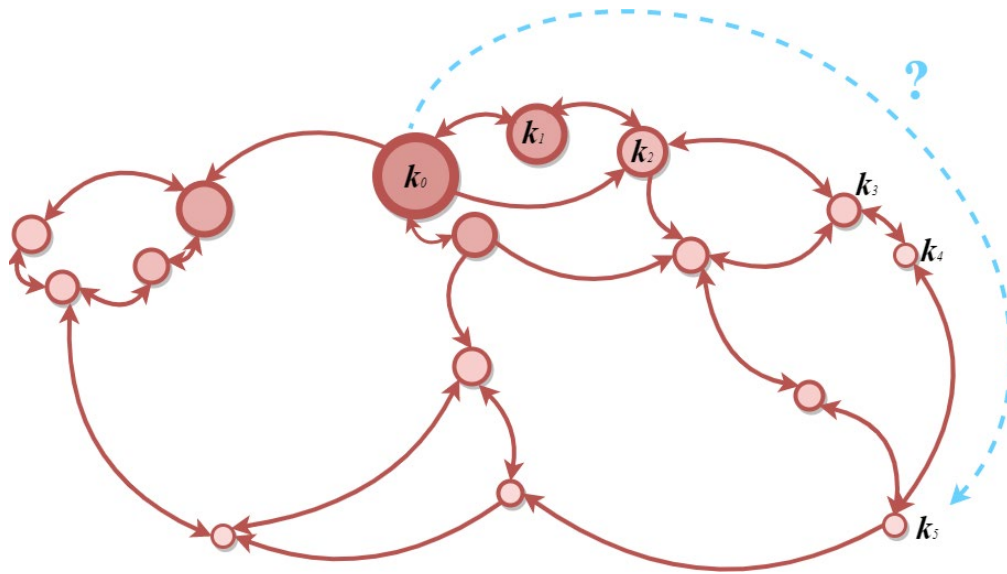
Main Results: Intuition



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How can the influence of **indirectly connected** nodes—such as nodes k_0 to k_5 —be quantified?



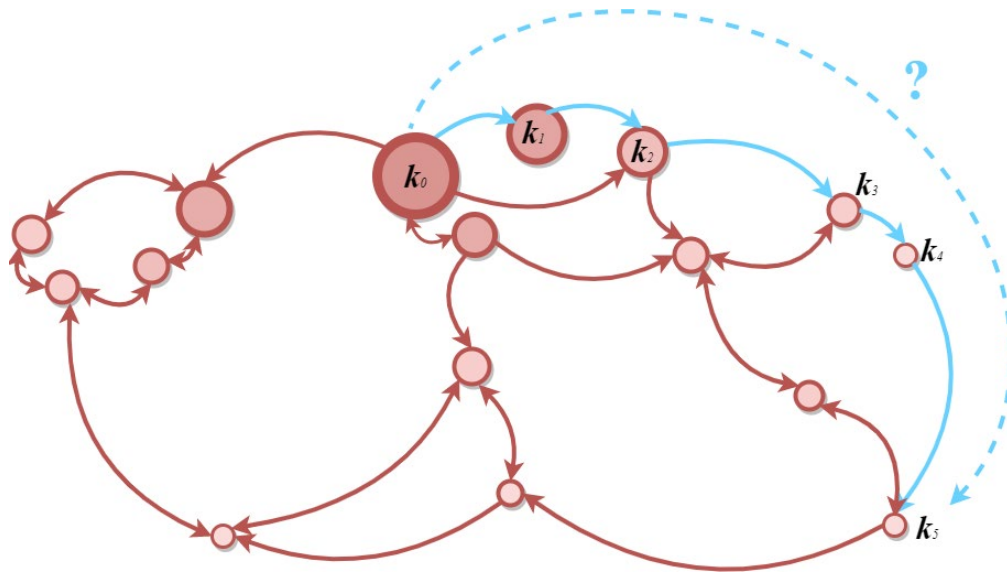
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How can the influence of **indirectly connected** nodes—such as nodes k_0 to k_5 —be quantified?



Theorem 2 (Approximation of r -hop DICE-GT). The r -hop DICE-GT influence $\mathcal{I}_{\text{DICE-GT}}^{(r)}(z_j^t, z')$ (see [Definition 3](#)) can be approximated as follows:

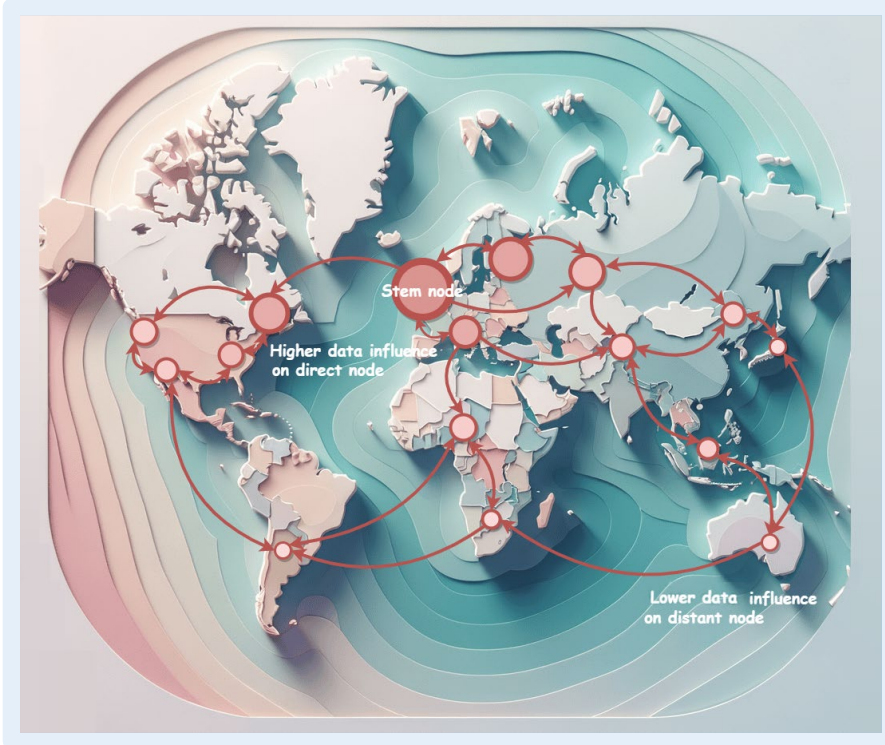
$$\mathcal{I}_{\text{DICE-E}}^{(r)}(z_j^t, z') = - \sum_{\rho=0}^r \sum_{(k_1, \dots, k_\rho) \in P_j^{(\rho)}} \eta^t q_{k_\rho} \underbrace{\left(\prod_{s=1}^{\rho} w_{k_s, k_{s-1}}^{t+s-1} \right)}_{\text{communication graph-related term}} \underbrace{\nabla L(\theta_{k_\rho}^{t+\rho}; z')^\top}_{\text{test gradient}} \times \underbrace{\left(\prod_{s=2}^{\rho} (I - \eta^{t+s-1} H(\theta_{k_s}^{t+s-1}; z_{k_s}^{t+s-1})) \right)}_{\text{curvature-related term}} \underbrace{\Delta_j(\theta_j^t, z_j^t)}_{\text{optimization-related term}}.$$

where $\Delta_j(\theta_j^t, z_j^t) = \mathcal{O}_j(\theta_j^t, z_j^t) - \theta_j^t$, $k_0 = j$. Here $P_j^{(\rho)}$ denotes the set of all sequences (k_1, \dots, k_ρ) such that $k_s \in \mathcal{N}_{\text{out}}^{(1)}(k_{s-1})$ for $s = 1, \dots, \rho$ (see [Definition A.7](#)) and $H(\theta_{k_s}^{t+s}; z_{k_s}^{t+s})$ is the Hessian matrix of L with respect to θ evaluated at $\theta_{k_s}^{t+s}$ and data $z_{k_s}^{t+s}$. For the cases when $\rho = 0$ and $\rho = 1$, the relevant product expressions are defined as identity matrices, thereby ensuring that the r -hop DICE-E remains well-defined. Full proof is deferred to [Appendix C.3](#).

Takeaways



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What phenomena does this paper uncover?

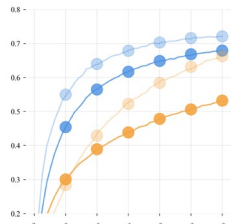
In decentralized learning, the influence of data “cascades” through the communication graph, resembling “ripples in water”.



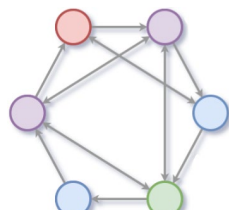
This influence is determined by both the original data and the **topological position** of the data-holding node.



Training data



Make influence



Communication



Cascade

$$\begin{aligned} \mathcal{I}_{\text{DICE-E}}^{(r)}(z_j^t, z') = & - \sum_{\rho=0}^r \sum_{(k_1, \dots, k_\rho) \in P_j^{(\rho)}} \eta^t q_{k_\rho} \underbrace{\left(\prod_{s=1}^{\rho} w_{k_s, k_{s-1}}^{t+s-1} \right)}_{\text{communication graph-related term}} \underbrace{\nabla L(\theta_{k_\rho}^{t+\rho}; z')}_{\text{test gradient}} \\ & \times \underbrace{\left(\prod_{s=2}^{\rho} (I - \eta^{t+s-1} H(\theta_{k_s}^{t+s-1}; z_{k_s}^{t+s-1})) \right)}_{\text{curvature-related term}} \underbrace{\Delta_j(\theta_j^t, z_j^t)}_{\text{optimization-related term}}. \end{aligned}$$

Collaborators



Many thanks to collaborators again!



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Thank you!

DICE: Data Influence Cascade in Decentralized Learning

<https://openreview.net/forum?id=2TIYkqieKw>

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